

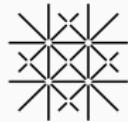
Landmark Progression in Heuristic Search

Clemens Büchner¹ Thomas Keller^{1,2} Salomé Eriksson¹ Malte Helmert¹

¹University of Basel

²University of Zürich

July 12, 2023



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of Basel



University of
Zurich UZH

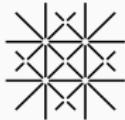
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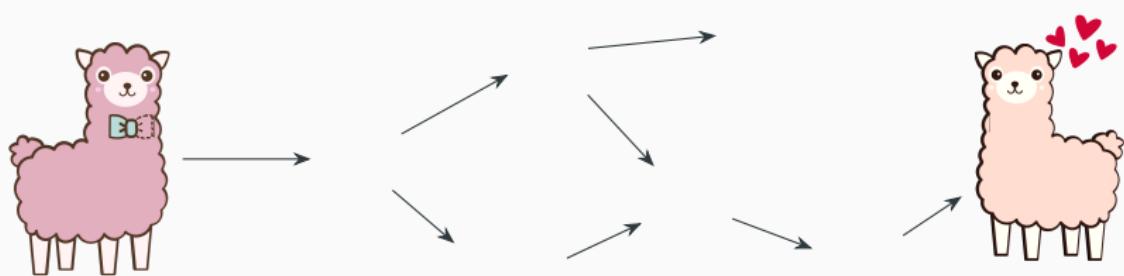
University
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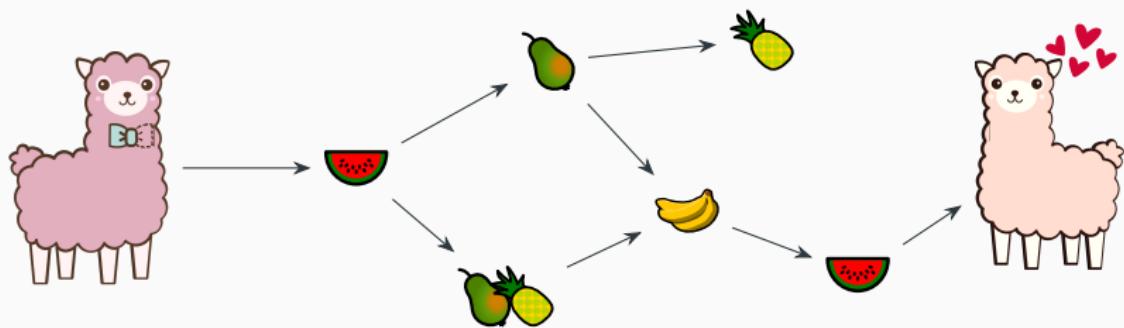
University of
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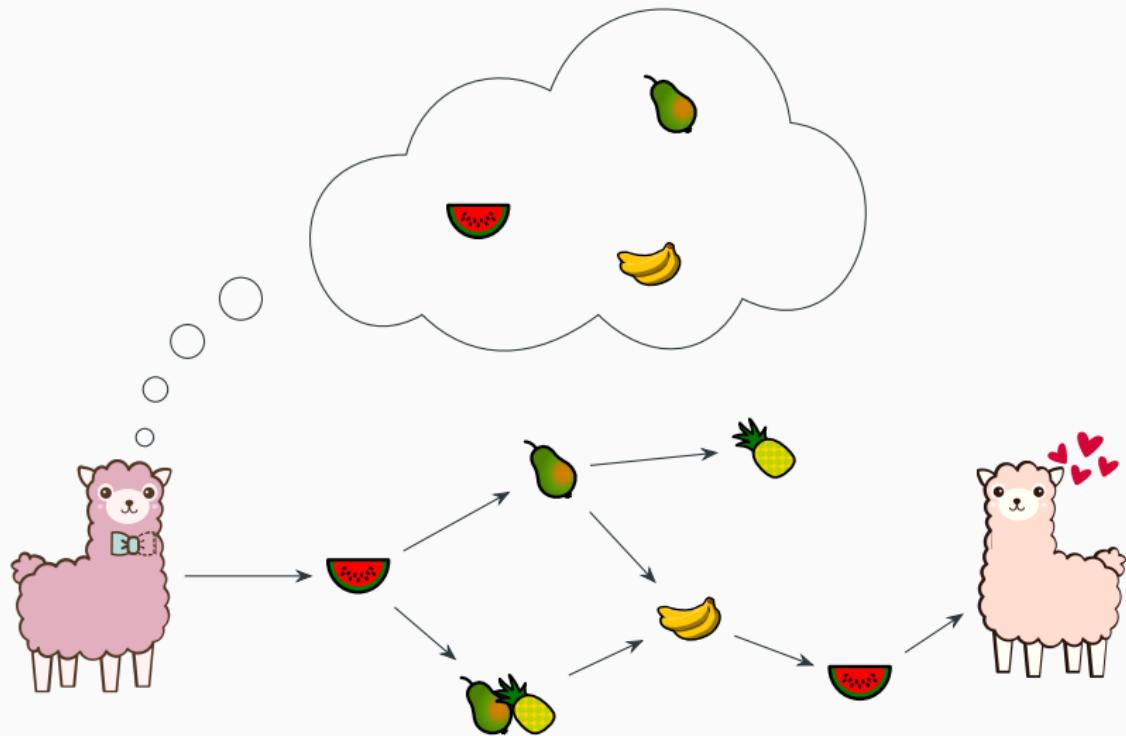
Thinking like LAMA



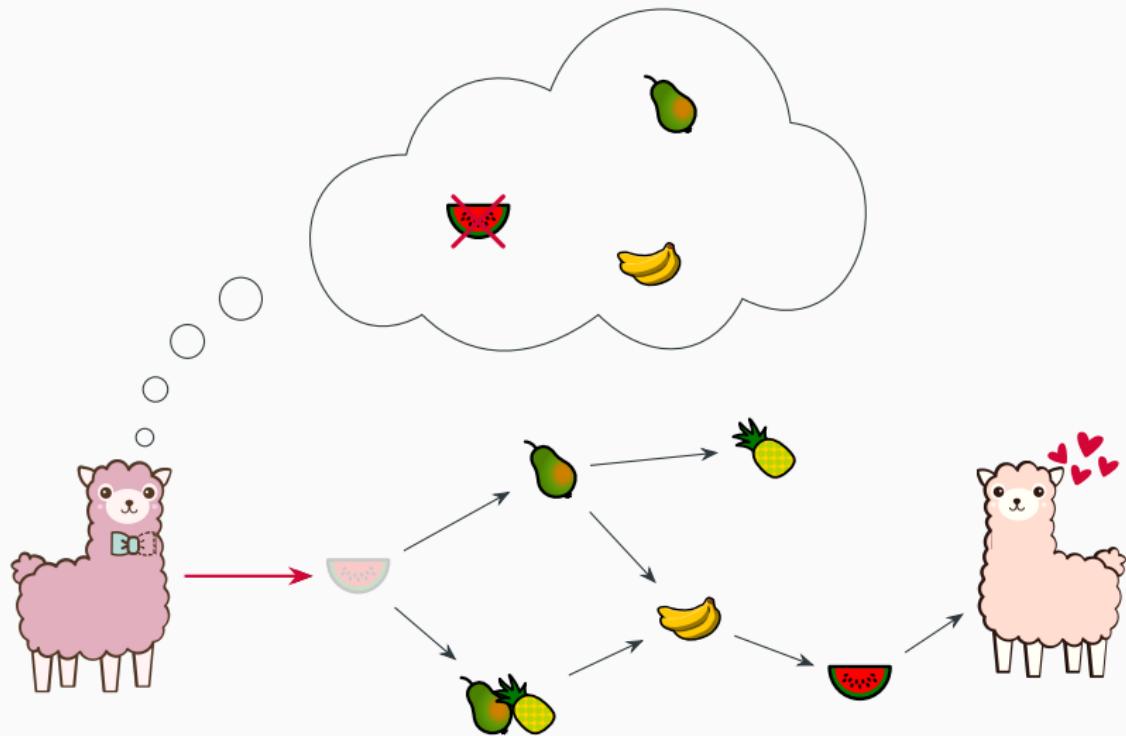
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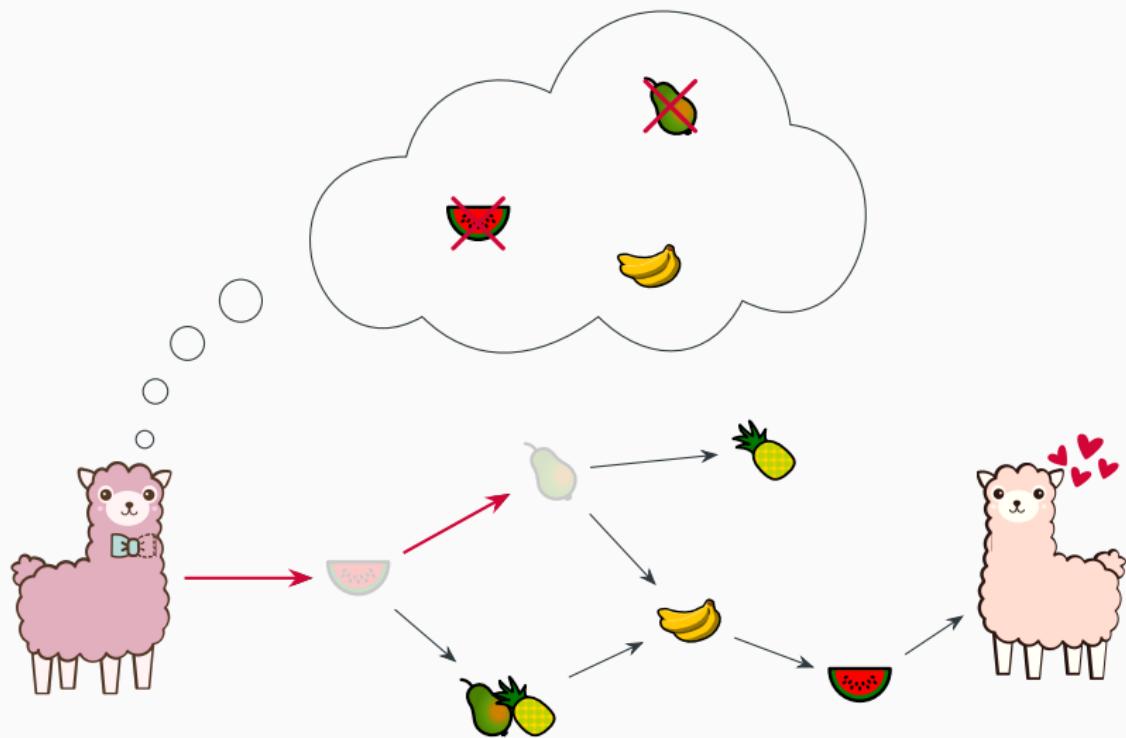
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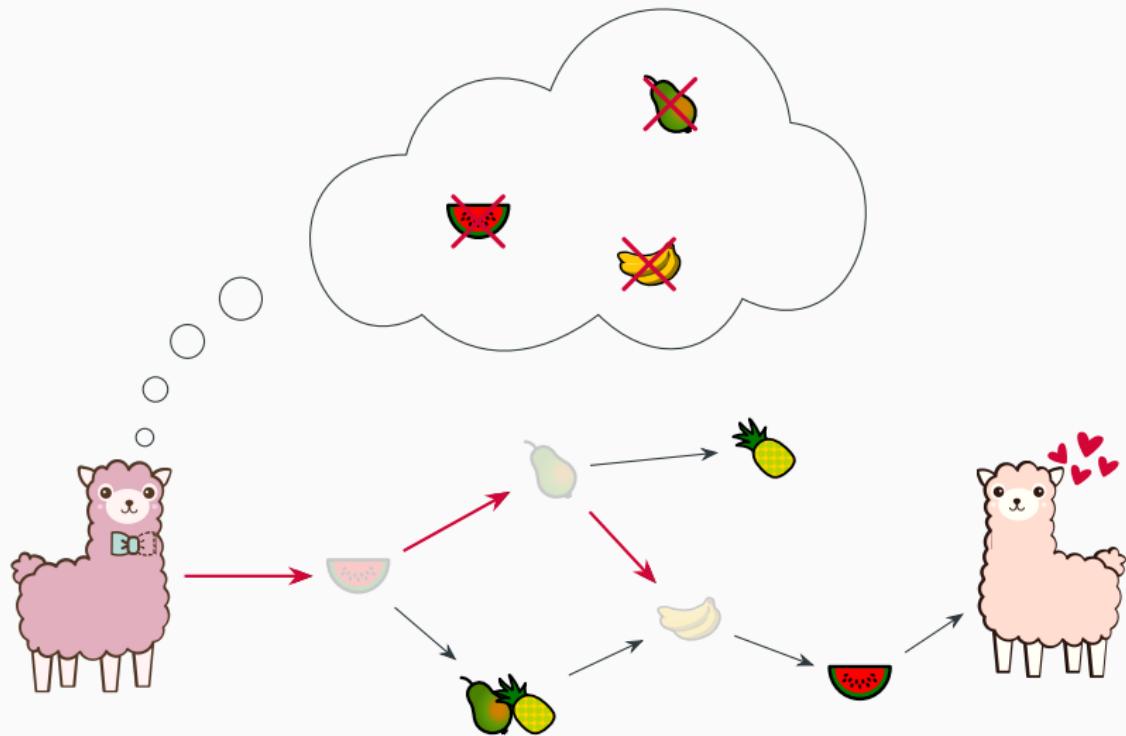
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Thinking like LAMA



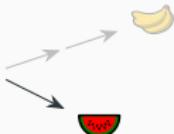
Thinking like LAMA



LAMA's Recipe for Success



Always try to improve yourself.
(anytime search)

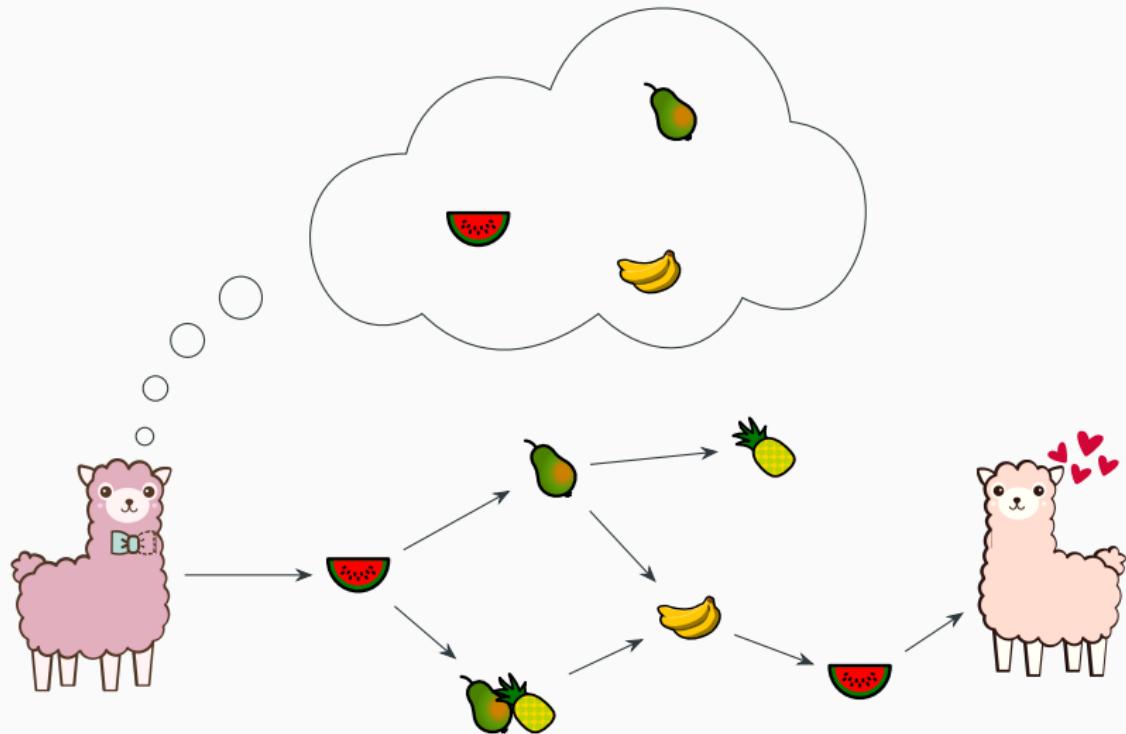


Follow strong smells.
(preferred operators)

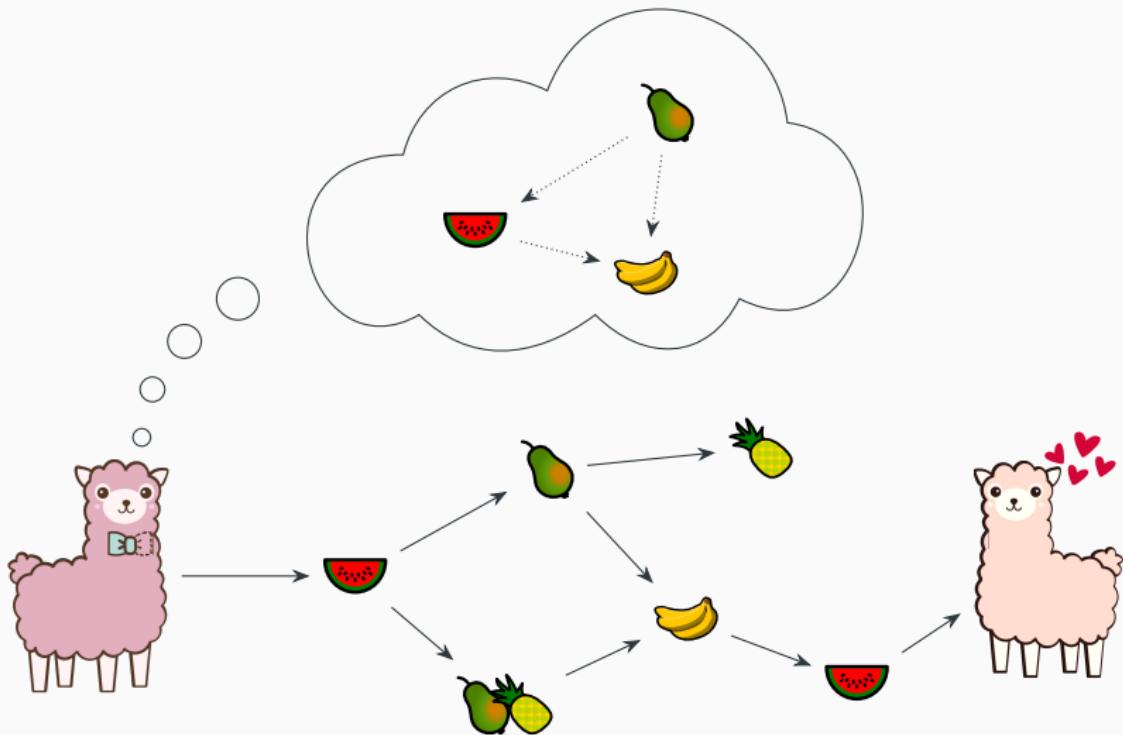


Accept help from friends.
(FF heuristic)

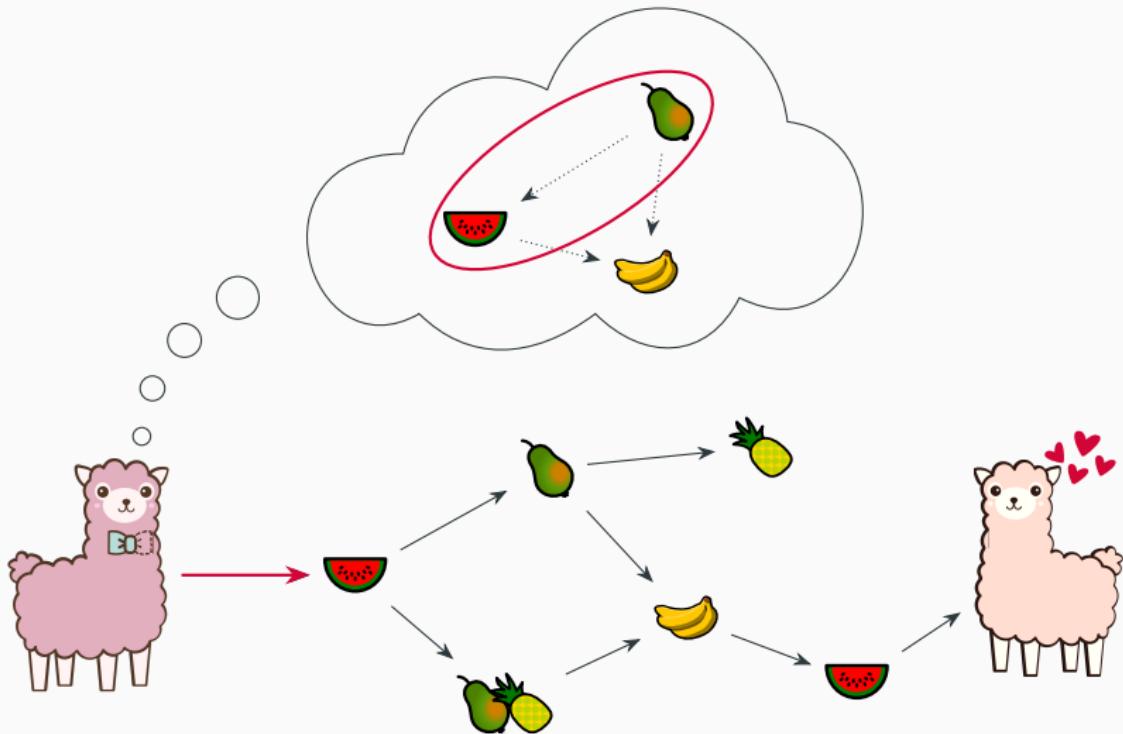
Ordered Landmarks



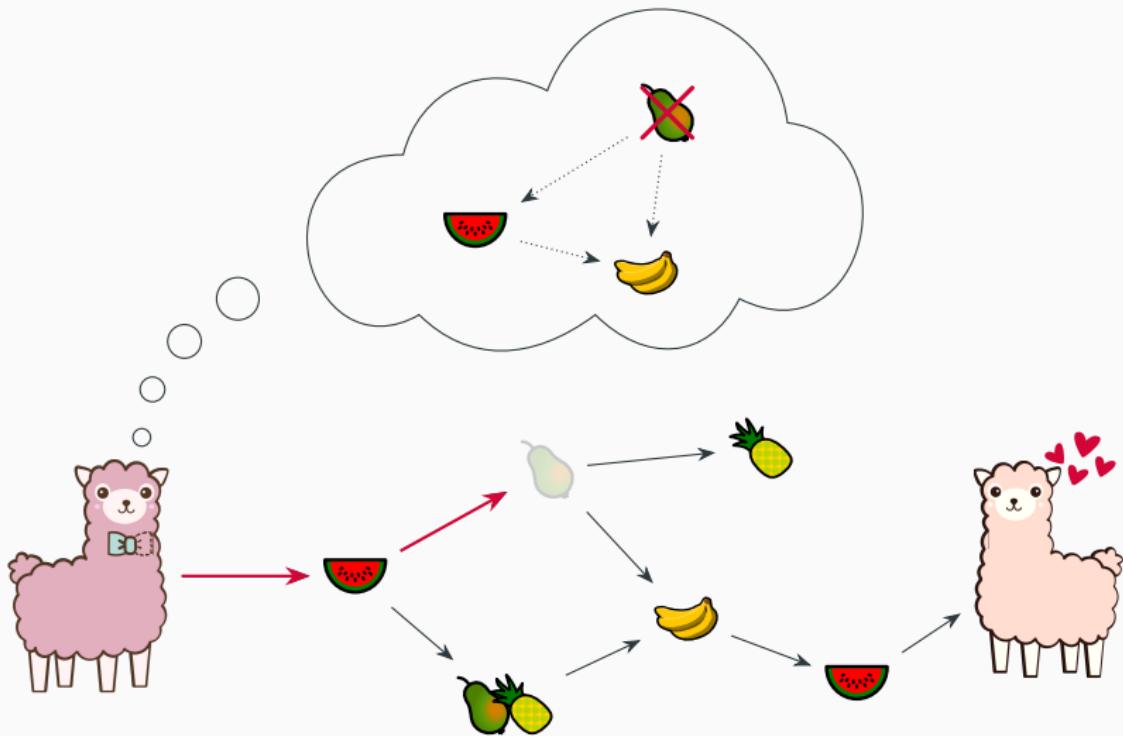
Ordered Landmarks



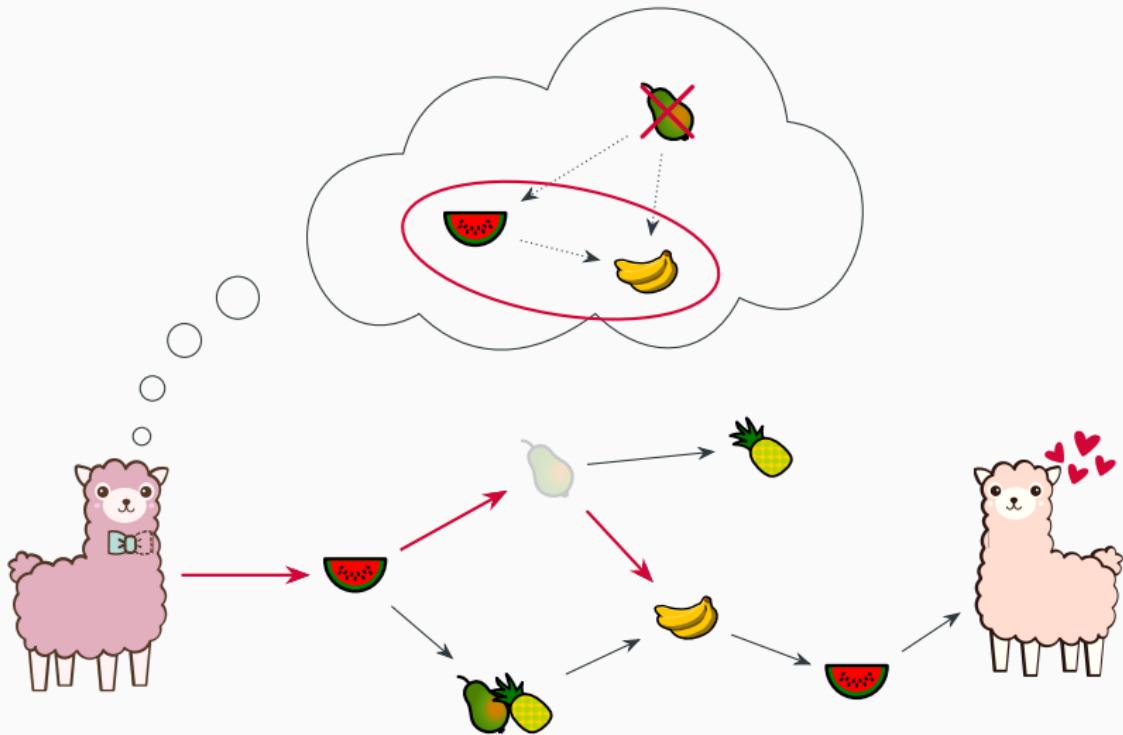
Ordered Landmarks



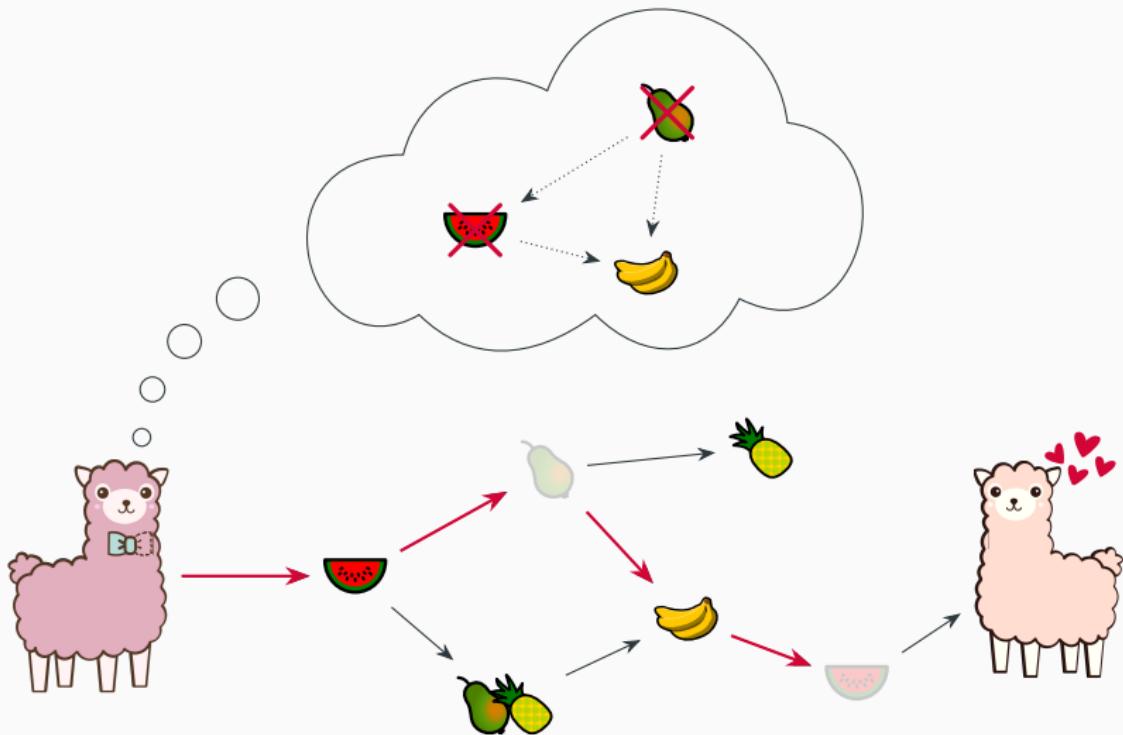
Ordered Landmarks



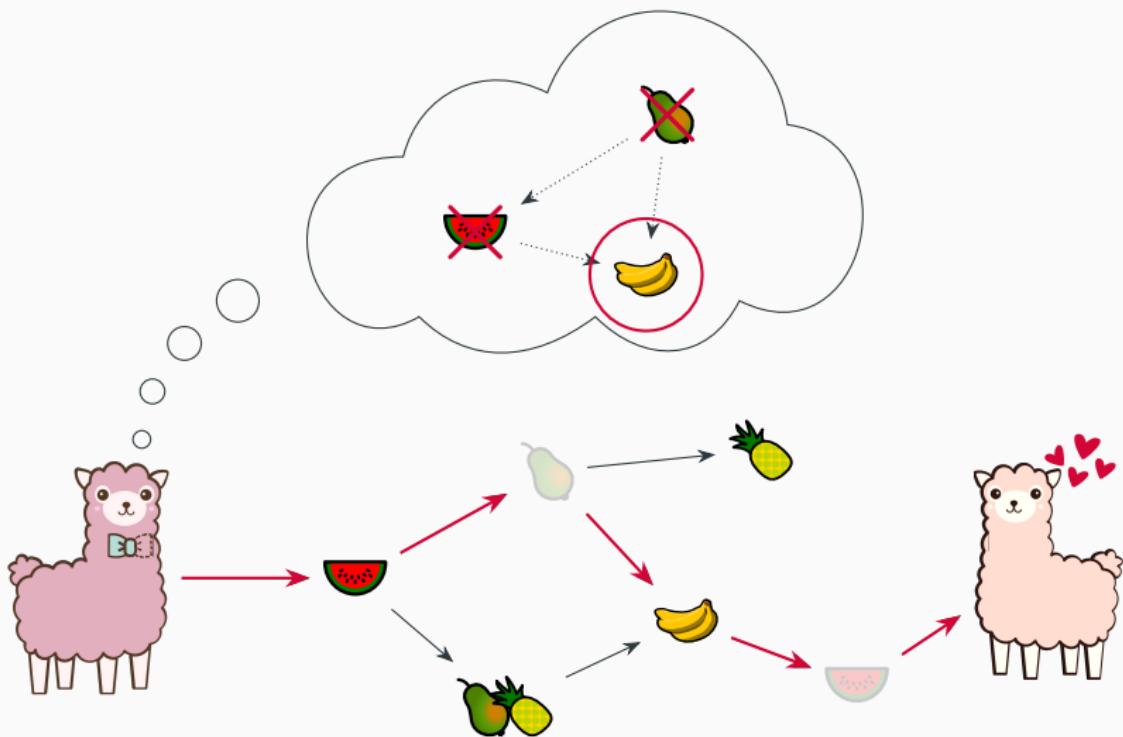
Ordered Landmarks



Ordered Landmarks



Ordered Landmarks



Issue

Observation

some landmarks never accepted

~~ worst case: LAMA finds no solution

Problem

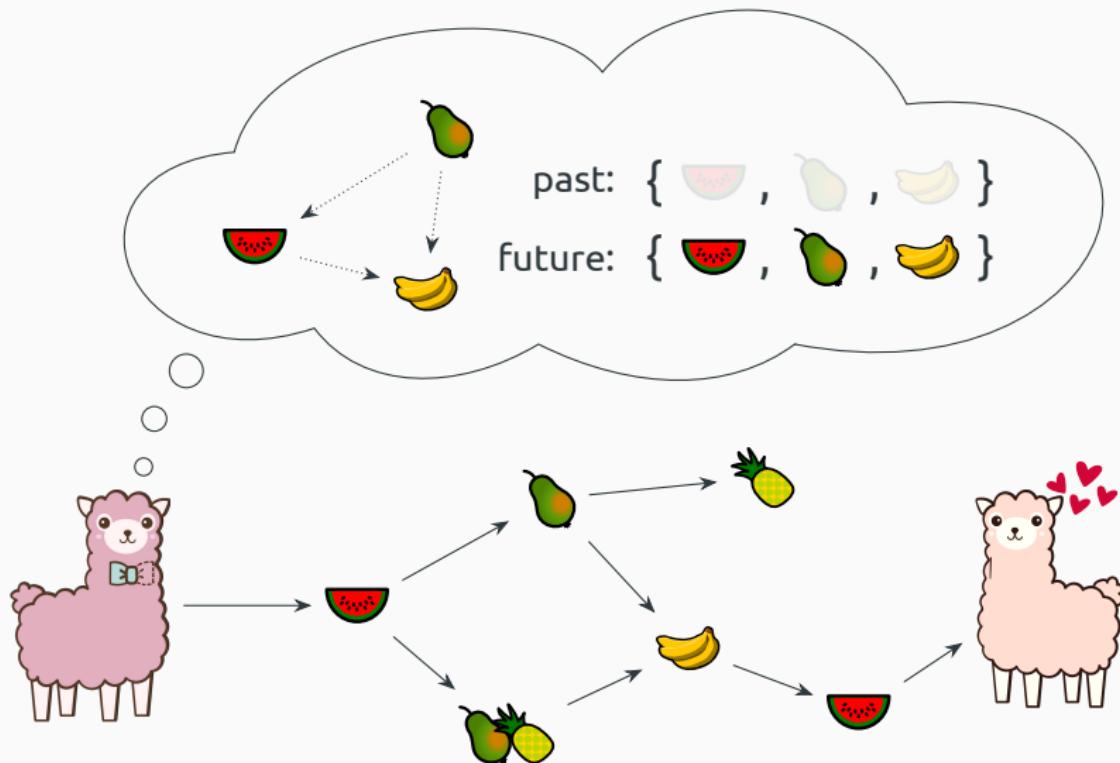
flawed landmark progression

~~ **unsound landmarks**

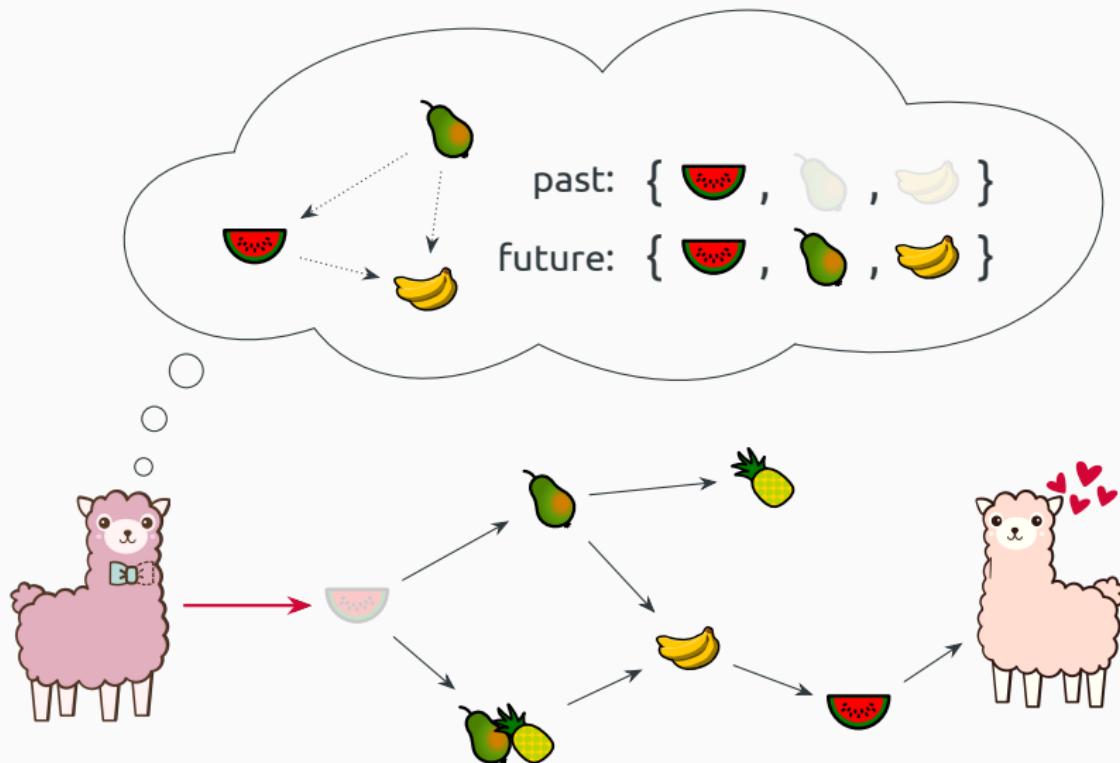
Solution

Always eat fruit and track landmarks **needed (again)** in the future.

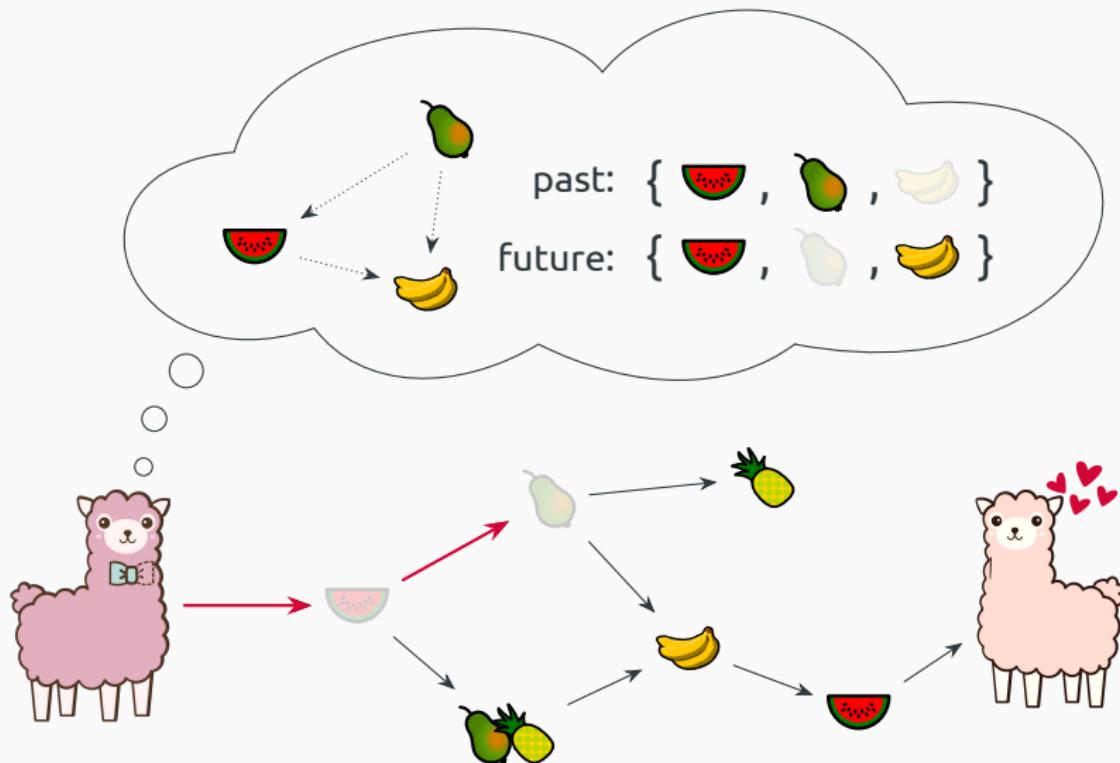
Valid Landmark Progression



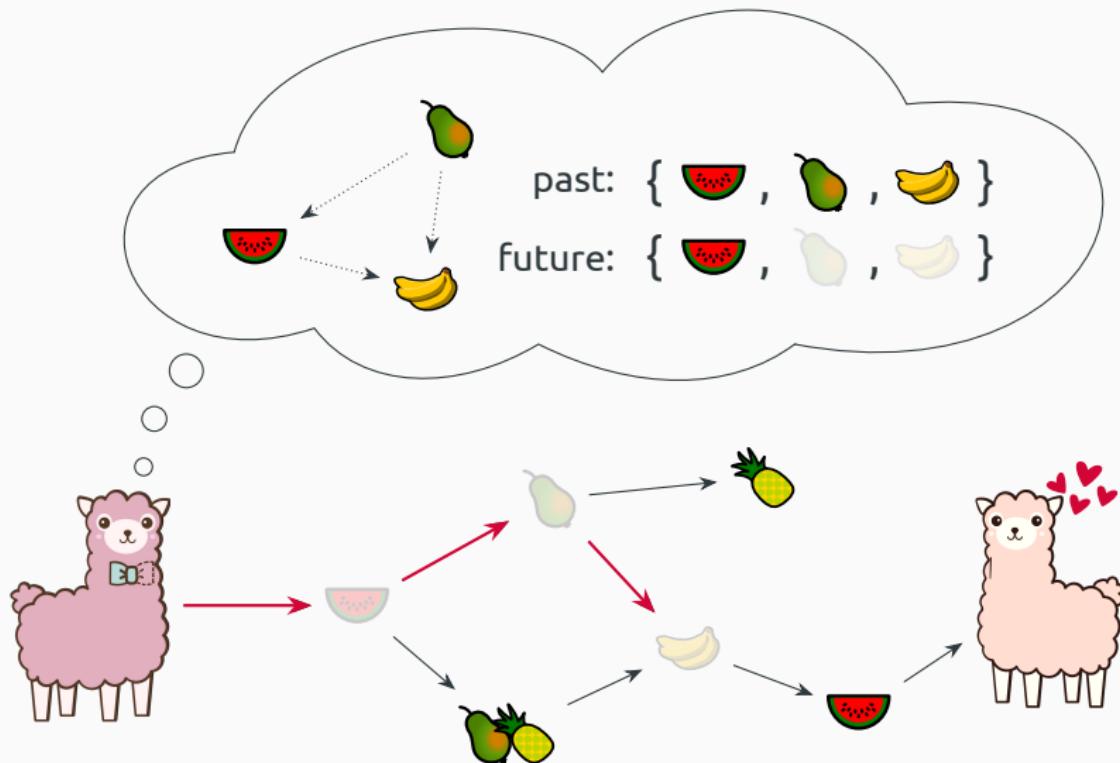
Valid Landmark Progression



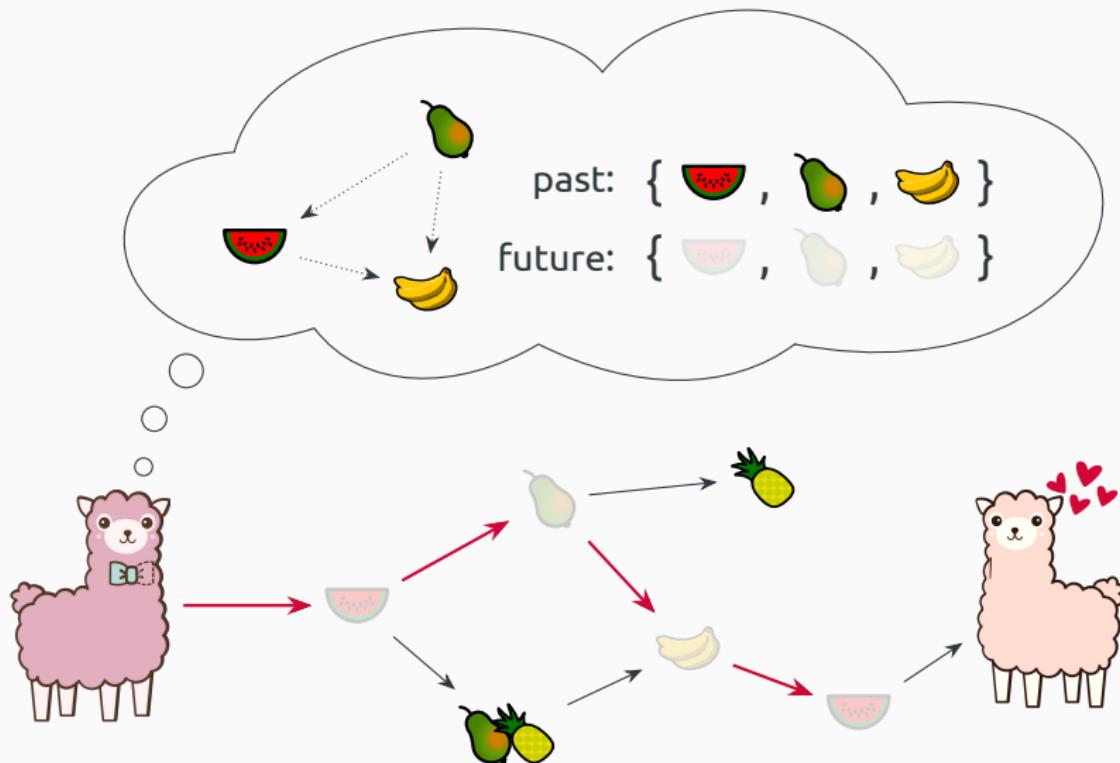
Valid Landmark Progression



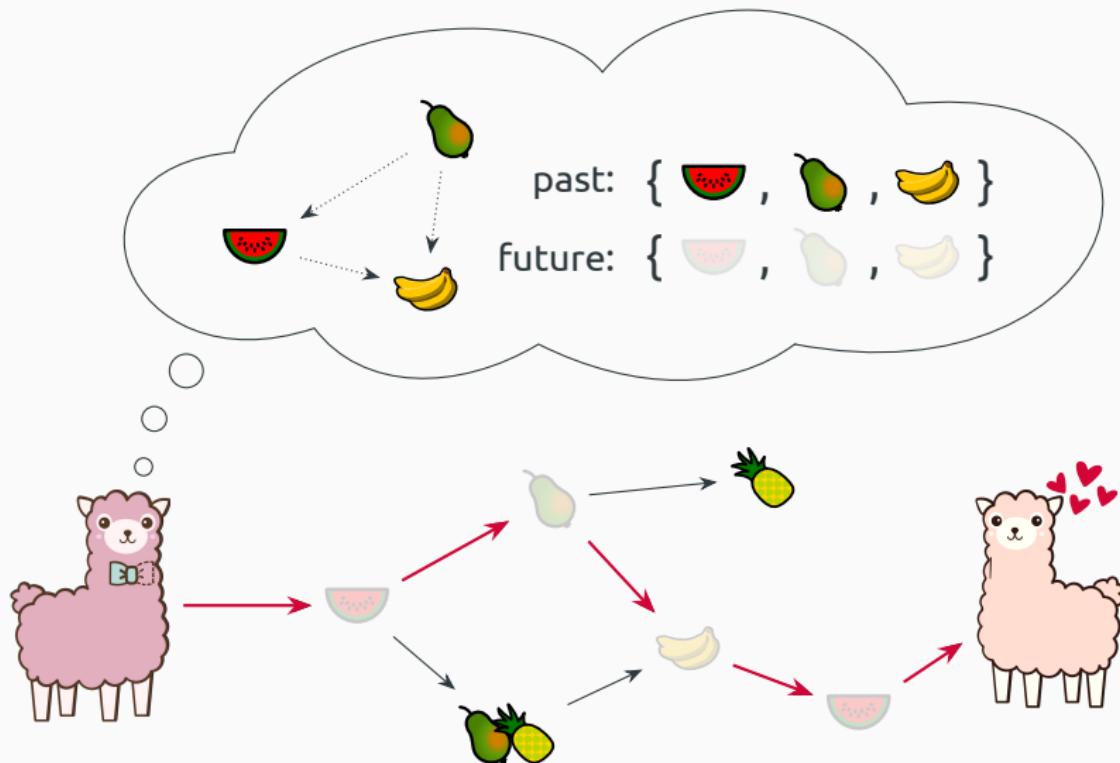
Valid Landmark Progression



Valid Landmark Progression



Valid Landmark Progression



Consequences

- increased memory-footprint
- slower to evaluate
- + information **always sound**
 - heuristic safe and more accurate.
- + **no restrictions** on landmark generation
 - cycles allowed
 - **reasonable orderings** for optimal planning

Consequences

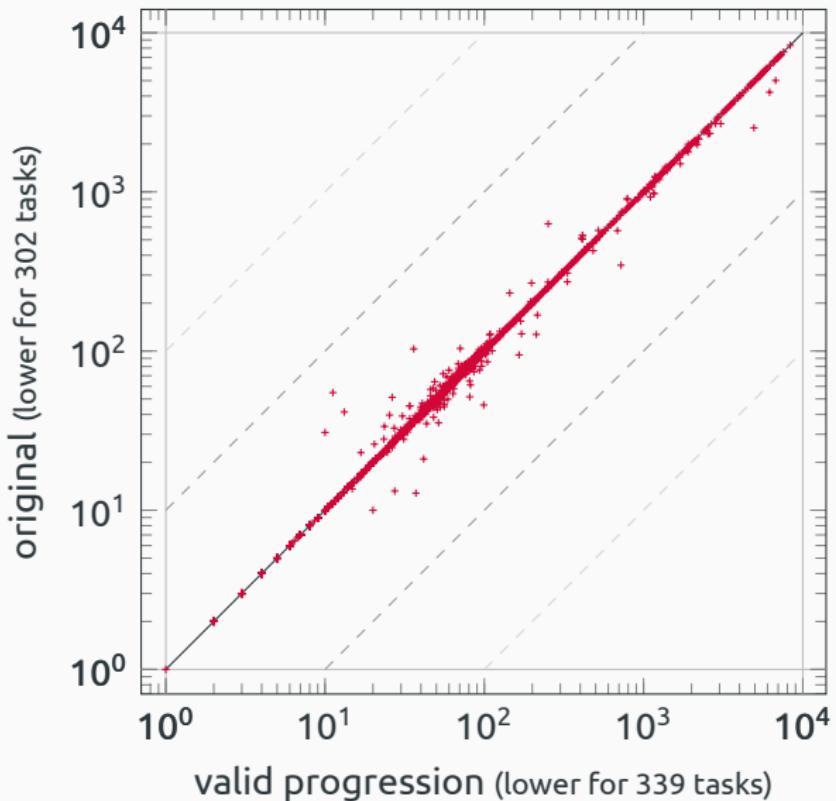
- increased memory-footprint
- slower to evaluate
- + information **always sound**
 - heuristic safe and more accurate.
- + **no restrictions** on landmark generation
 - cycles allowed
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Remark

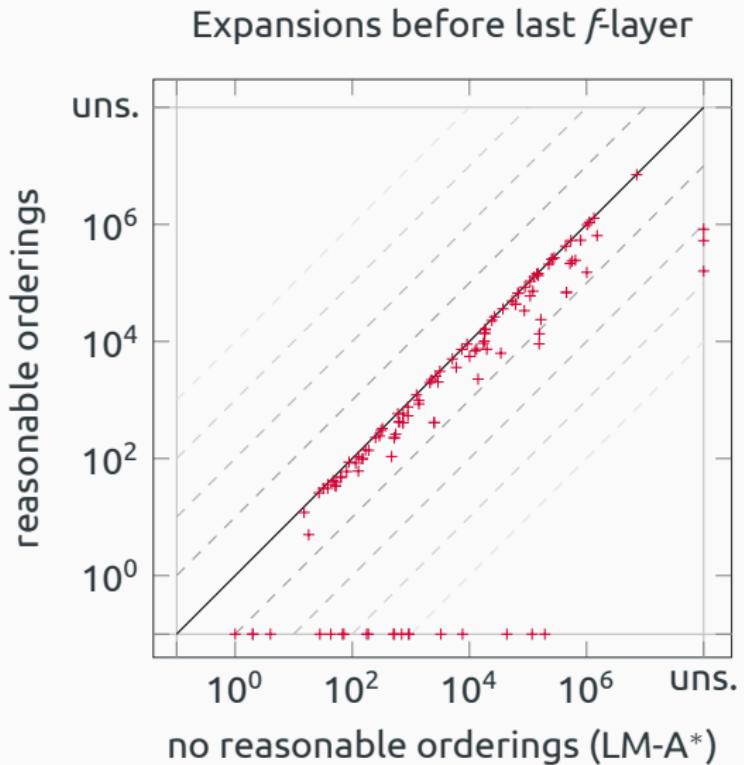
For **path-dependent** heuristics:

increased accuracy $\not\Rightarrow$ improved search behaviour

LAMA Plan Cost



Reasonable Orderings for Optimal Planning



Summary

LAMA progresses **invalid** information.

- heuristic inaccurate
- planner incomplete

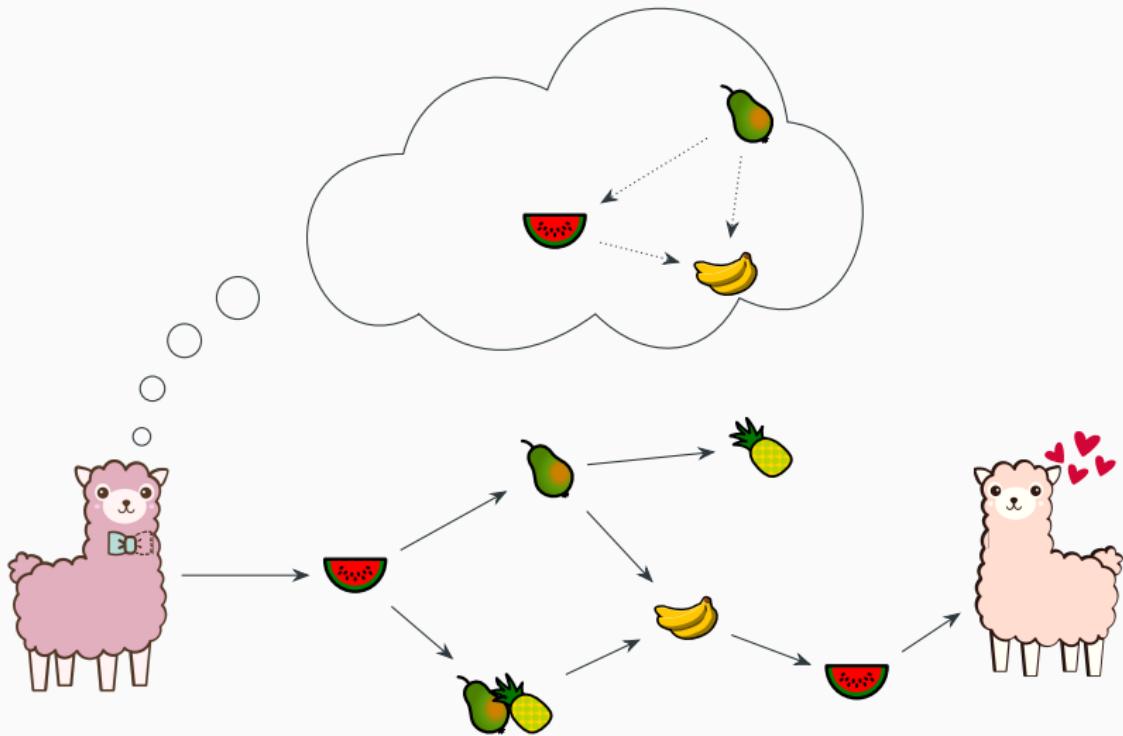
Store both **past and future** for valid landmark progression.

- information always sound

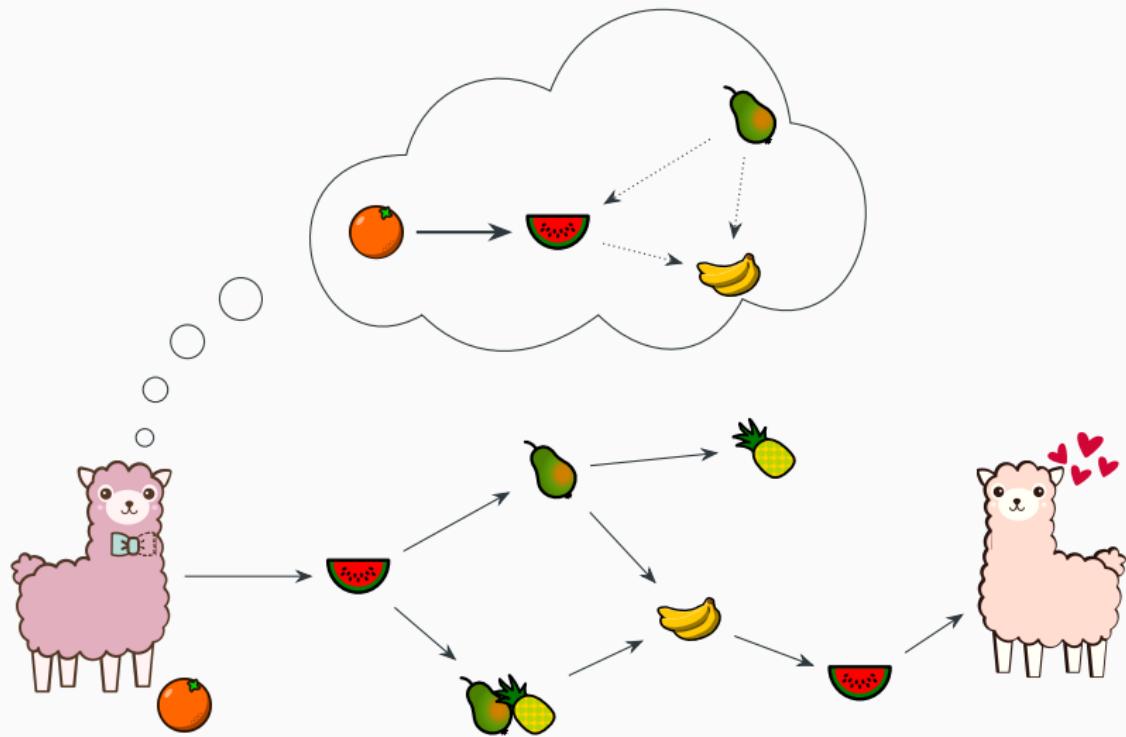
No more **restrictions** on landmark and ordering generation.

- clean framework

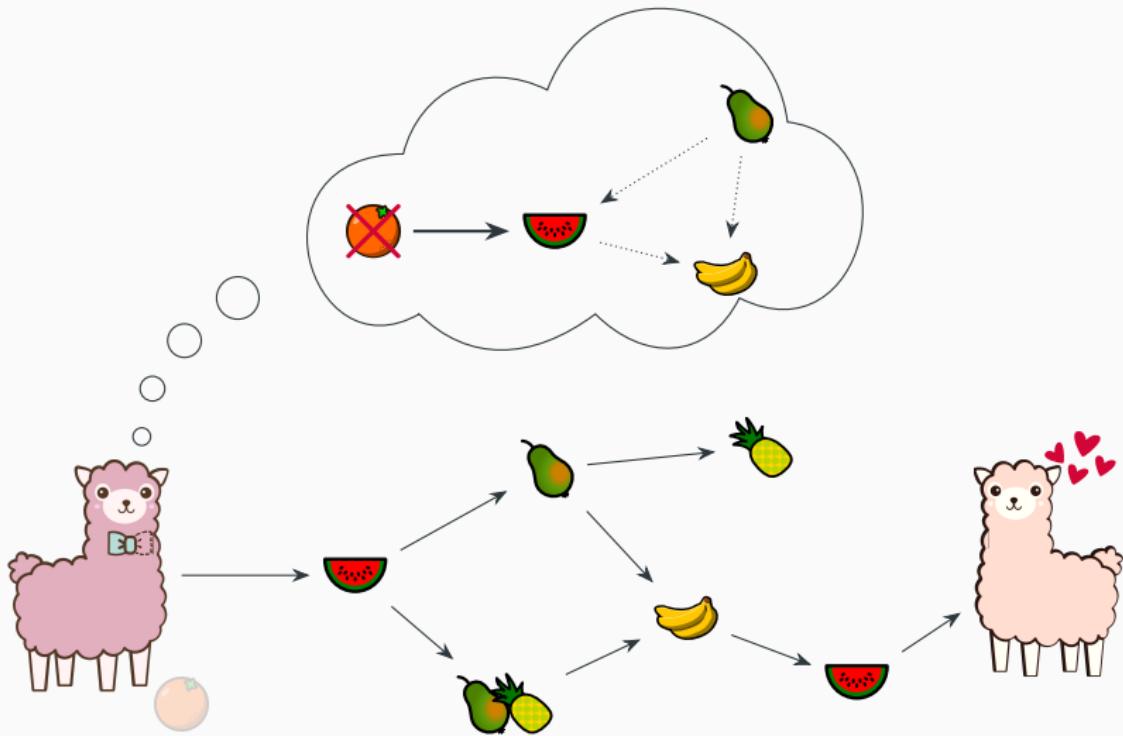
Incompleteness Example



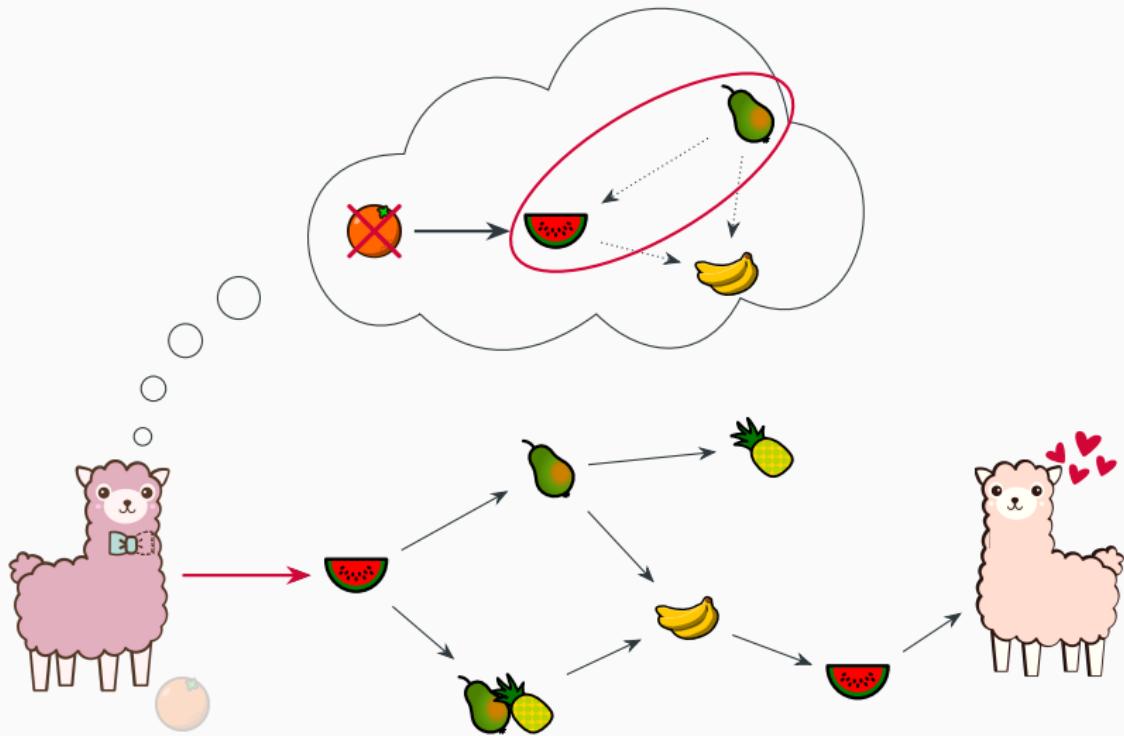
Incompleteness Example



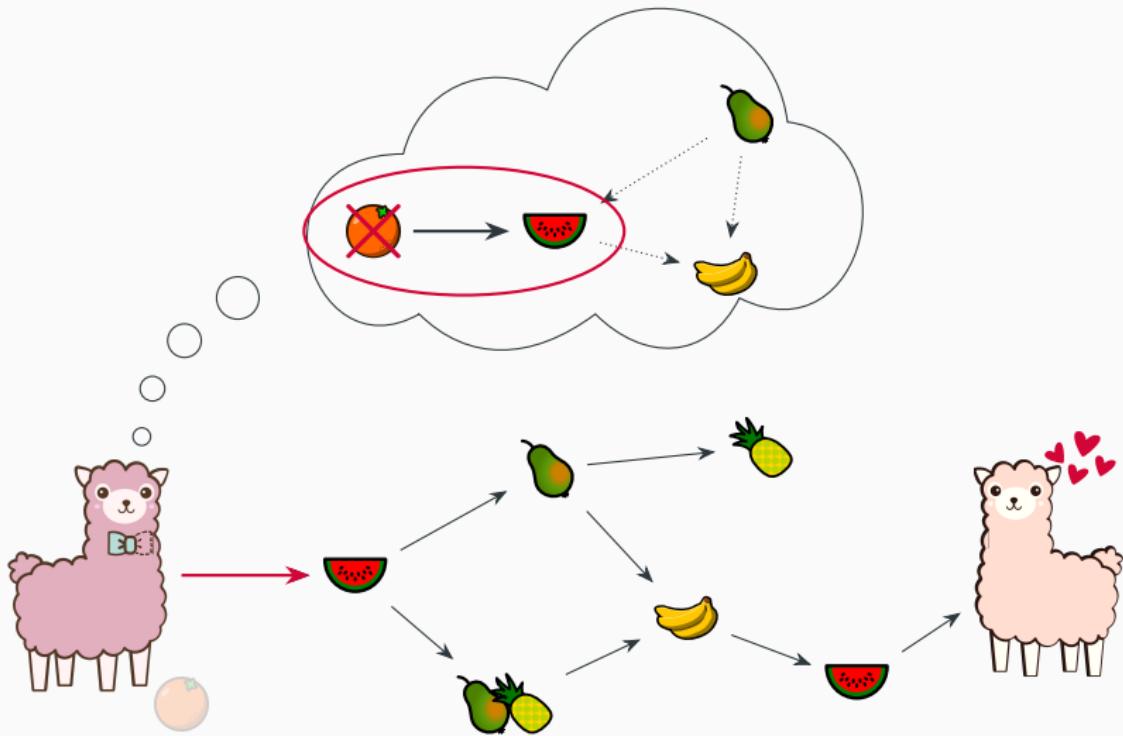
Incompleteness Example



Incompleteness Example



Incompleteness Example



Incompleteness Example

