

Computing Planning Task Width via SAT Compilation

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24th of June 2026

Introduction

- › *width* : measure of the difficulty of a planning task
- › Hard to compute
- › Can help understand domain properties

Goal

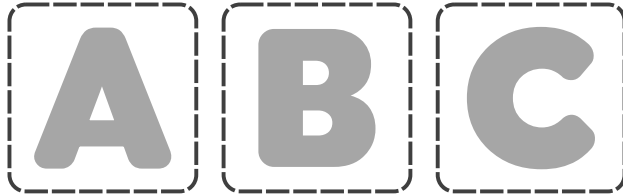
A theoretical, non-deterministic algorithm was developed to compute the width, we want to :

- › Ground this algorithm
- › Concrete software implementation
- › Automatically compute the width for any planning task

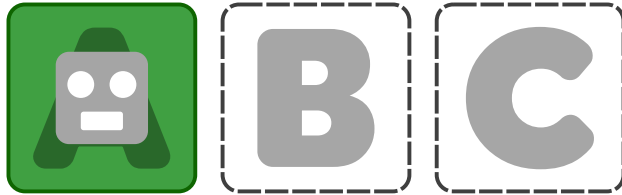
Meaning

Computing **Planning Task** Width via SAT Compilation

Example : Visit-All



Example : Visit-All



Example : Visit-All

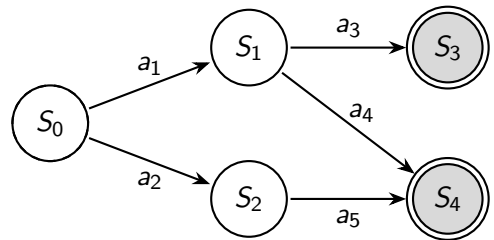


Example : Visit-All



Generalization : State Space

- > States
- > Actions
- > Transitions
- > Initial and Goal states



Propositional Logic

$$\varphi = (v_1 \wedge \neg v_2) \vee v_3$$

Propositional Planning Task

- › Set of variables V
- › Operators with effects and preconditions
- › States are assignments to variables
- › The goal and effects/preconditions are formulas over V

Example : Visit-All

- Cells A , B and C
- Variables like : "robot-on- A ", "visited- B ", "connected- A - B "
- Operators like : "move-from- B -to- C "
- Goal : visit all cells by moving between connected ones.

Example : Transition

- From { robot-on-*A*, visited-*A*, connected-*c*₁-*c*₂ }
- Via : move-from-*A*-to-*B*
- From { robot-on-*A*, visited-*A*, robot-on-*B*, visited-*B*, connected-*c*₁-*c*₂ }

Meaning

Computing Planning Task **Width** via SAT Compilation

Algorithm : $IW(i)$

Breadth-first search with pruning:

- Compute *novelty* of newly generated states
- Prune states with novelty higher than i
- Guaranteed to find optimal plan if i is the width of the task

(Seemingly) Obvious Solution

Iterate over i until $IW(i)$ finds a solution:

- Start with 1
- Go until $|V|$. Why ?
- Unfortunately, computes **effective** width not **true** width.

Real Solution

For a planning task Π , if $IW(i)$ finds a plan, i is not guaranteed to be the width, so we:

- Reject early if $IW(i)$ does **not** find a solution.
- Do additional checking if it does.

Reachability Graph

Inductively build graph G^i :

- › Start with all conjunctions $\leq i$, true in I
- › Add new nodes only if condition satisfied
- › Condition on directed edge between nodes t_1 and t_2

Reachability Condition

“All optimal plans for $\Pi(t_1)$ can be extended to be optimal plans for $\Pi(t_2)$ with just one operator.”

Meaning

Computing Planning Task Width via SAT Compilation

SAT Encoding of Planning Task

“There exists a plan for Π of length T ”

Example : SAT

“All rooms have a projector.”

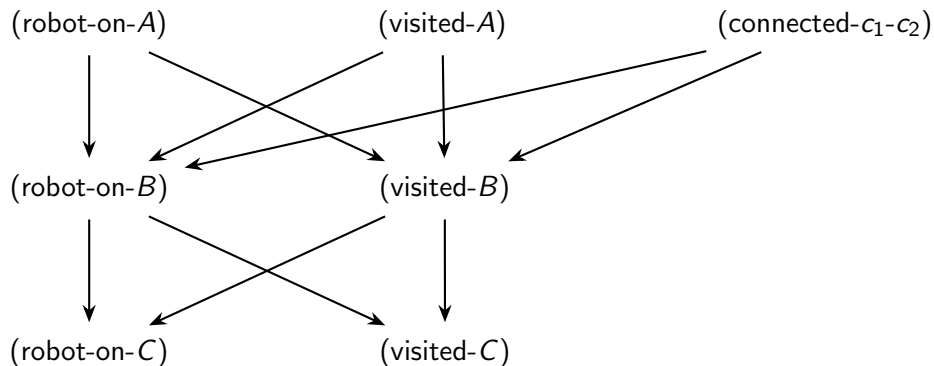
Example : SAT

“Theres exists a room with no projector.”

Reachability Condition

“There exists an optimal plan for $\Pi(t_1)$ that cannot be extended to be an optimal plan for $\Pi(t_2)$ with just one operator.”

Example : Visit-All



G^1 reachability graph

Example : Visit-All



Goal Implication

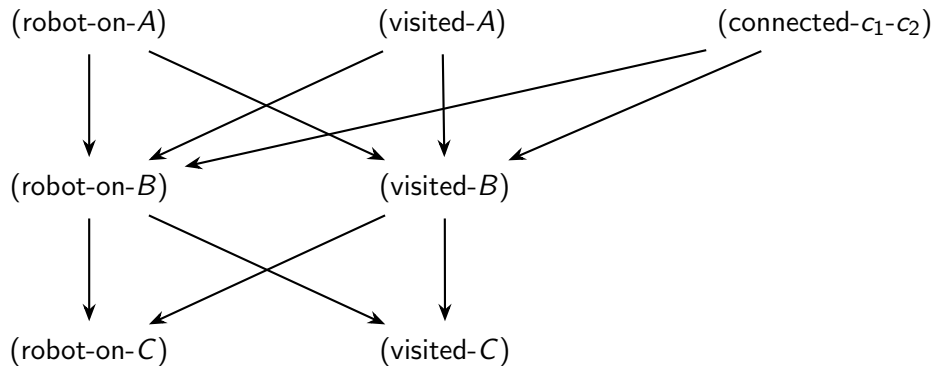
The graph is done, what now ?

- Loop through every node in that graph
- If one of them implies the goal, we found the width

Goal Implication Condition

“All optimal plans for $\Pi(t)$ are also optimal plans for Π .”

Example : Visit-All



G^1 reachability graph

Example : Visit-All



Software used

The implementation was made in Python using the `pyperplan` and `pysat` packages. Problems were in the PDDL format.

Problems during Implementation

- › `pyperplan` SAT encoding couldn't be used
- › `pyperplan` parsing code had to be modified
- › Built-in `pysat` classes were too memory inefficient
- › Encodings are cached

Experiments

- › instances from the downward-benchmarks repo
- › ran on sciCORE grid with 1ab

Results

Nir Lipovetzky and Hector Geffner, found upper bounds on the width of certain domains :

- › Blocks World : 2
- › Logistics : 2
- › n-puzzle : 2

Results

- › Low success rate of 6.28%, the rest either timed out or ran out of memory.
- › The bounded domains were correct
- › Several other domain's effective width was similar

Results

- › movie domain had 210 instances
- › All succeeded with width of 1
- › Conjecture an upper bound on the width

Future Work

- › Algorithmic Optimizations
- › Faster language
- › Parallelization

Questions?

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Backup

Domain	OOM Error	Timeout	Success
barman-opt14-strips (43)	36	7	0
blocks (302)	18	219	65
childsnaack-opt14-strips (15)	15	0	0
depot (188)	176	2	10
driverlog (250)	173	44	33
grid (19)	18	0	1
gripper (460)	35	425	0
logistics00 (249)	151	53	45
miconic (2325)	2143	167	15
movie (210)	0	0	210
mystery (45)	37	4	4
pipesworld-notankage (259)	183	65	11
rovers (558)	455	95	8
satellite (1742)	1735	4	3
storage (240)	205	23	12
tpp (85)	85	0	0
visitall-opt11-strips (505)	284	185	36
zenotravel (215)	163	21	31
Sum (7710)	5912	1314	484
Percentage (100%)	76.68%	17.04%	6.28%

Backup

Domain (Successes)	Minimum width	Average width	Maximum width
barman-opt14-strips (0)	-	-	-
blocks (65)	0	0,69	1
childsnack-opt14-strips (0)	-	-	-
driverlog (33)	0	0,06	1
gripper (0)	-	-	-
miconic (15)	2	2	2
movie (210)	1	1	1
pipesworld-notankage (11)	1	1	1
rovers (8)	1	1	1
storage (12)	1	1	1
tpp (0)	-	-	-
visitall-opt11-strips (36)	0	0,72	1
zenotravel (31)	0	0,06	1
Average (421)	0,67	0,84	1,11

Backup

Domain (Successes)	Width
depot (10)	0
grid (1)	0
logistics00 (45)	0
mystery (4)	0
satellite (3)	0

Backup

- **Miconic** : Out of 650 instances, they found all of them had an effective width of 2. In our case only 15 instances finished computation but all of them reported a width of 2 as well.
- **Visitall** : Out of 21859 instances, they found all of them had an effective width of 1. In our case only 36 instances finished computation but the reported maximum width was indeed 1.
- **Storage** : Out of 240 instances, they found all of them had an effective width of 1. In our case only 12 instances finished computation but all of them reported a width of 1 as well.