

Analysing and Combining Static Pruning Techniques for Classical Planning Tasks

Master Thesis

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Overview

1. Introduction

2. Pruning Techniques

3. Synergies

4. Experiments

5. Conclusion

I. Introduction

A



B



Planning Task

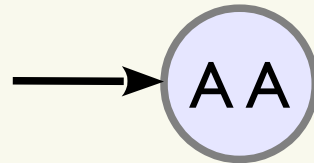
- Variables



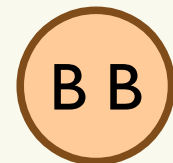
- Operators

$drive_{A \rightarrow B}$ $drive_{B \rightarrow A}$ $load_A$ $unload_A$ $load_B$ $unload_B$

- Initial state



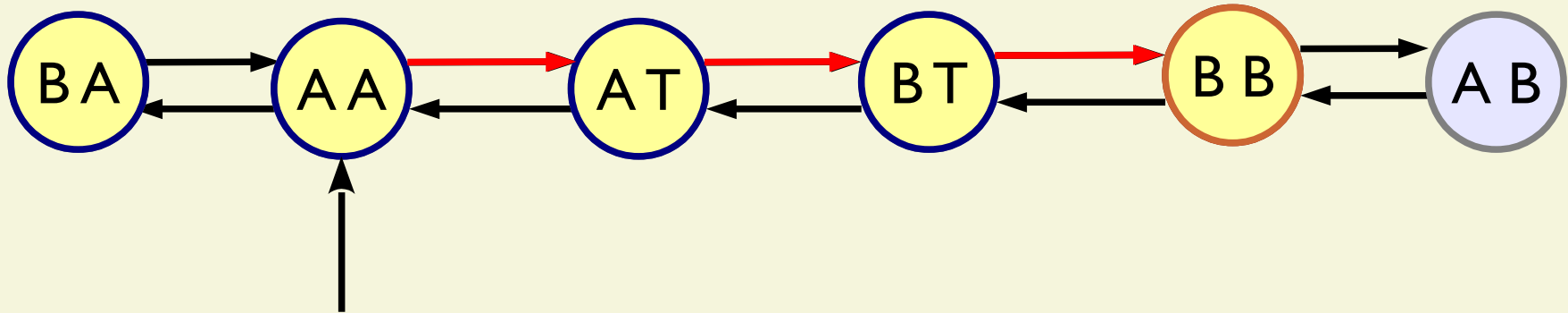
- Goal state



A



B



Plan: $load_A$ $drive_{A \rightarrow B}$ $unload_B$

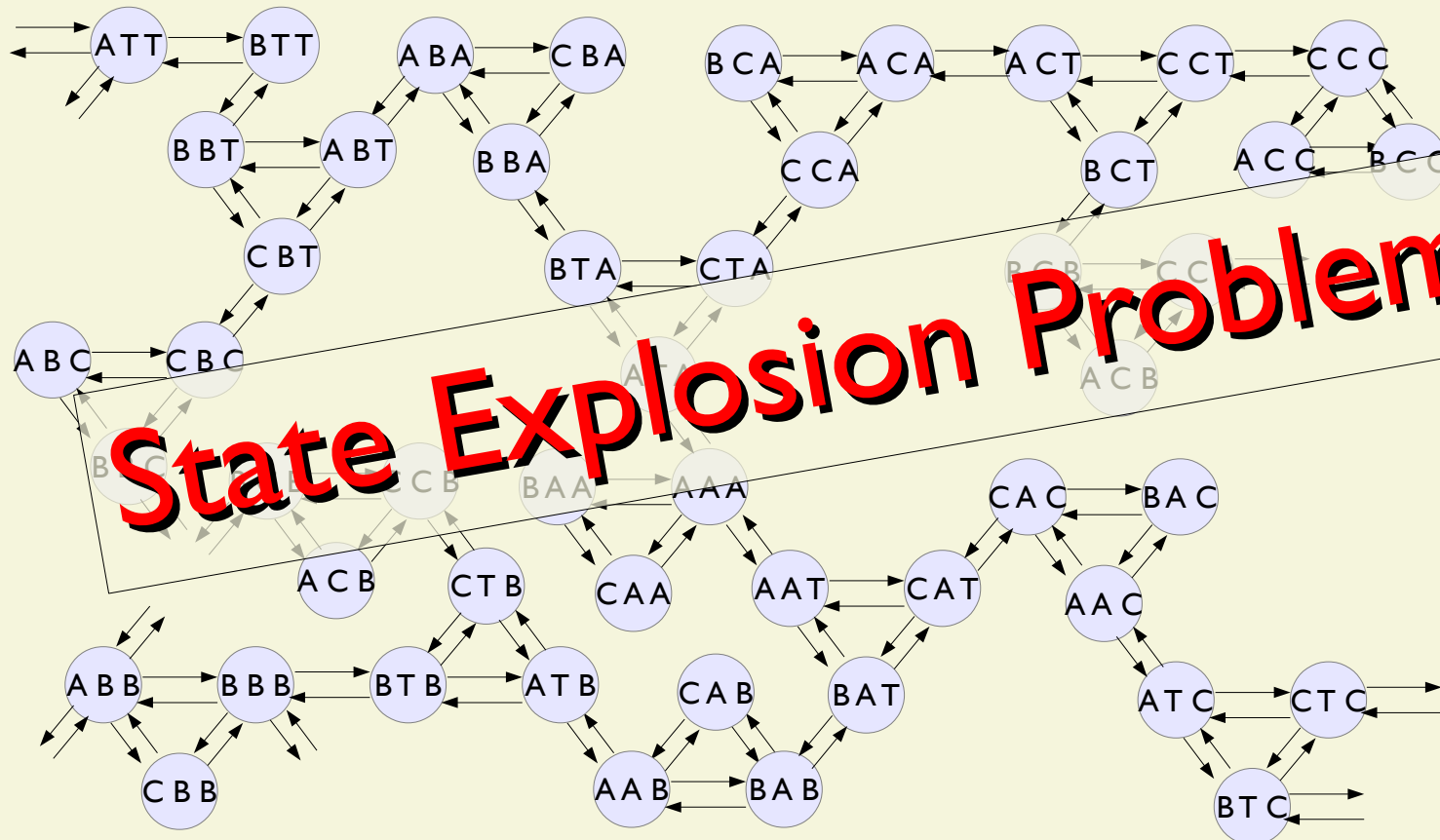
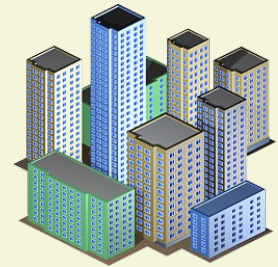
A



C

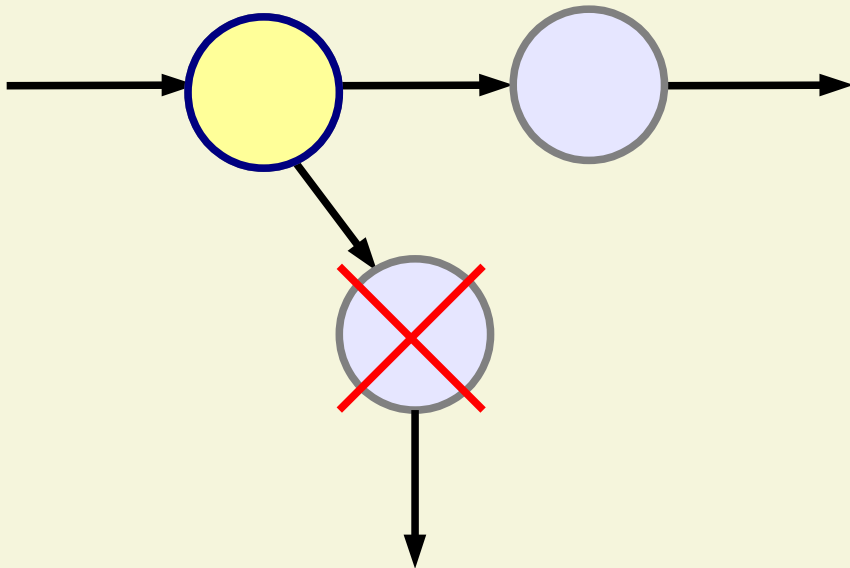


B



State Explosion Problem

Dynamic Pruning



Static Pruning

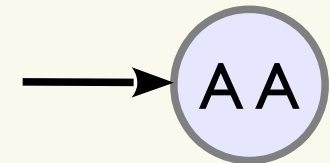
- Variables



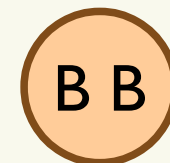
- Operators

~~unload_B~~ ...

- Initial state



- Goal state



2. Pruning Techniques

- ◆ Safe Abstraction
- ◆ Redundant Operator Reduction
- ◆ Dominance Pruning

Safe Abstraction

- ◆ Original version by **Helmert (2006)**
- ◆ Variant by **Haslum (2007)**

General idea:

1. Abstract *safe* variables
2. Solve abstract task
3. *Refine* plan

Safe Abstraction

Abstracting a Planning Task

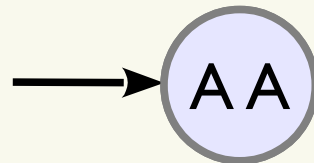
- Variables



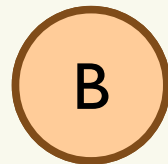
- Operators

$drive_{A \rightarrow B}$ $drive_{B \rightarrow A}$ $load_A$ $unload_A$ $load_B$ $unload_B$

- Initial state



- Goal state



Safe Abstraction

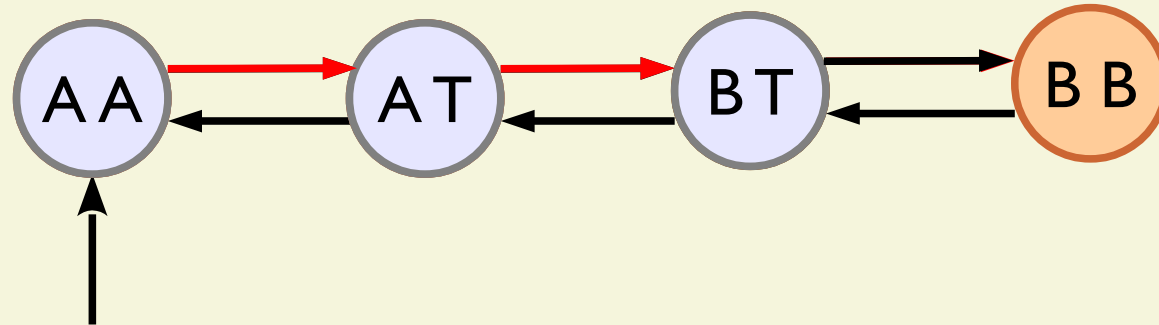
A



B



~~Original~~ Planning Task



Plan: load_A drive_{A→B} unload_B

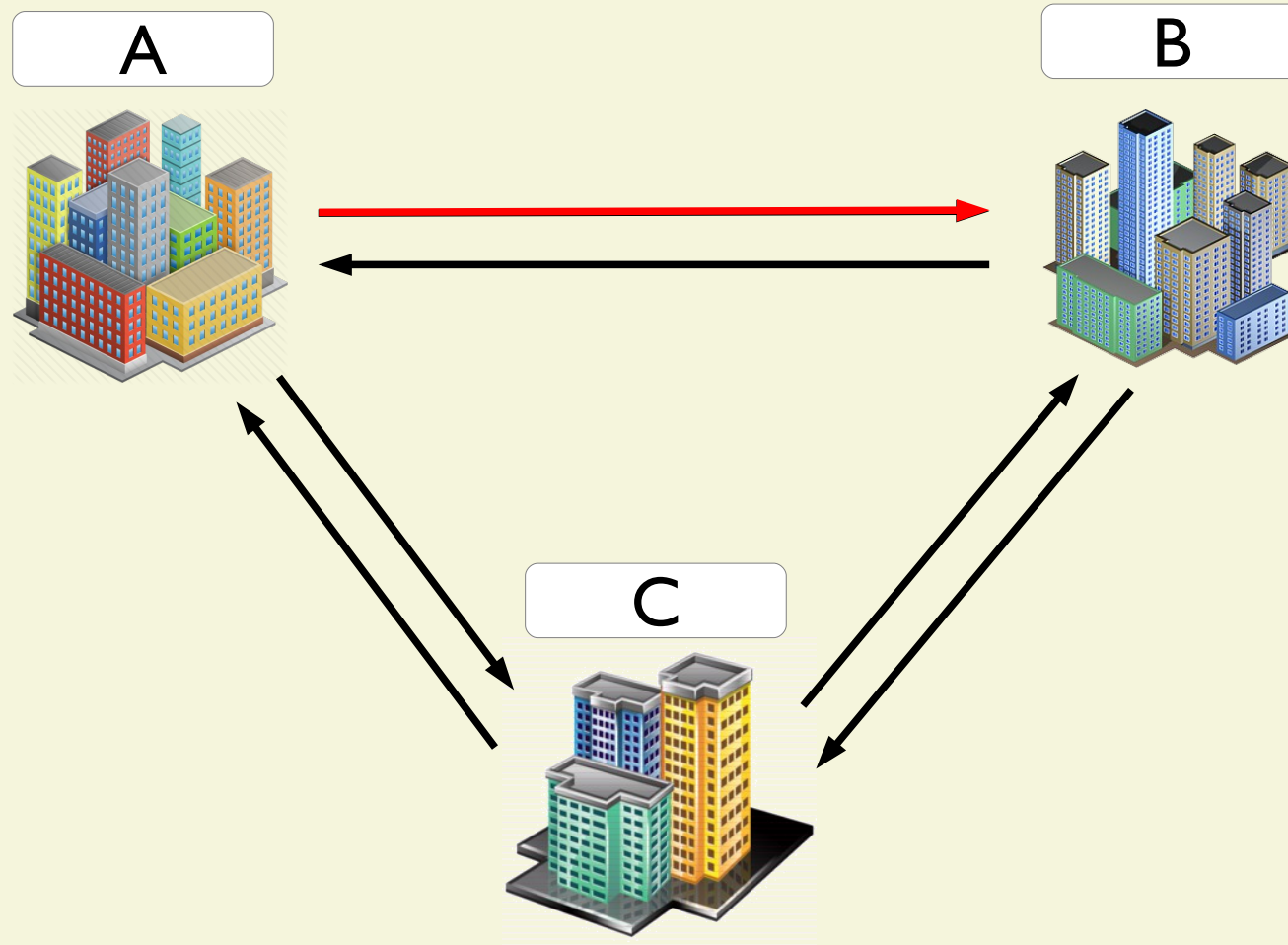
Redundant Operator Reduction

- ◆ Researched by **Haslum and Jonsson (2000)**

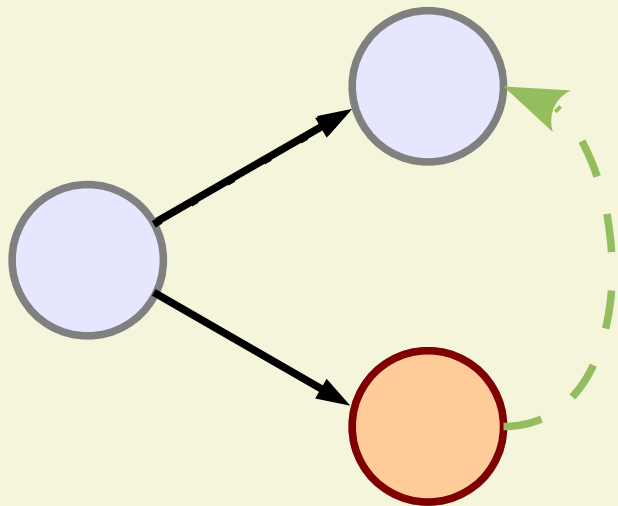
General idea:

- ◆ More operators than necessary
- ◆ Remove *redundant* operators

Redundant Operator Reduction



Dominance Pruning



- ◆ Optimality-preserving

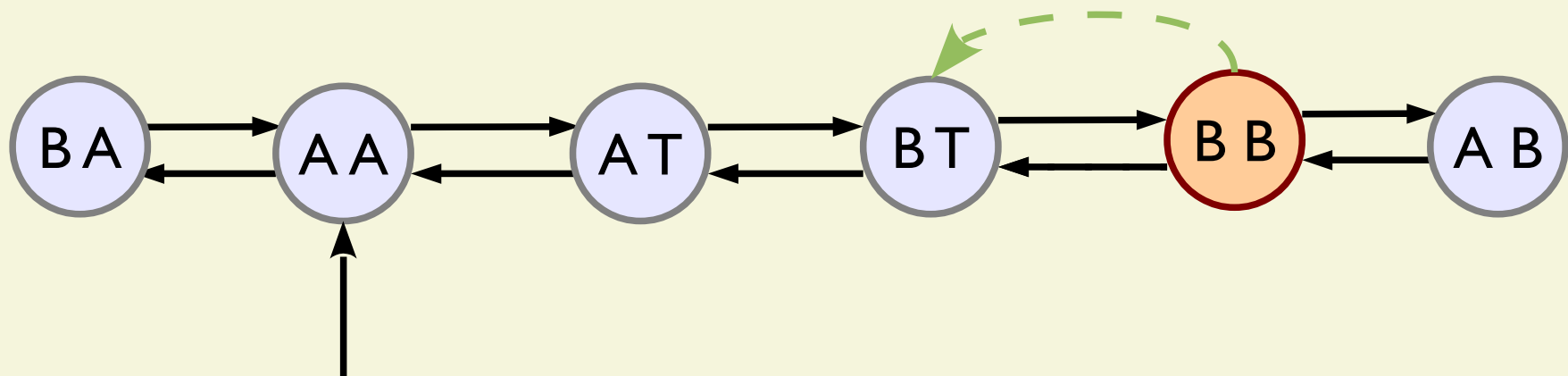
Torralba and Hoffmann (2015)

- ◆ Compute state simulation

Kissmann and Torralba (2015)

- ◆ Identify *subsumed* transitions
- ◆ Remove „bad“ operators

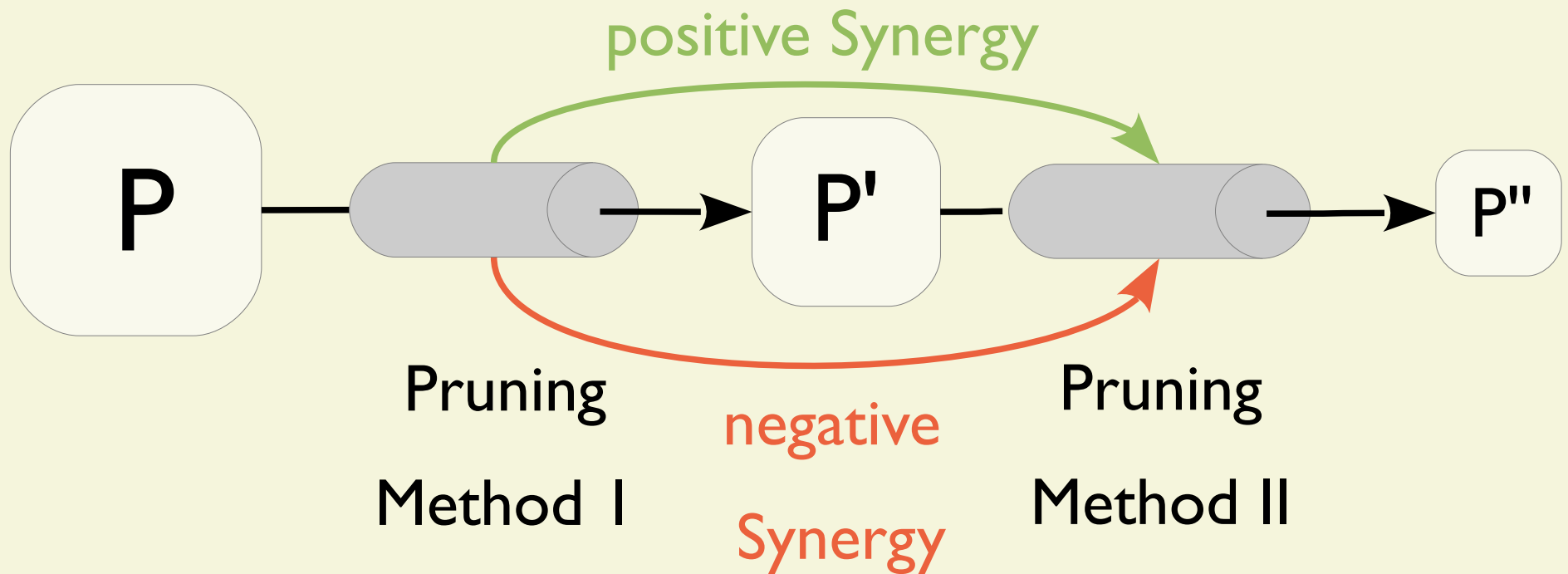
Dominance Pruning



- Operators $drive_{A \rightarrow B}$ $drive_{B \rightarrow A}$ $load_A$ $unload_A$ ~~$load_B$~~ $unload_B$

3. Synergies

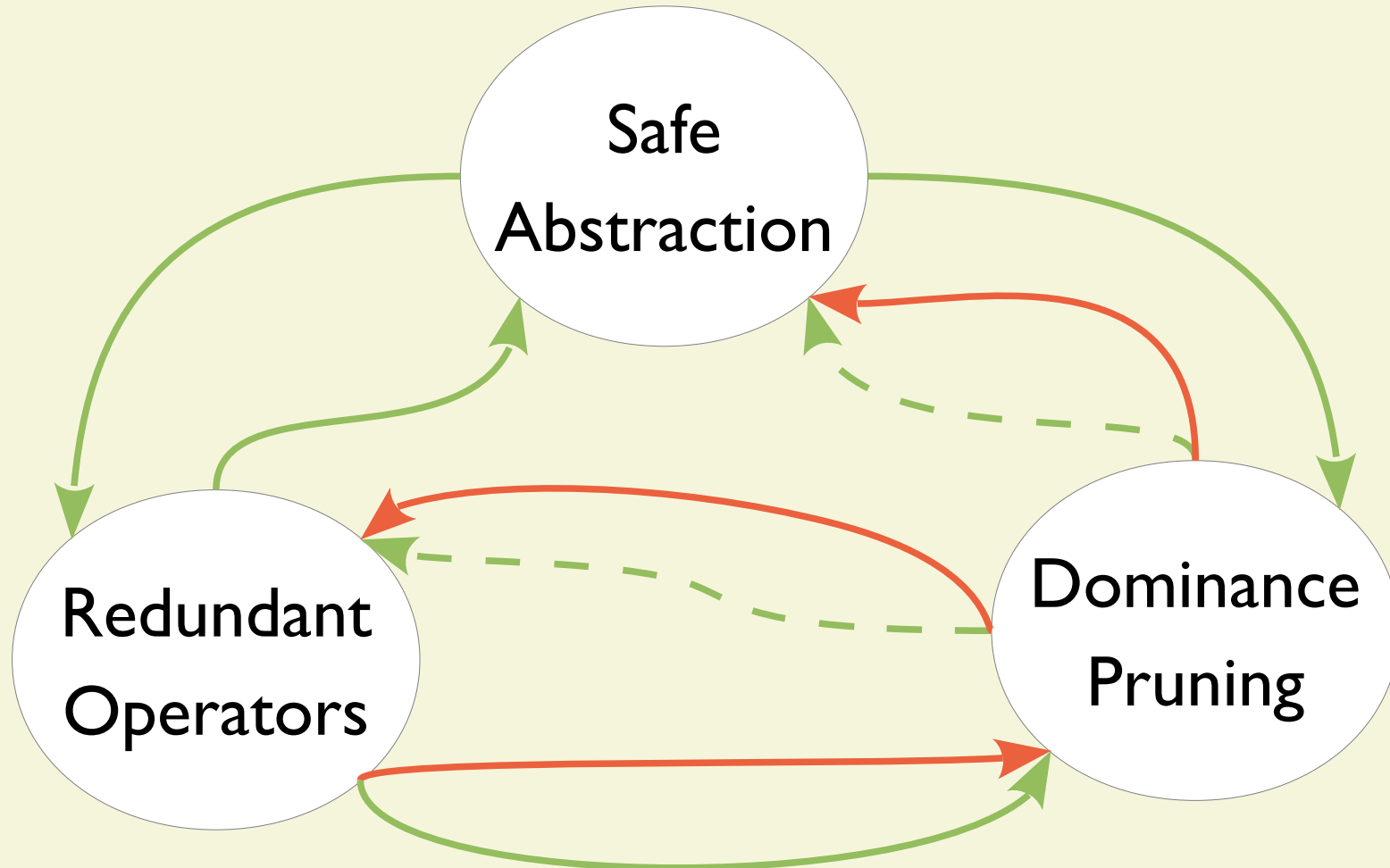
Synergy Effects



Which synergies exist?

→ Proven theorems

Synergy Effects



4. Experiments

- ◆ Implementation in Fast Downward
- ◆ IPC Benchmarks

Roadmap Experiments

1. Techniques separately

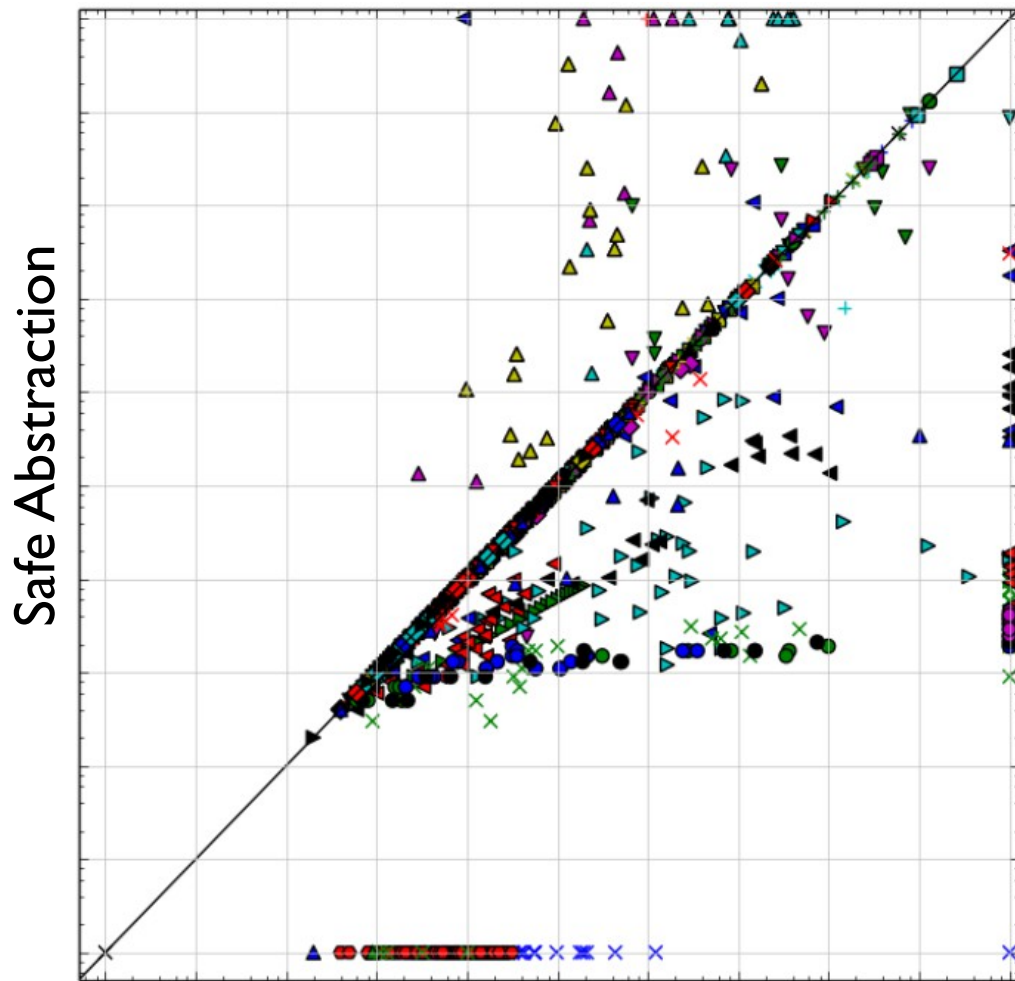
- ◆ Configurations
- ◆ Best performance

2. Combinations and Synergies

- ◆ Synergies separately
- ◆ Synergies compared

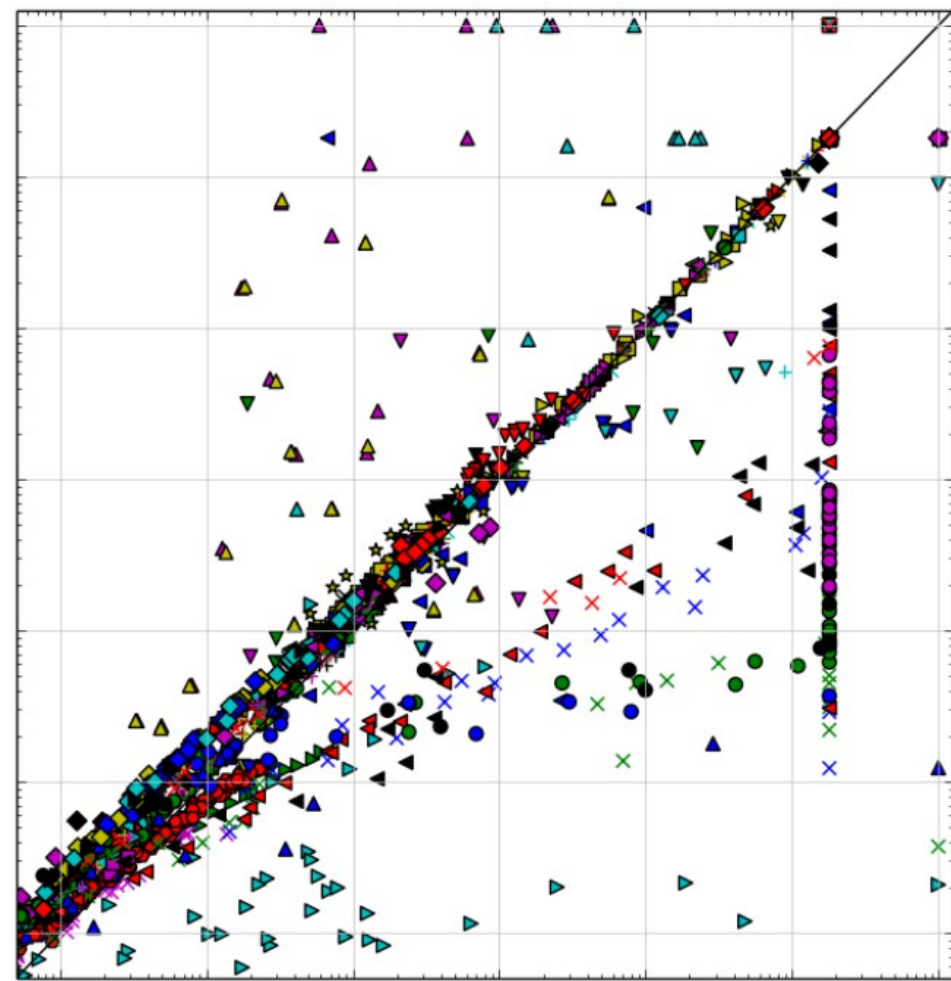
Safe Abstraction

Expanded States



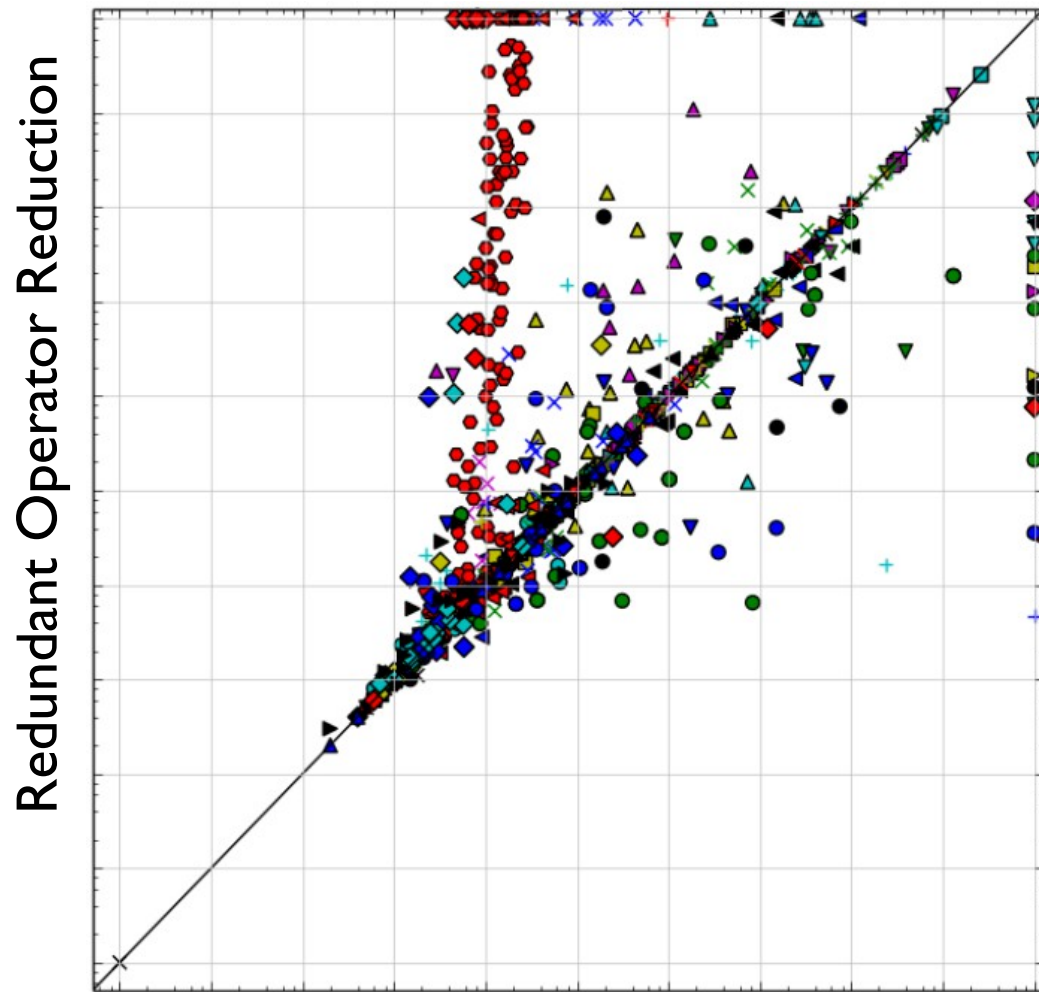
baseline (Greedy + FF)

Planning Time

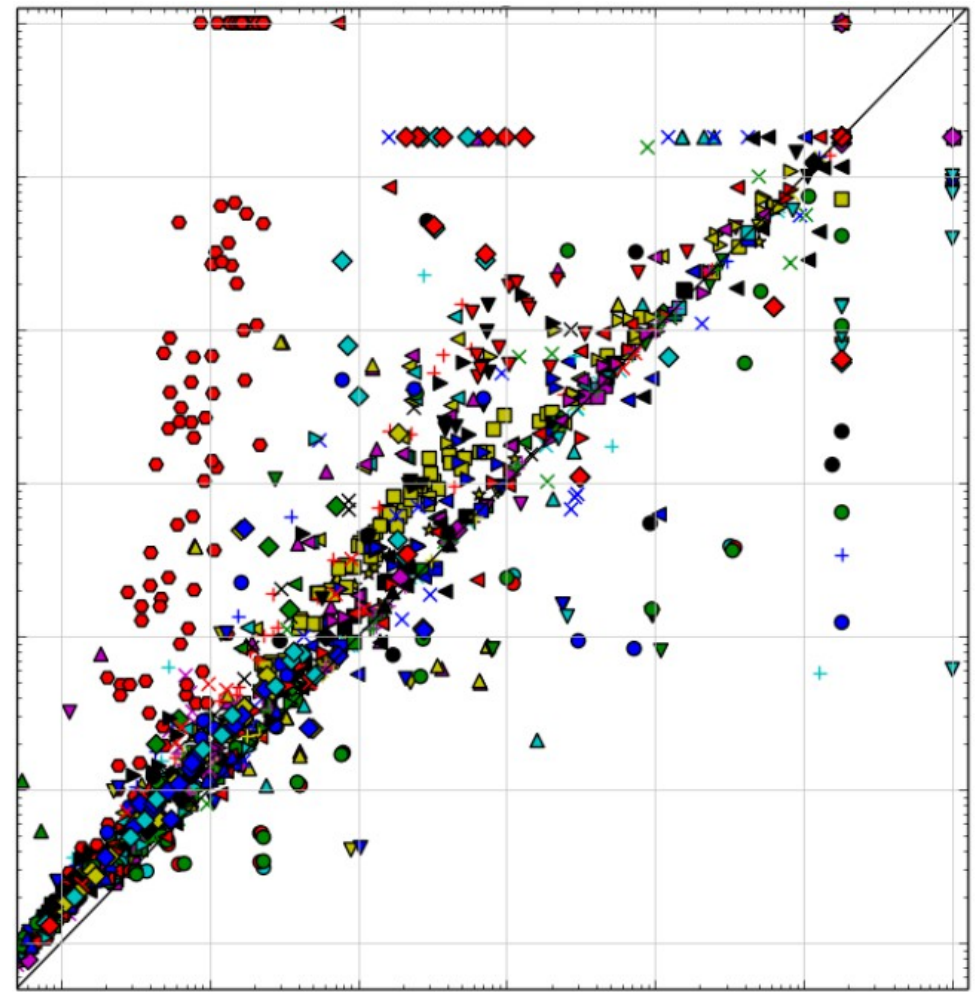


Redundant Operator Reduction

Expanded States



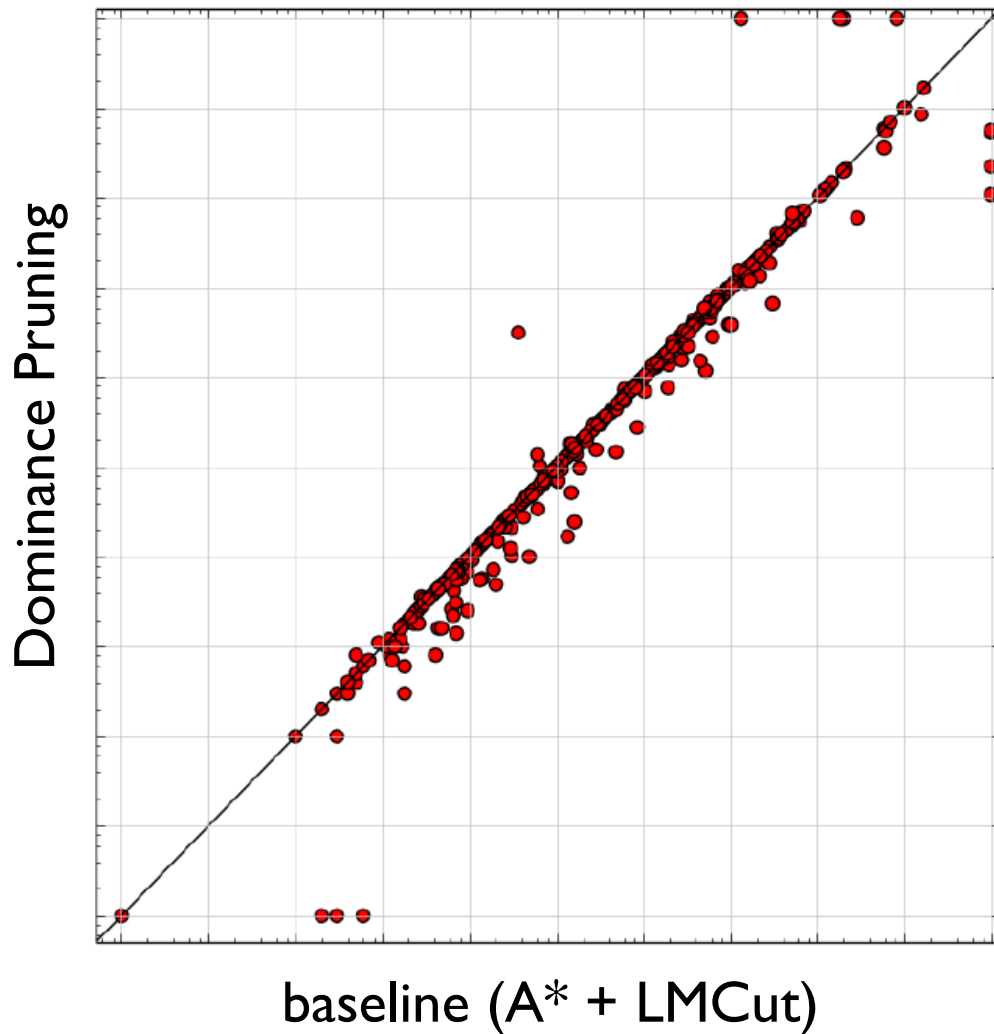
Planning Time



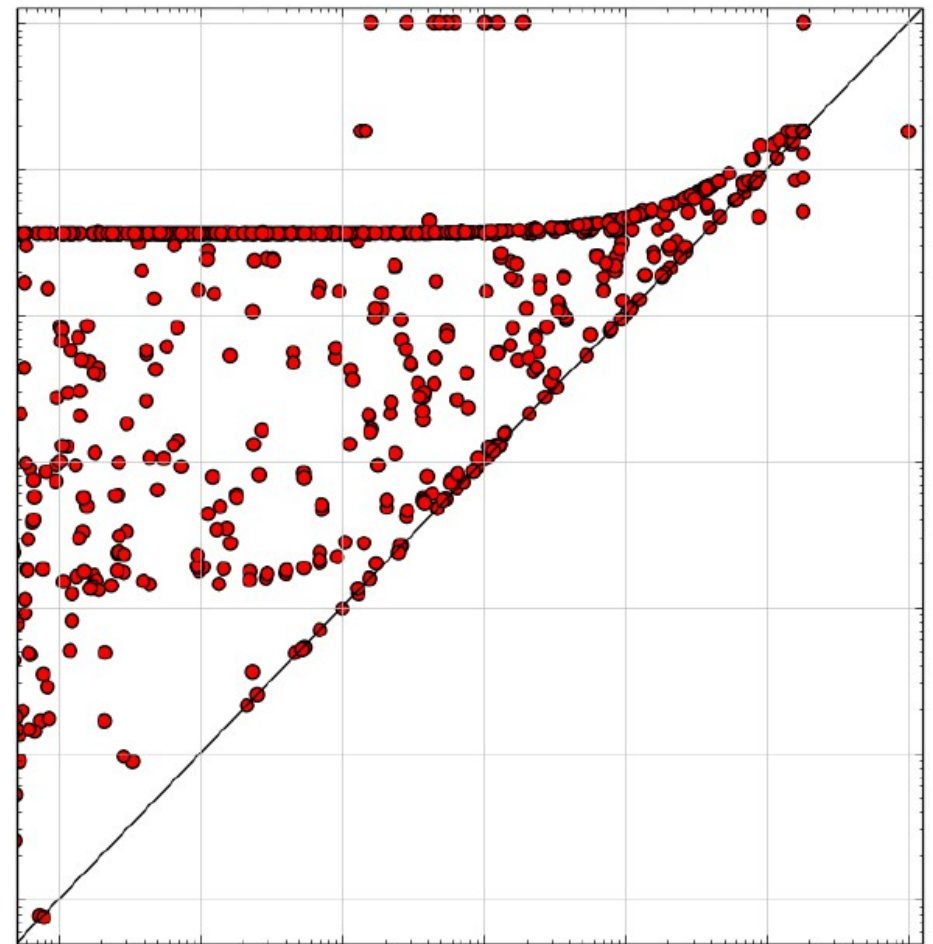
baseline (Greedy + FF)

Dominance Pruning

Expanded States

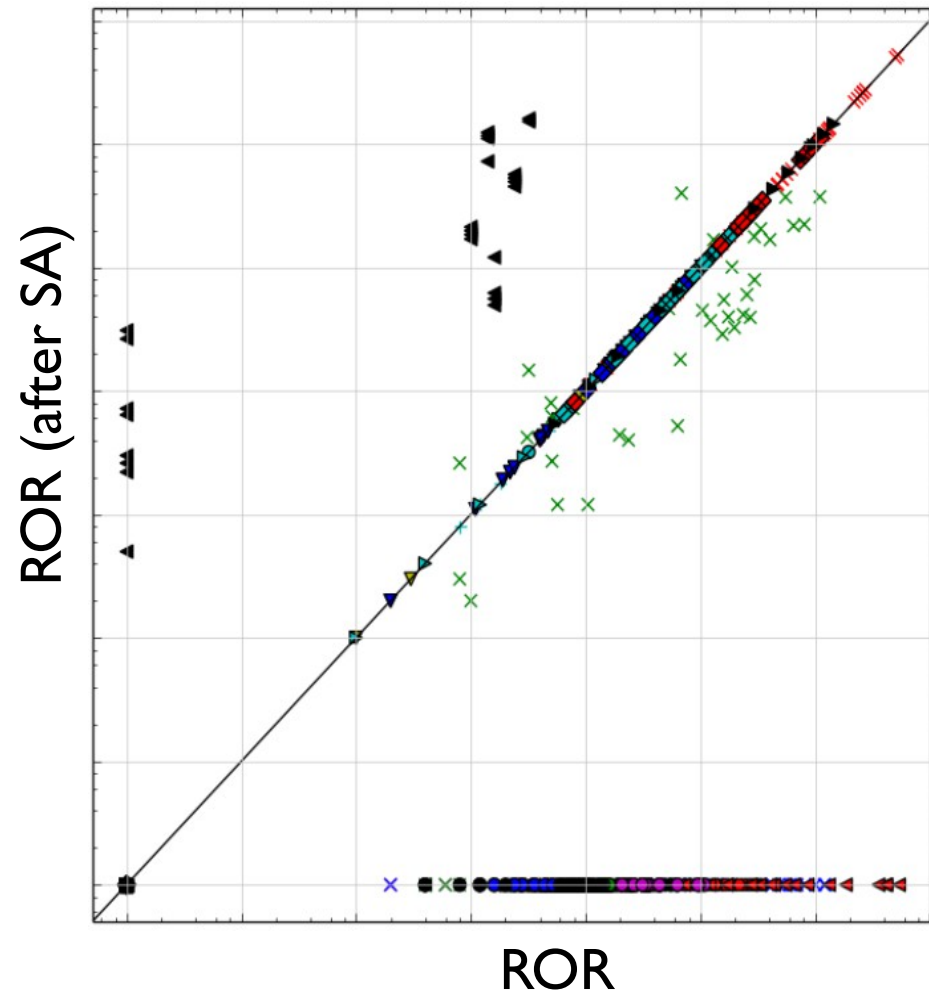


Planning Time



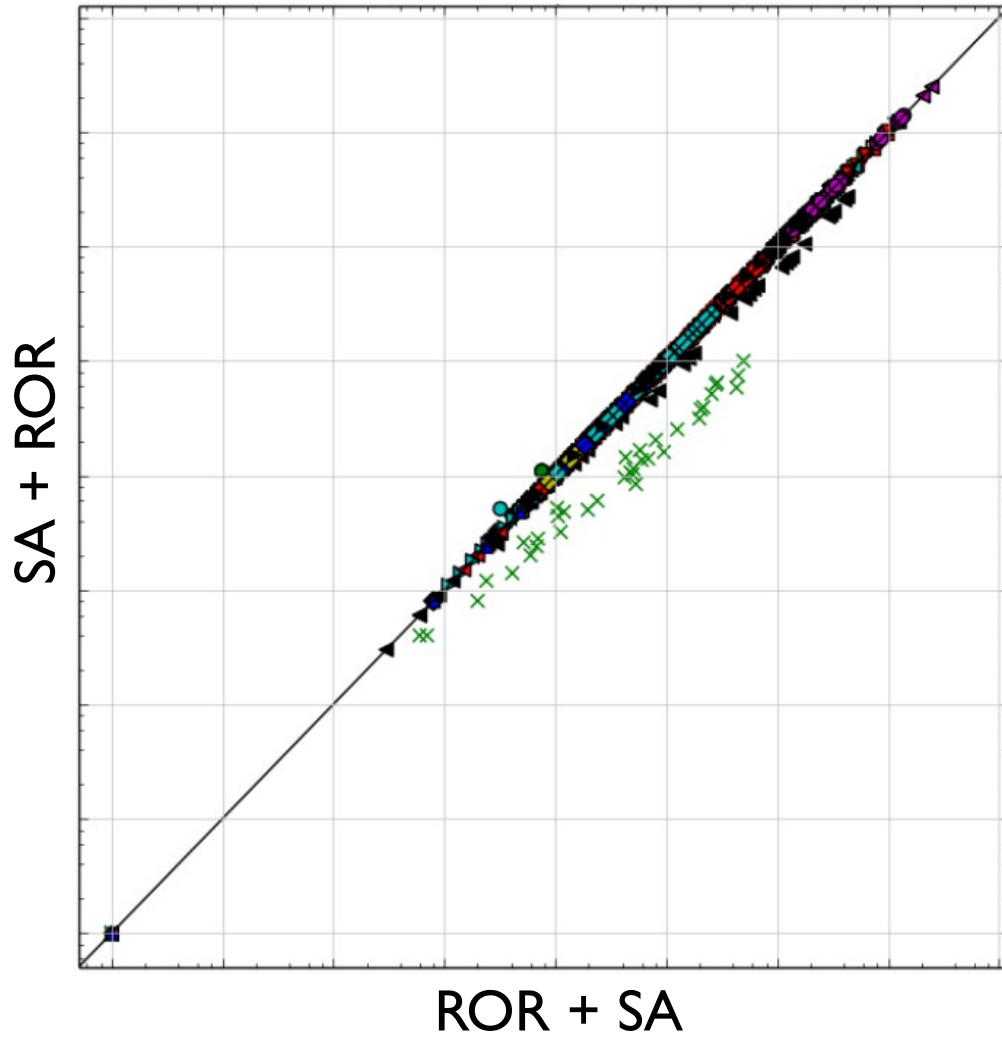
Synergies separately

Pruned Operators

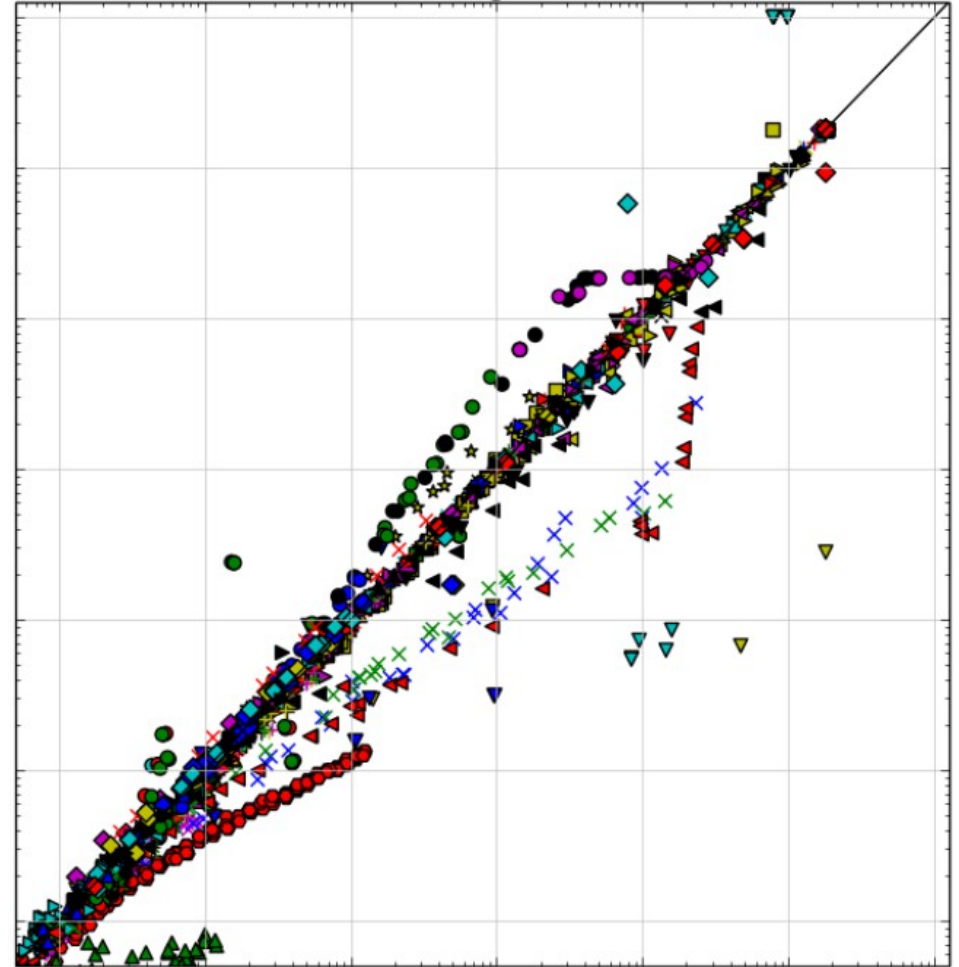


Synergies compared

Operators left



Planning Time



5. Conclusion

- ◆ Static Pruning can improve coverage
- ◆ Synergies exist & occur on IPC domains

Further research:

- ◆ less strict Safe Abstraction
- ◆ more fine-grained ROR
- ◆ satisficing Dominance Pruning

Thank you!