

# A Formal Verification of Strong Stubborn Set Based Pruning

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# Roadmap

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1. Classical Planning
2. Strong Stubborn Set based pruning
3. Isabelle/HOL Implementation
4. Contributions & Future work

# Roadmap

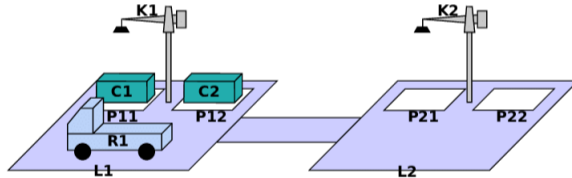
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# Classical Planning

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Branch of AI that studies single agent, static, deterministic, fully observable, discrete search problems.



## Definition

A transition system is a 6-tuple

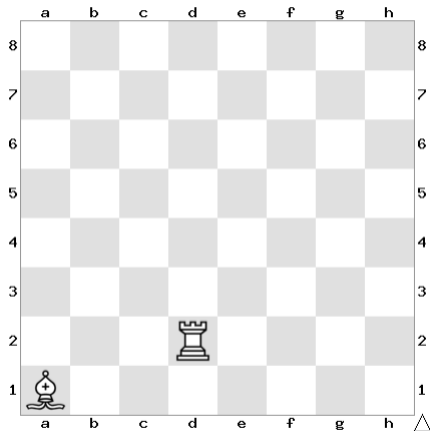
$$\mathcal{T} = \langle S, T, A, cost, s_0, G \rangle$$

1.  $S$  is a set of states.
2.  $T \subseteq S \times A \times S$  is a set of transitions  $t = \langle src\ t, act\ t, dst\ t \rangle$ .
3.  $A$  is a set of action.
4.  $cost$  is a function  $A \rightarrow \mathbb{N}_0$ .
5.  $s_0$  is the initial state.
6.  $G \subseteq S$  is the set of goals.

$op$  is an operator in  $\mathcal{T}$  if  $op \subseteq T \wedge \forall t, t' \in op : act\ t = act\ t'$ .

## An example

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- >  $S = \{\text{positions}\}$
- >  $T = \{\langle \text{position, move, effect} \rangle\}$
- >  $A = \{\text{possible moves}\}$
- >  $\text{cost} \equiv 1$
- >  $op_i = \{\langle s, act_i, s' \rangle \in T\}$
- > solution = sequence of operators.

State spaces tend to be too vast!

One solution: Pruning

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**However ...** pruning procedures are tricky to prove.

**This thesis:** Validate correctness of Strong Stubborn Set based pruning for transition systems in Isabelle/HOL.



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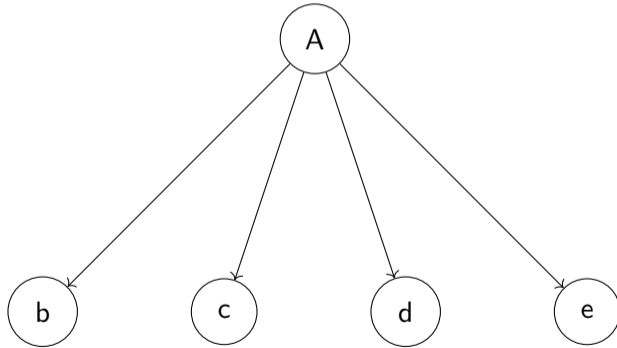
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# Pruning

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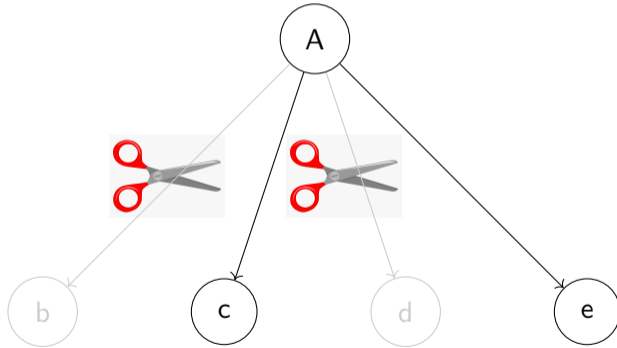
State space pruning is a domain-independent technique that narrows down the set of applicable operators into an optimality preserving set.



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# Strong Stubborn Sets

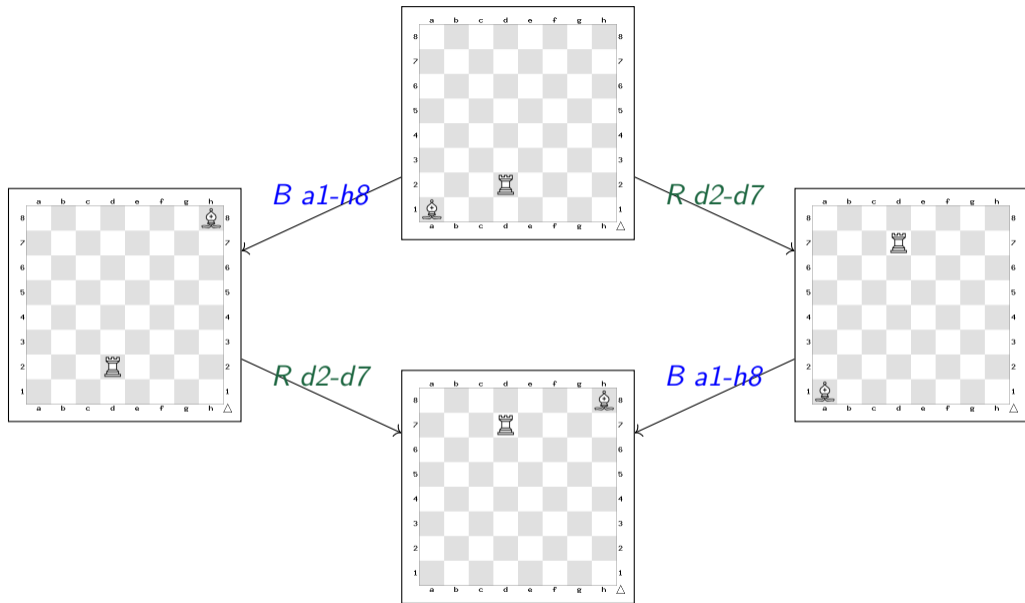
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First introduced in the area of model checking.

Then adopted to classical planning in  $SAS^+$ .

Here: to transition systems.

Idea: exploit properties about independent operators.

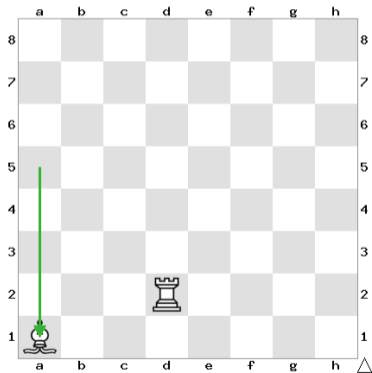


## Necessary enabling set

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$N$  is a necessary enabling set for  $op$  in  $s$  if

$\forall$  solution  $\pi$  for  $s$  that contains  $op$ :  $\exists op' \in \text{set}(\pi) \cap N$  that comes before  $op$  in  $\pi$ .

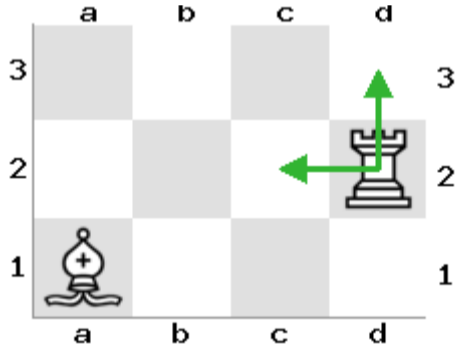


$$N = \{B-a1-b2, B-a1-c3, \dots, B-a1-h8\}$$

# Disjunctive action landmark

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A disjunctive action landmark  $L$  for a state  $s \in S$  is a set of operators such that for every solution for  $s$ , there exists an operator in that path that is also in  $L$ .



## Definition

A Strong Stubborn Set  $SSS$  for  $s \in S$  if the following hold:

- ›  $SSS$  contains a disjunctive action landmark for  $s$ .
- › if  $op \in SSS$  and  $\neg app(op, s)$  then  $SSS$  contains a necessary enabling set for  $op$  in  $s$ .
- › if  $op \in SSS$  and  $app(op, s)$  then  $SSS$  contains all the operators  $op'$  for which  $op$  and  $op'$  are dependent.



## Theorem

Let  $s \in S$  be an active state and  $SSS$  be a Strong Stubborn Set for  $s$ . Then there exists an  $op \in SSS$  that starts some optimal solution for  $s$ .

Proof sketch:

- ›  $s$  active so  $\exists$  solution  $\pi = \langle op_1, \dots, op_n \rangle$ .
- ›  $SSS$  contains a disjunctive landmark  $\implies \text{set}(\pi) \cap SSS \neq \emptyset$ .
- › Let then  $op$  in  $\pi$  s.t. it has the lowest index in  $\pi$  and  $op \in SSS$ .
- ›  $\neg \text{app}(op, s) \implies SSS$  contains a necessary enabling set for  $op$  in  $s \implies \exists op'$  comes before  $op$  and  $op' \in SSS \cap \text{set}(\pi) \cap SSS \neq \emptyset$ .
- ›  $\exists op'$  in  $\pi$  :  $op'$  comes before  $op$  and  $op$  and  $op'$  are dependent  $\implies op' \in SSS \neq \emptyset$ .
- › Thus moving  $op$  to the front of  $\pi$  is also an optimal solution.

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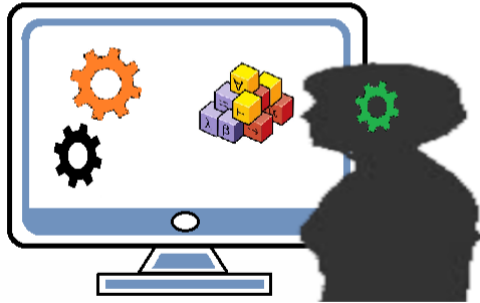
# Isabelle

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Isabelle is an interactive theorem prover.

Proofs are well defined  $\implies$  proof search is suited for automation.

Isabelle/HOL provides a higher-order logic theorem proving environment.



# Implementation

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- > Bottom up approach.
- > 72 lemmas proven before tackling the main theorem.

```
232 lemma
233   fixes L :: "'a operator set" and pi :: "'a path"
234   shows "L ∩ set pi ≠ {} ⇒ pi ≠ [] ⇒ first_occurrence pi L ∈ L ∩ set pi"
235 proof (induct pi)
236   case Nil
237   from this show ?case by auto
238 next
239   case (Cons x xs)
240
241   from this have ONE: "(x ∉ L ∧ xs = []) ⇒ ?case" by simp
242   from local.Cons have TWO: "(x ∉ L ∧ xs ≠ []) ⇒ ?case" by simp
243   from local.Cons have THREE: "x ∈ L ⇒ ?case" by simp
244
245   from ONE and TWO and THREE show ?case by auto
246 qed
```

## The Isabelle/HOL proof



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# Contributions

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1. Validate an important theorem about the optimality preserving property of Strong Stubborn Set based pruning.
2. Adapt the theory of Strong Stubborn Sets to transition systems.
3. Provide an Isabelle/HOL base code for future proofs.

## Future Work

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1. Validate correctness of Strong Stubborn Set finding algorithms.
2. Validate the the correctness of the optimality preserving property in  $SAS^+$



# Contributions

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1. Validate an important theorem about the optimality preserving property of Strong Stubborn Set based pruning.
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“Who fails to plan, plans to fail”

proverb