

A Proof System for Unsolvable Planning Tasks

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Motivation

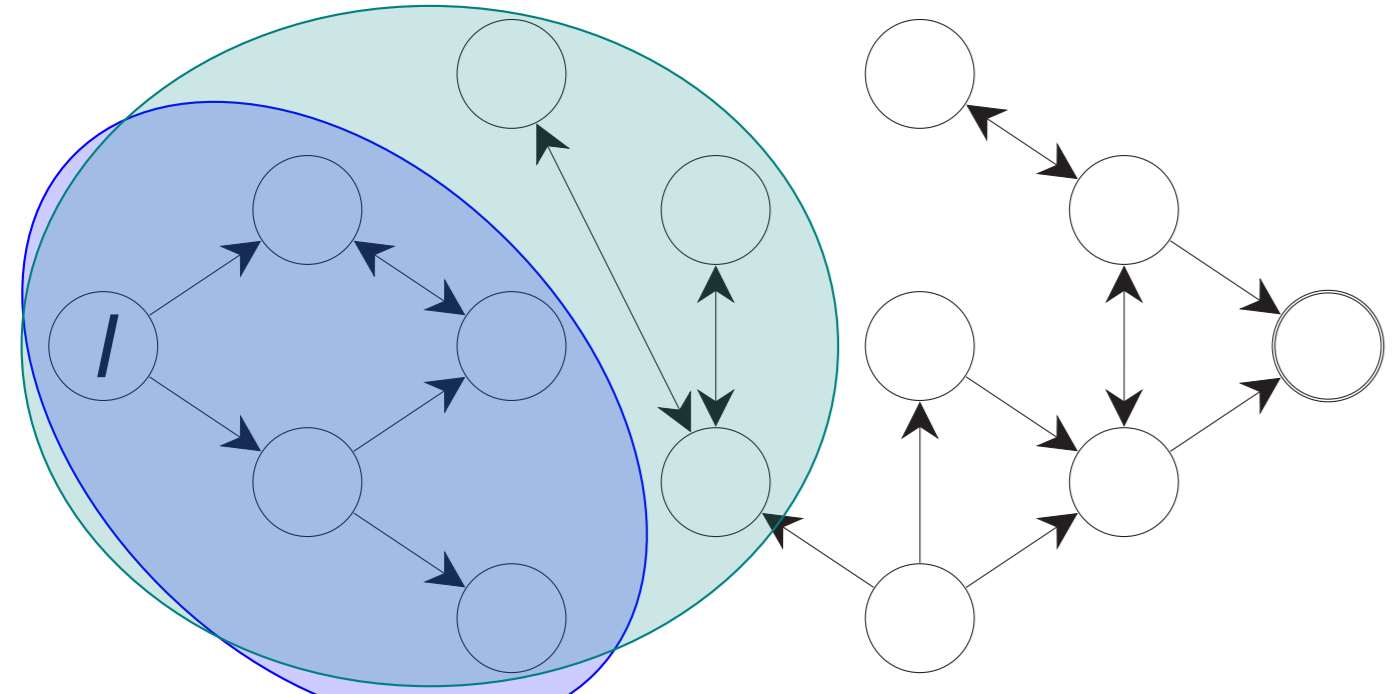
planner should emit proof for its output:

- ▶ solvable: plan
- ▶ unsolvable: inductive certificate [Eriksson et al. 2017]

weakness of inductive certificates: **not compositional**

↪ new approach: proof system

Inductive Certificates



no path from I to goal
↪ partition into S_I and S_G

S_I is inductive
↪ no outgoing edges

A state set S is an inductive certificate iff

1. $I \in S$,
2. S contains no goal and
3. applying any $a \in A$ to any $s \in S$ leads to some $s' \in S$. (written $S[A] \subseteq S$)

Proof System

build up a knowledge base:

- ▶ basic statements
 - ▶ state facts about concrete objects
 - ▶ need to be verified
- ▶ derivation rules
 - ▶ derive new knowledge from existing knowledge
 - ▶ universally true (only correct application needs to be verified)

Example: Set Theory

objects: elements a, b, c, d, e and sets $A = \{a, b\}$, $B = \{b, c, e\}$, $C = \{b, c\}$

basic statements:

- ▶ $(A \cap B) \subseteq C$
- ▶ $b \in (A \cap B)$

derivation rules:

- ▶ $X \subseteq Y, Y \subseteq Z \rightarrow X \subseteq Z$
- ▶ $x \in X, X \subseteq Y \rightarrow x \in Y$

Unsolvability Proof System

objects: state sets S described by

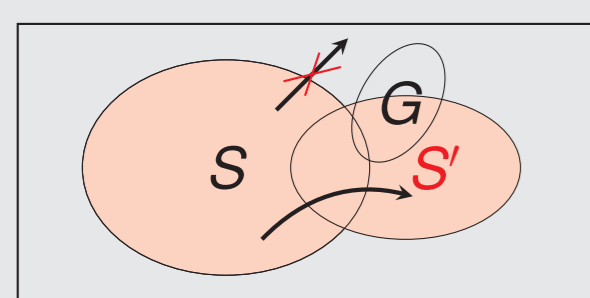
- ▶ BDDs
- ▶ Horn formulas
- ▶ 2CNF formulas
- ▶ explicit

types of statements:

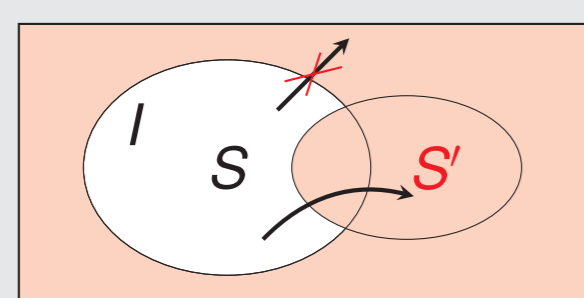
- ▶ S is dead (no plan through any $s \in S$)
- ▶ $S \subseteq S'$
- ▶ task unsolvable

Derivation Rules

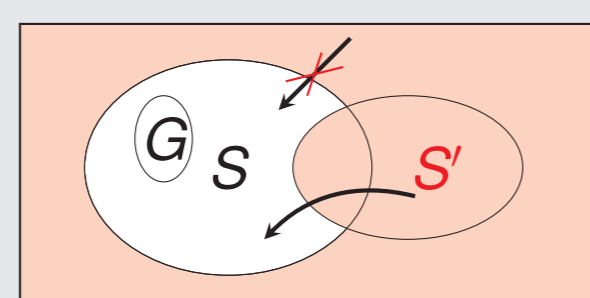
- | | | |
|-----------|---|-------------------------------|
| D1 | \emptyset is dead | \emptyset is dead |
| D2 | S dead, S' dead | $\rightarrow S \cup S'$ dead |
| D3 | $S' \subseteq S$, S dead | $\rightarrow S'$ dead |
| D4 | $\{I\}$ dead | \rightarrow task unsolvable |
| D5 | G dead | \rightarrow task unsolvable |
| D6 | $S[A] \subseteq S \cup S'$, S' dead, $S \cap G$ dead | $\rightarrow S$ dead |
| D7 | $S[A] \subseteq S \cup S'$, S' dead, $\{I\} \subseteq S$ | $\rightarrow \bar{S}$ dead |
| D8 | $[A]S \subseteq S \cup S'$, S' dead, $\bar{S} \cap G$ dead | $\rightarrow \bar{S}$ dead |
| D9 | $[A]S \subseteq S \cup S'$, S' dead, $\{I\} \subseteq \bar{S}$ | $\rightarrow S$ dead |



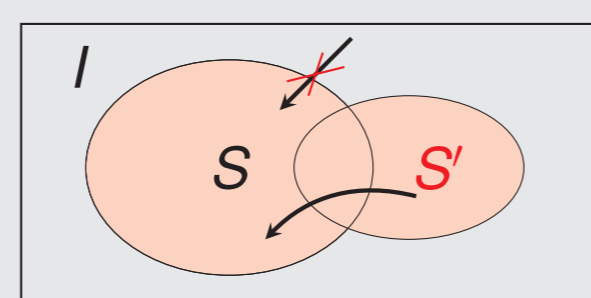
D6



D7



D8



D9

Basic Statements

restrict basic statements to cases that are verifiable in polynomial time:

- B1** $L \subseteq L'$ mixed representations for L, L' in some cases
- B2** $X \subseteq X' \cup X''$
- B3** $L \cap G \subseteq L'$
- B4** $X[A] \subseteq X \cup L'$
- B5** $[A]X \subseteq X \cup L'$

X : constant ($\{I\}$, G , \emptyset) or set variable (explicitly represented set)

L : constant, set variable or their complement

Proof Generation

examples of covered planning techniques:

- ▶ explicit and symbolic blind search
- ▶ heuristic search with
 - ▶ delete-relaxation heuristic
 - ▶ $h^{M\&S}$ with linear merge strategy
 - ▶ h^C
- ↪ combination of multiple heuristics now possible
- ▶ trapper [Lipovetzky et al. 2016]
- ▶ clause learning state space search [Steinmetz and Hoffmann 2016]
- ▶ h^2 -based preprocessing [Alcázar and Torralba 2015]

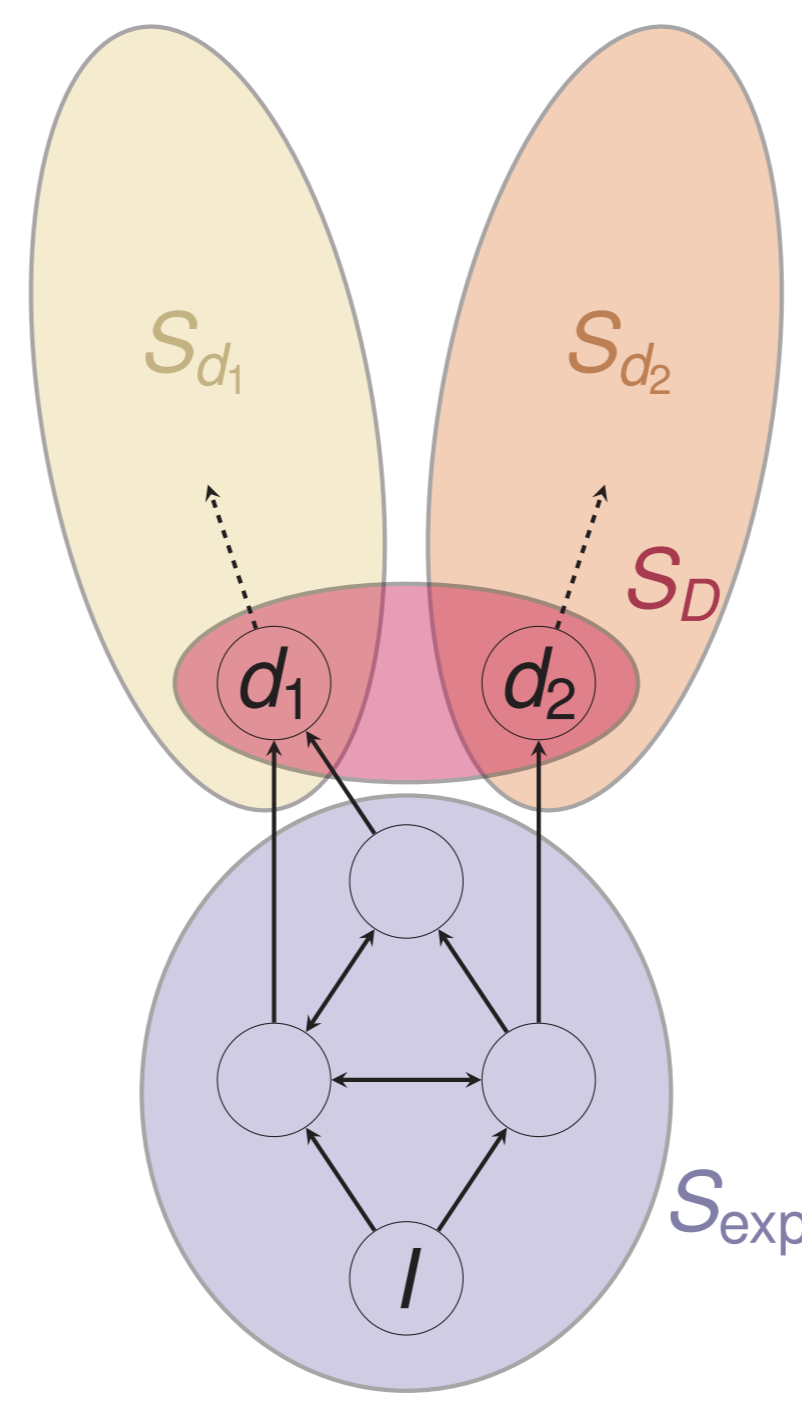
Translating Inductive Certificates

inductive certificate S : no successor, no goal and contains I

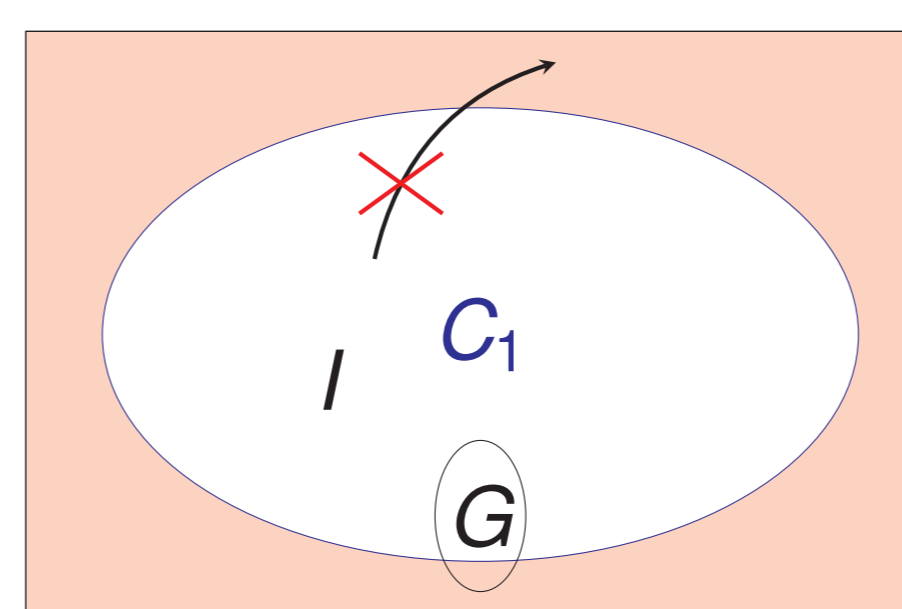
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|-----|-----------------------------------|------------|-----|---------------------|----------------|
| (1) | \emptyset dead | D1 | (5) | S dead | D6 (2),(1),(4) |
| (2) | $S[A] \subseteq S \cup \emptyset$ | B4 | (6) | $\{I\} \subseteq S$ | B1 |
| (3) | $S \cap G \subseteq \emptyset$ | B3 | (7) | $\{I\}$ dead | D3 (6),(5) |
| (4) | $S \cap G$ dead | D3 (3),(1) | (8) | task unsolvable | D4 (7) |

Heuristic Search

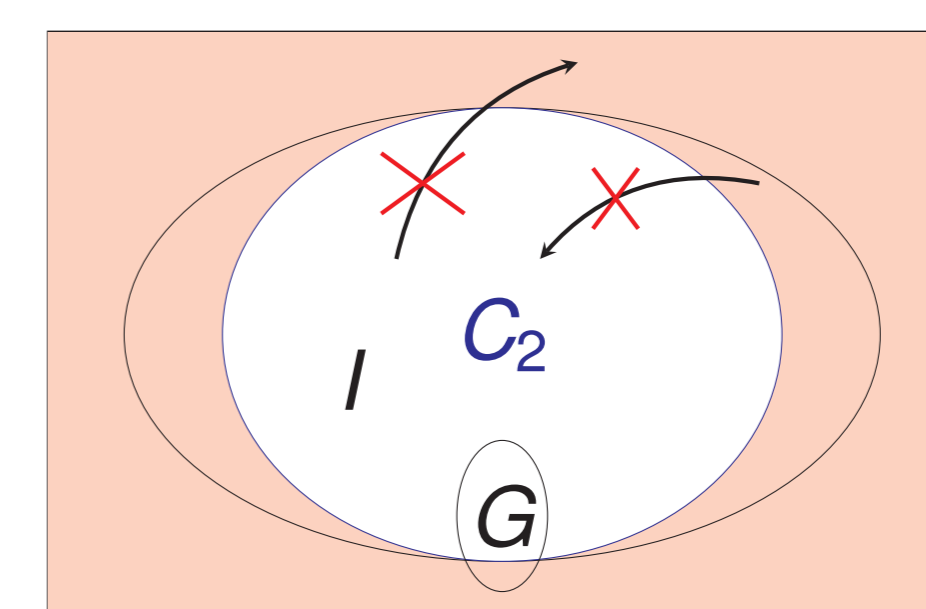
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|------|---|-------------------|
| (1) | \emptyset dead | D1 |
| (2) | $S_{d_1}[A] \subseteq S_{d_1} \cup \emptyset$ | B4 |
| (3) | $S_{d_1} \cap G \subseteq \emptyset$ | B3 |
| (4) | $S_{d_1} \cap G$ dead | D3 (3),(1) |
| (5) | S_{d_1} dead | D6 (2),(1),(4) |
| (6) | $\{d_1\} \subseteq S_{d_1}$ | B1 |
| (7) | $\{d_1\}$ dead | D3 (6),(5) |
| ... | | |
| (8) | $\{d_2\}$ dead | D3 ... |
| (9) | $\{d_1\} \cup \{d_2\}$ dead | D2 (7),(8) |
| (10) | $S_D \subseteq \{d_1\} \cup \{d_2\}$ | B2 |
| (11) | S_D dead | D3 (10),(9) |
| (12) | $S_{exp}[A] \subseteq S_{exp} \cup S_D$ | B4 |
| (13) | $S_{exp} \cap G \subseteq \emptyset$ | B3 |
| (14) | $S_{exp} \cap G$ dead | D3 (13),(1) |
| (15) | S_{exp} dead | D6 (12),(11),(14) |
| (16) | $\{I\} \subseteq S_{exp}$ | B1 |
| (17) | $\{I\}$ dead | D3 (16),(15) |
| (18) | task unsolvable | D4 (17) |



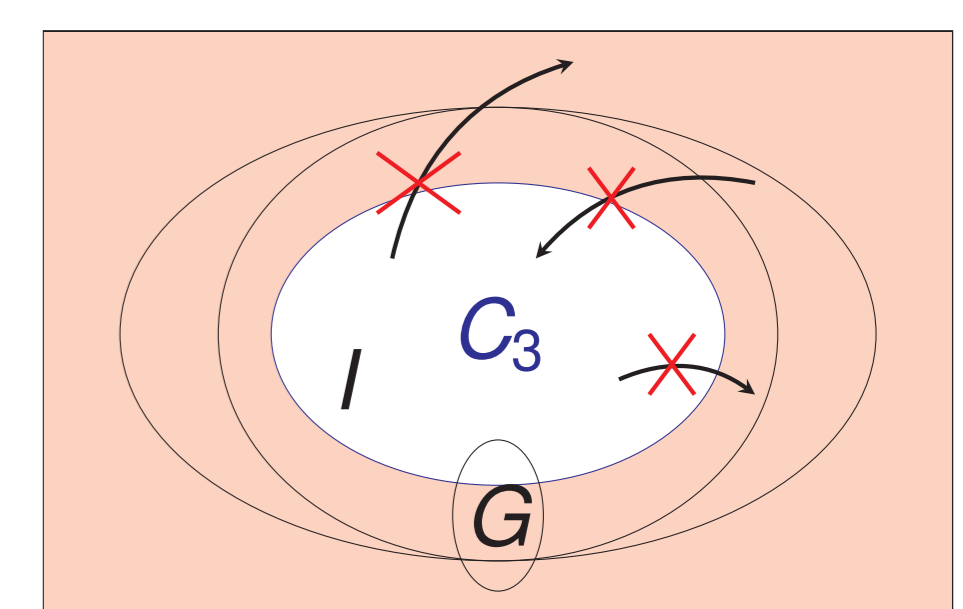
h^2 -based Preprocessing



$C_1[A] \subseteq C_1 \cup \emptyset$
 \emptyset dead, $I \in C_1$
 $\rightarrow \bar{C}_1$ dead



$[A]C_2 \subseteq C_2 \cup \bar{C}_1$
 \bar{C}_1 dead, $\bar{C}_2 \cap G$ dead
 $\rightarrow \bar{C}_2$ dead



$C_3[A] \subseteq C_3 \cup \bar{C}_2$
 \bar{C}_2 dead, $I \in C_3$
 $\rightarrow \bar{C}_3$ dead

Experimental Evaluation

	base	certifying	verifier
FD- h^{\max}	211	168 (135)*	167 (125)*
FD- $h^{M\&S}$	230	191 (200)*	184 (163)*
FD- h^2	183	177	177
FD-max($h^{M\&S}, h^2$)	204	199	195
DFS-CL	385	386	383

*inductive certificate approach

