

# Combining Novelty-Guided and Bounded Suboptimal Search

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# Classical Planning

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- › Find a series of actions which lead from the initial state to a goal state
- › *Examples:*
  - › Tidybot
  - › Blocks world

# Best-First Search

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- › Forward state space search
- › Expanding the most promising node first
- › *Examples:*
  - › GBFS:  $f(n) = h(n)$
  - ›  $A^*$ :  $f(n) = g(n) + h(n)$

# Novelty

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## Definition

The **novelty**  $w(s)$  of a state  $s$  is  $i$  iff there is a tuple  $t$  of  $i$  atoms such that  $s$  is the first state in the search that makes all the atoms in  $t$  true, and no tuple of smaller size has this property.

*Examples: IW, IW+, SIW*

# Novelty

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- › List of subsets
- › List of offsets
- › Lookup table for encountered partial states

# Novelty

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Is the novelty of the state  $s = \{v_0 \mapsto 2, v_1 \mapsto 4, v_2 \mapsto 1, v_3 \mapsto 0\}$  within our novelty bound of 2?

- › Variables:  $V = \{v_0, v_1, v_2, v_3\}$
- › Variable domain sizes:  $|D_{v_0}| = 4, |D_{v_1}| = 5, |D_{v_2}| = 3, |D_{v_3}| = 1$


# Novelty

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- Variables:  $V = \{v_0, v_1, v_2, v_3\}$
- Variable domain sizes:  $|D_{v_0}| = 4, |D_{v_1}| = 5, |D_{v_2}| = 3, |D_{v_3}| = 1$
- Subsets:  $subs = \langle \{v_0, v_1\}, \{v_0, v_2\}, \dots, \{v_2, v_3\} \rangle$
- Offsets:  $off = \{0, 20, 32, 36, 51, 56\}$

0: F	1: F	2: T	...	20: T	21: F	22: F	...
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 $\{v_0 \mapsto 0, v_2 \mapsto 0\}$

# Novelty

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Is the novelty of the state  $s = \{v_0 \mapsto 2, v_1 \mapsto 4, v_2 \mapsto 1, v_3 \mapsto 0\}$  within our novelty bound of 2?

## Example

- Subset:  $s_u = \{v_1, v_2\}$  produces  $s^+ = \{v_1 \mapsto 4, v_2 \mapsto 1\}$
- $off(s_u) = 36$
- $off^*(s^+) = 36 + s[v_1] \cdot |D_{v_2}| + s[v_2] = 49$

**Yes** if cell 49 in *encountered\_states* holds *false*



# Novelty

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Is the novelty of the state  $s = \{v_0 \mapsto 2, v_1 \mapsto 4, v_2 \mapsto 1, v_3 \mapsto 0\}$  within our novelty bound of 2?

## Example

- > Subset:  $s_u = \{v_1, v_2\}$  produces  $s^+ = \{v_1 \mapsto 4, v_2 \mapsto 1\}$
- >  $off(s_u) = 36$
- >  $off^*(s^+) = 36 + s[v_1] \cdot |D_{v_2}| + s[v_2] = 49$

**Yes** if cell 49 in *encountered\_states* holds *false*

**Continue iterating through all remaining subsets**

# Bounded Suboptimal Search

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## Motivation

- › Reduce memory requirements
- › Reduce search time
- › Bind solution cost

# Bounded Suboptimal Search

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## Earlier approaches

- › Weighted  $A^*$ :  $f'(n) = g(n) + w \cdot h(n)$
- › Optimistic Search
- ›  $A_\epsilon^*$
- › Explicit Estimation Search

# Bounded Suboptimal Search

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$A_\epsilon^*$ :

- > *open* list: sorted on  $f(n)$
- > *focal* list: nodes with  $f(n) \leq w \cdot f(\mathbf{best}_f)$  sorted on distance-to-go estimator  $\hat{d}(n)$
- > Thrashing problem leads to poor performance

# Bounded Suboptimal Search

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## Explicit Estimation Search (EES):

- › *open* list: sorted on  $\hat{f}(n)$
- › *cleanup* list: sorted on  $f(n)$
- › *focal* list: nodes with  $\hat{f}(n) \leq w \cdot \hat{f}(\mathit{best}_{\hat{f}})$  sorted on distance-to-go estimator  $\hat{d}(n)$

# Bounded Suboptimal Search

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## Explicit Estimation Search (EES):

*selectNode*

1. **if**  $\hat{f}(best_{\hat{d}}) \leq w \cdot f(best_f)$  **then**  $best_{\hat{d}}$
2. **else if**  $\hat{f}(best_{\hat{f}}) \leq w \cdot f(best_f)$  **then**  $best_{\hat{f}}$
3. **else**  $best_f$

$$\hat{h}(n) \geq h(n)$$

# Combination

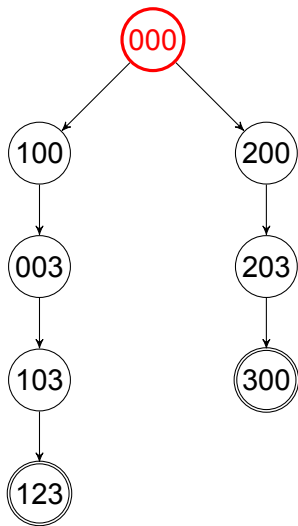
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## Combining Novelty-Guided and Bounded Suboptimal Search:

- $w_h(s)$ : one lookup table per unique heuristic value  $h(s)$
- EES with *focal* sorted on  $w_h$  instead of  $\hat{d}$
- Additional inclusion restriction for *focal*:  $w_h(s) \leq nov_b$

# Example

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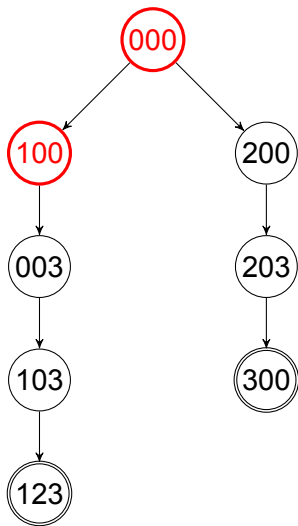


<b>s</b>	<b>w</b>	$\hat{f}$	<b>f</b>
100	1	4	4
200	1	5	3



# Example

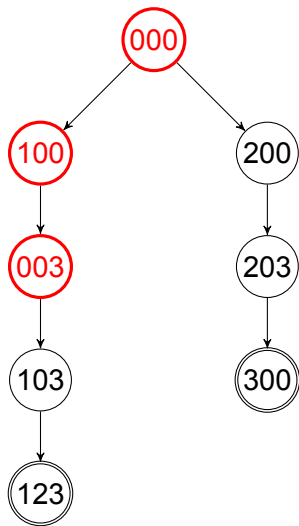
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<b>s</b>	<b>w</b>	$\hat{f}$	<b>f</b>
100	1	4	4
200	1	5	3
003	1	4	4

# Example

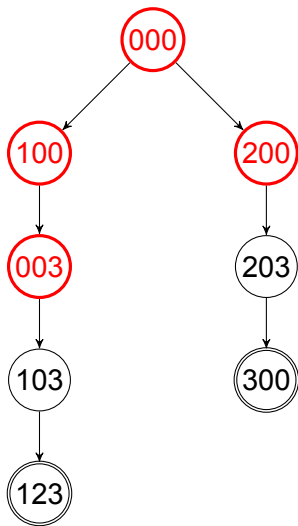
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<b>s</b>	<b>w</b>	$\hat{f}$	<b>f</b>
100	1	4	4
200	1	5	3
003	1	4	4
103	2	4	4

# Example

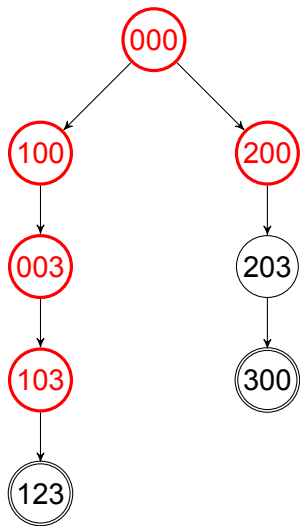
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<b>s</b>	<b>w</b>	$\hat{f}$	<b>f</b>
100	1	4	4
200	1	5	3
003	1	4	4
103	2	4	4
203	2	5	3

# Example

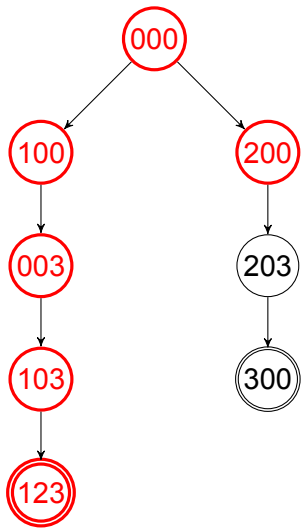
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s	w	$\hat{f}$	f
100	1	4	4
200	1	5	3
003	1	4	4
103	2	4	4
203	2	5	3
123	2	4	4

# Example

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# Evaluation

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- › Implemented in the Fast Downward planning system (C++)
- › 2GB memory limit
- › Three minute time limit

# Evaluation

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- › Picking a novelty bound
- › Effect of the weighting parameter
- › Heuristics used:
  - ›  $h = h^{LM}$
  - ›  $\hat{h} = h^{FF}$
  - ›  $w_{h^{FF}}(s)$

# Evaluation

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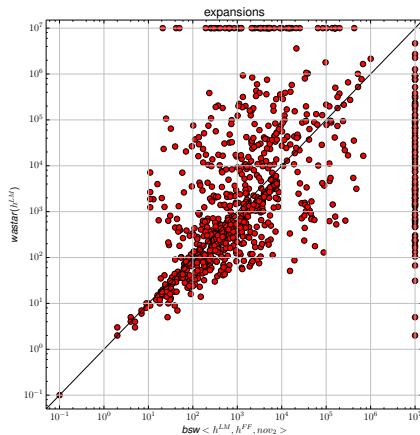
Summary of the search attributes of the runs using *bsw* with different novelty values

<b>Summary</b>	$bsw(n_b = 1)$	$bsw(n_b = 2)$	$bsw(n_b = 3)$	$wA^*$
Plan length - Sum	26962	<b>26936</b>	26945	27348
Memory - Sum	<b>8337552</b>	8491108	20315652	10079064
Generated - Geometric mean	9383.61	9379.55	<b>9375.64</b>	12664.49
Expansions - Geometric mean	<b>1098.68</b>	1100.06	1099.75	1493.06
Coverage - Sum	947	947	882	<b>1027</b>
Search time - Geometric mean	0.80	0.85	1.44	<b>0.25</b>



# Evaluation

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Comparison of expansions between  $\text{bsw}(n_n = 2)$  and weighted  $A^*$  with  $w = 2$

# Evaluation

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Coverage	$w = 1.5$	$w = 2.0$		$w = 3.0$		
	bsw( $n_b = 2$ )	bsw( $n_b = 2$ )	weighted $A^*$	bsw( $n_b = 2$ )	weighted $A^*$	
Nr. of problems	1667	869	947	1027	1008	<b>1071</b>

# Evaluation

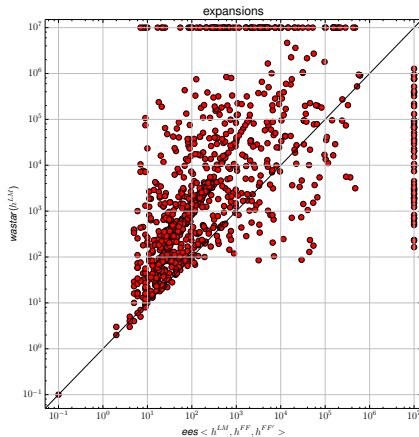
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Summary of the search attributes for the runs using the implementations of the search engine components separately

<b>Summary</b>	$wA^*$	$\text{tie}\langle wA^*, \text{nov}_2 \rangle$	ees
Plan length - Sum	<b>35999</b>	37096	36504
Memory - Sum	14876532	15126440	<b>9523920</b>
Generated - Geometric mean	20926.90	19148.35	<b>2576.71</b>
Expansions - Geometric mean	2360.67	2164.33	<b>298.77</b>
Coverage - Sum	1027	1029	<b>1070</b>
Search time - Geometric mean	0.46	<b>0.37</b>	0.47

# Evaluation

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Comparison of expansions between ees and weighted  $A^*$  with  $w = 2$

# Conclusion

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- › Tendency of a lower number of expanded and generated nodes
- › Higher mean search time
- › Lower coverage
- › Good results with pure EES

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Questions?