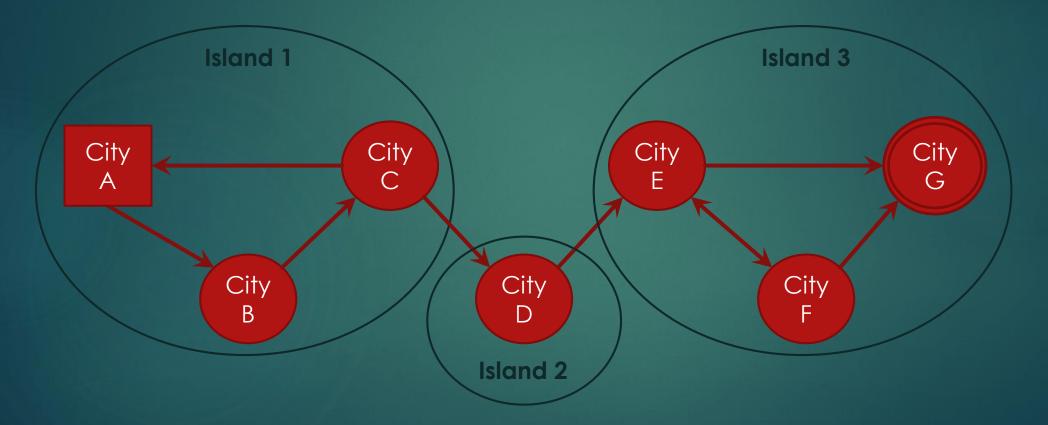
Solving Delete-Relaxed Planning Tasks by Using Cut Sets BACHELOR THESIS PRESENTATION BY MARVIN BUFF

Overview

- Classical Planning
- What is the Problem?
- The Flow-Cut Algorithm
- Experiments / Results
- Conclusion

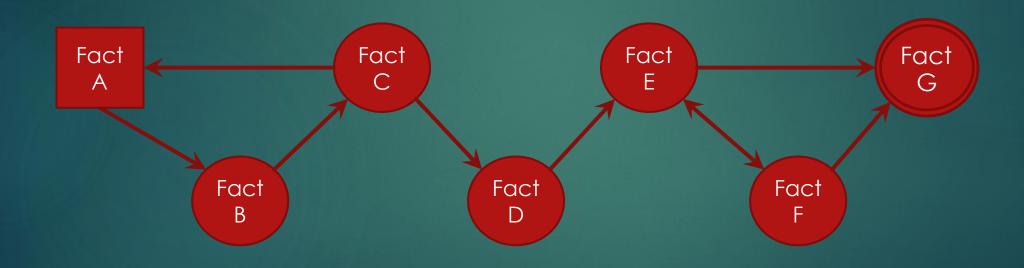
Classical Planning

Island Problem



Classical Planning

Causal Graph

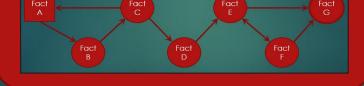


What is the Problem? Exponential Growth!

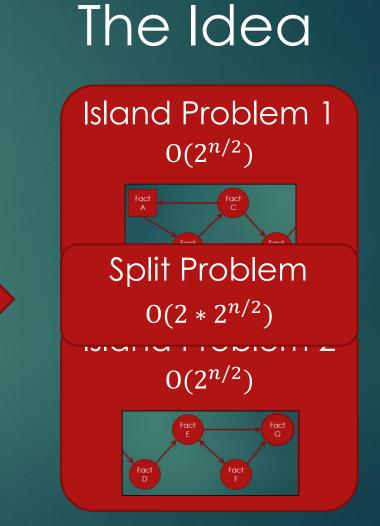


Flow-Cut Algorithm



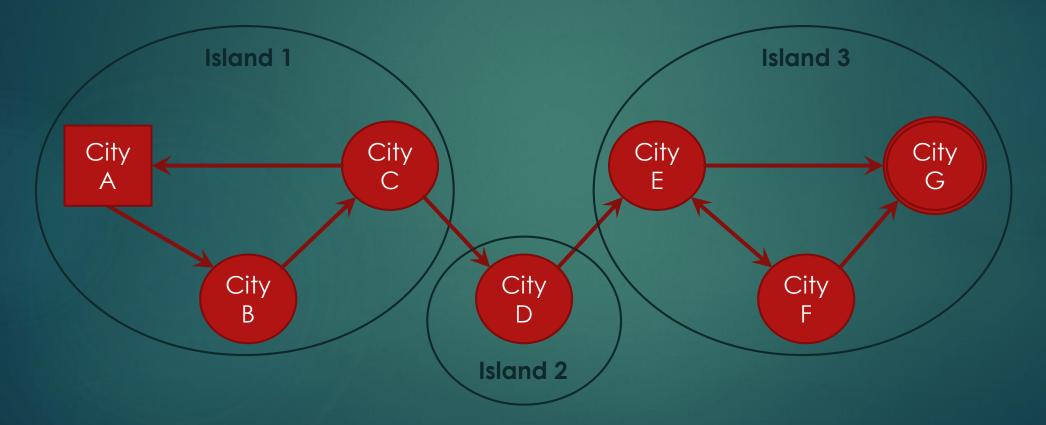


Splitting

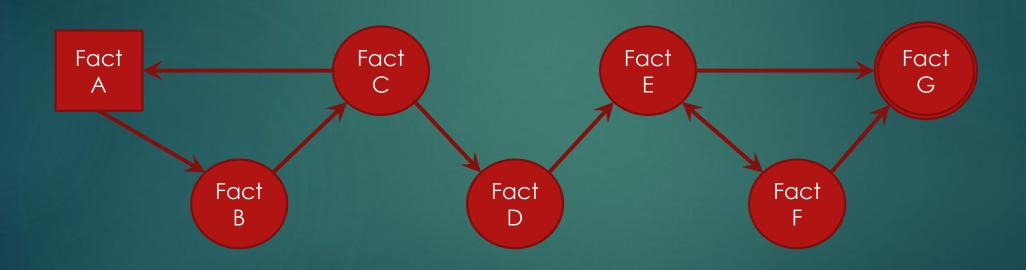


Flow-Cut Algorithm

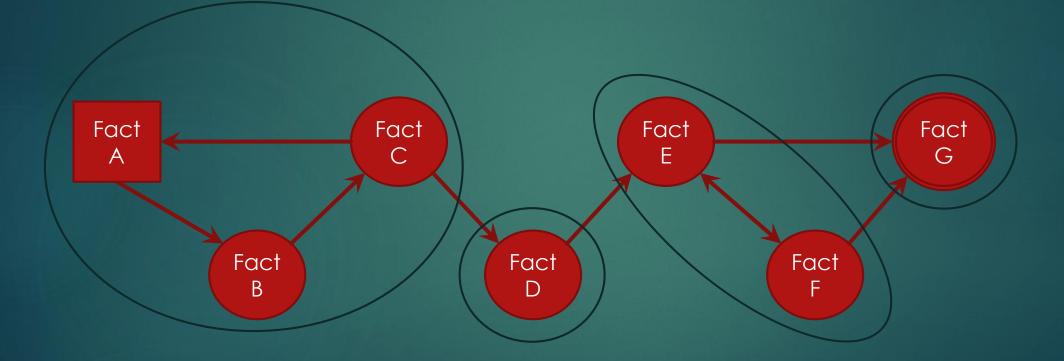
Given Problem

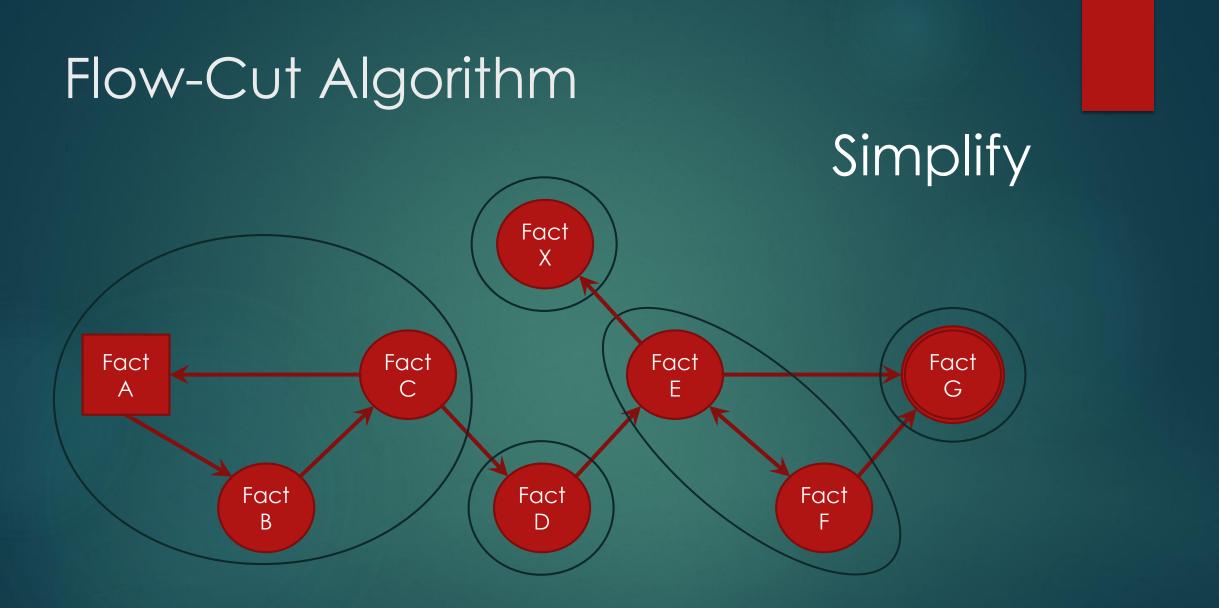


Flow-Cut Algorithm Derive Causal Graph



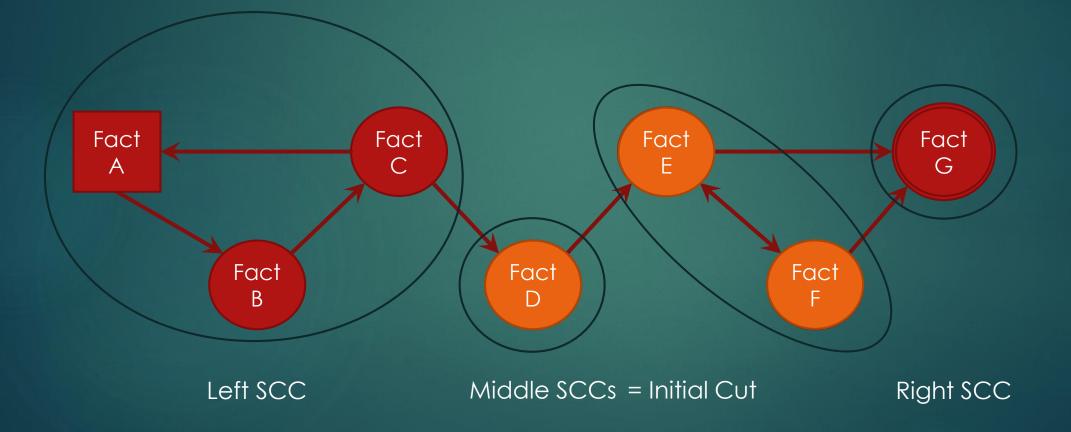
Flow-Cut Algorithm Determine SCC's





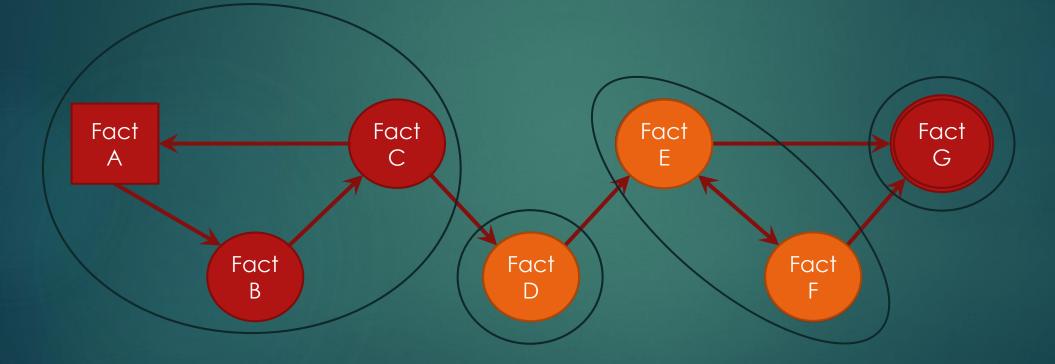
Flow-Cut Algorithm

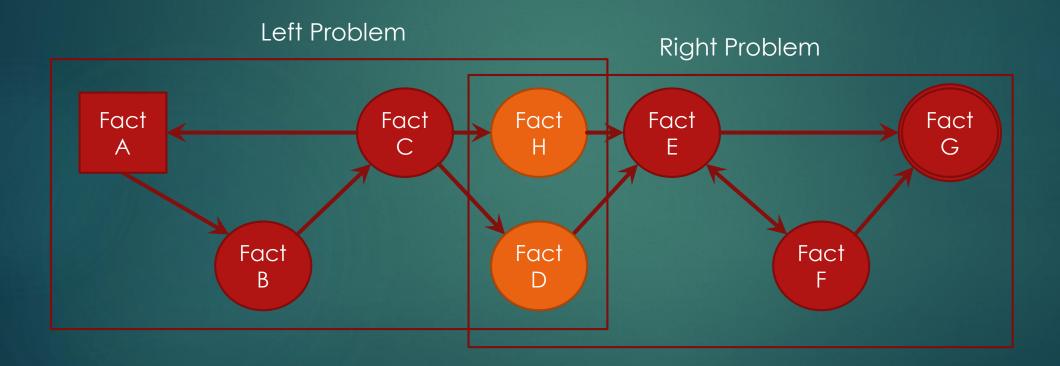
Initial Cut

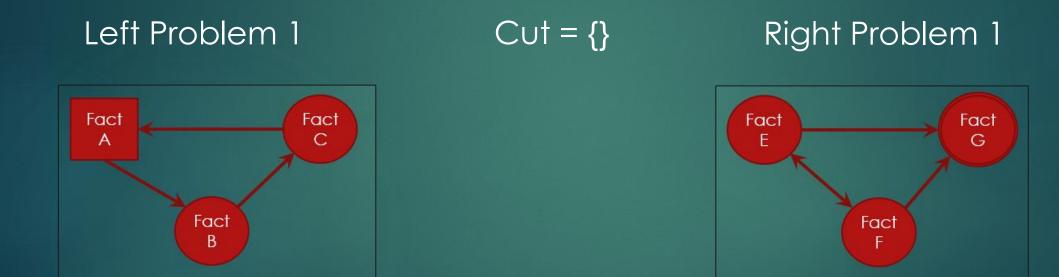


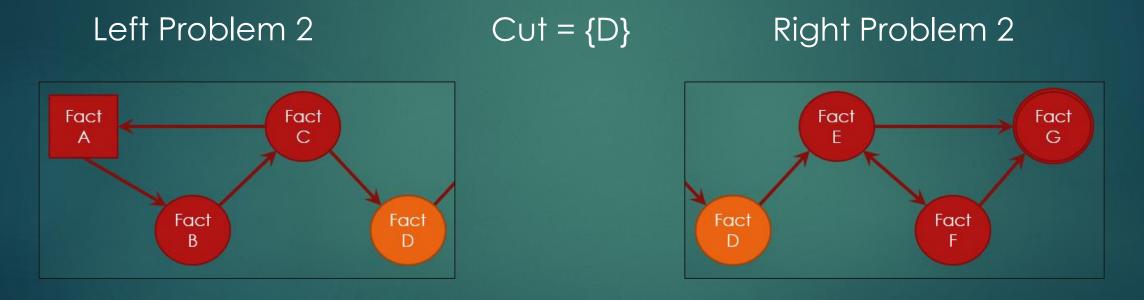
Flow-Cut Algorithm

Minimize Cut

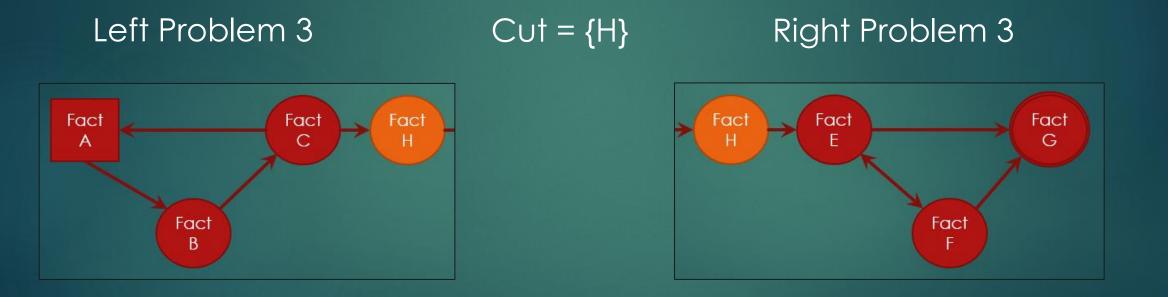




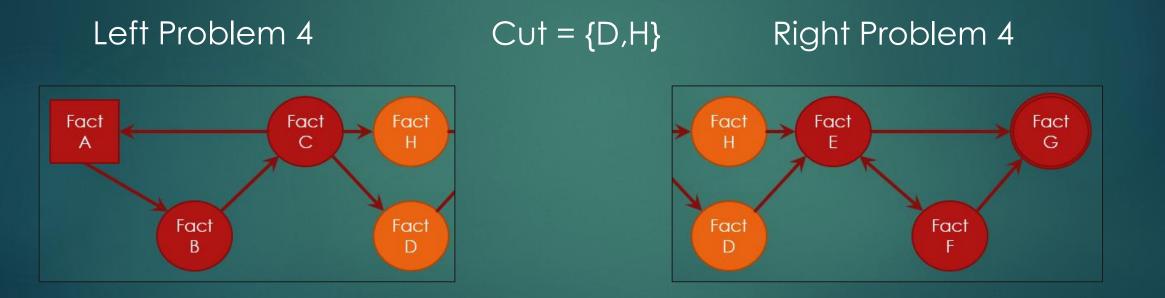




Solution = 3 + 2



Solution = 3 + 2



Solution = 4 + 2

Setup

- Implemented in C++
- Tested on IPC Benchmark
- Run over 60 minutes per problem

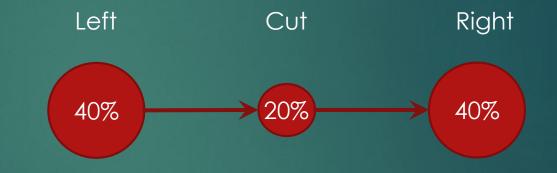
Results

- ► Type A: Solvable
- ► Type B: Big Cut
- ► Type C: No Cut

Type A: Solvable



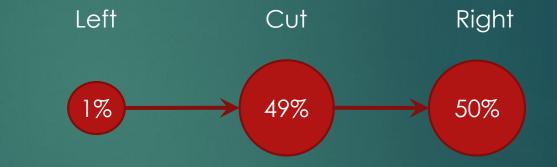
► satellite



Type A: Solvable

Unbalanced Domains

- Mystery
- ► Rovers
- ► trucks-strips



Type B: Big Cut

Domains with Big Cut

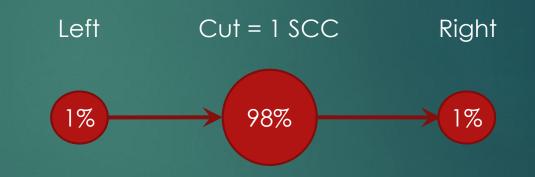
- childsnack
- ▶ no-mystery
- ▶ parcprinter
- ► tidybot



Type B: Big Cut

Domains with Big Cut

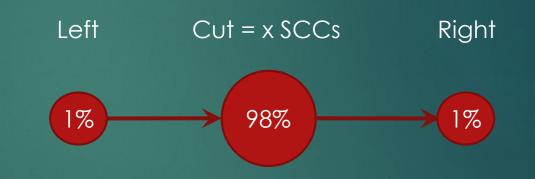
- childsnack
- ▶ no-mystery
- ► parcprinter
- ► tidybot



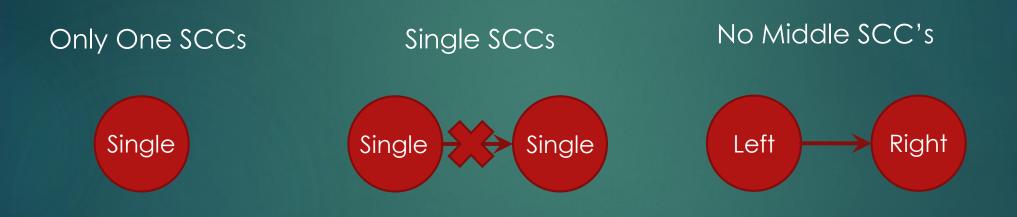
Type B: Big Cut

Domains with Big Cut

- childsnack
- ▶ no-mystery
- ► parcprinter
- ► tidybot



Type C: No Cut



Conclusion

- ► What did we do?
 - Algorithm to compute h^+
- What could be done different?
 - ► No SCCs
 - Undirected Structure
 - Multiple Left- /Right-Parts

Questions?