

Certified Unsolvability in Classical Planning

1. Theoretical Foundations

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Certified Unsolvability in Classical Planning

1 / 38

Certified Unsolvability in Classical Planning

1. Theoretical Foundations

1.1 Introduction

1.2 Certifying Algorithms

1.3 Proof Systems

1.4 Unsolvability Proof System

1.5 Efficient Verification

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2 / 38

1. Theoretical Foundations

Introduction

Introduction

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3 / 38

1. Theoretical Foundations

Introduction

Goal

learn about:

- ▶ different levels of correctness guarantees
- ▶ unsolvability certificates for classical planning
- ▶ how to make your planner certifying

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4 / 38

Target Audience

- ▶ familiar with classical planning
- ▶ optional: planner developer

Certifying Algorithms

About us



Salomé



Gabi



Malte

Motivation

- ▶ ISP wants to build antenna towers for 5G.
- ▶ antenna supplier:
 - ▶ "You need **at least** x towers"
 - ▶ shows calculations with a tool, if using less than x towers tool says "unsolvable"
- ▶ ISP's options:
 - ▶ blindly trust the tool
 - ▶ demand some form of **correctness guarantee** for their tool

Levels of Verification

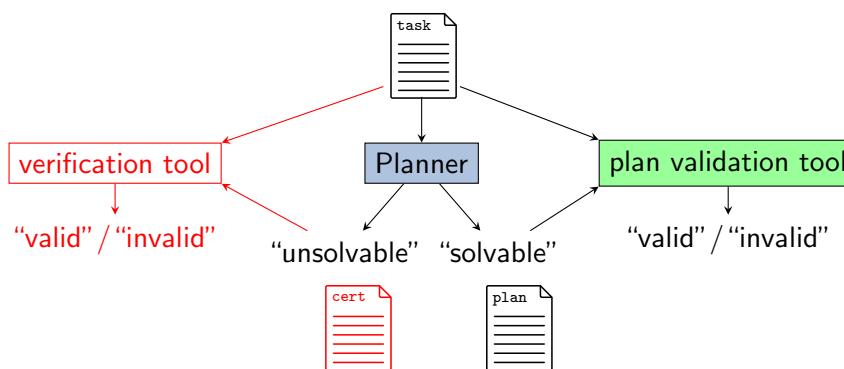
How can we verify the correctness of an algorithm?

- ① **theoretical**: correctness proof in papers
- ② **implementation**:

verification method	verified inputs
unit test	some predesignated inputs
certifying algorithms	each input when it occurs
theorem provers	all possible inputs

- ▶ Unit tests are easy to do, but it is also easy to miss bugs.
- ▶ Theorem provers are very expensive but offer highest guarantee (tiny core which is checked very carefully).
- ▶ Certifying algorithms strike a balance between trust and effort.

Certifying Algorithms in Planning



Certifying Algorithms [McConnell et al. 2011]

"A certifying algorithm is an algorithm that produces, with each output, a certificate or witness (easy-to-verify proof) that the particular output has not been compromised by a bug."

→ algorithm might still contain bug, but current output is correct

Example

Is CNF formula φ satisfiable?

- ▶ yes → provide satisfying assignment \mathcal{I}
- ▶ no → provide UNSAT certificate (resolution, DRAT proof...)

Guiding Properties

Soundness & Completeness

We can create a certificate for task Π iff Π is unsolvable.

Efficient Generation

Certificate creation incurs only polynomial overhead to the planner.

Efficient Verification

Certificate verification is at most polynomial in its size.

Generality

A wide variety of planning techniques can produce a certificate.

Quis custodiet ipsos custodes?

Certificate must be verified by a verifier. But what if the verifier has bugs?

- ▶ Verify the verifier!
- ▶ Verify the verifier-verifier!
- ▶ ...?
- ▶ At some point we need to trust something.

Good news: Verifiers are often simpler than the original algorithm.

→ [Verify the verifier with theorem provers.](#)

Example: A Formally Verified Validator for Classical Planning Problems and Solutions [Abdulaziz & Lammich, 2018]

Proof Systems

Natural Deduction

- ▶ Proof systems are built on [axioms](#) and [inference rules](#).
 - ▶ axioms: tautology ($A \vee \neg A$)
 - ▶ inference rules: conclusion based on premises (if $A \wedge B$ then A)
- ▶ [Hilbert-style systems](#) try to express as much as possible in axioms.
- ▶ [Natural deduction](#) in contrast focuses on inference rules.
 - ▶ first proposed by Gerhard Genzen [Genzen 1935]
 - ▶ should more closely reflect our natural way of reasoning

The proof system presented here uses the natural deduction style.

Inference Rules

Inference rule

An inference rule \mathbf{I} takes premises A_1, \dots, A_n and concludes B :

$$\frac{A_1 \quad \dots \quad A_n}{B} \mathbf{I}$$

- ▶ Rules use placeholder variables and are [universally true](#) for all instantiations.
- ▶ The correctness of rules can be shown in two ways:
 - ▶ within the proof system using existing rules, or
 - ▶ outside of the proof system.
- ▶ Once proven correct, we can use rules purely [syntactically](#).
- ▶ [Axioms](#) are rules with no premises.
- ▶ Rules can also use and discard [assumptions](#): For example, if under assumption A we can prove B , we have shown $A \rightarrow B$.

Example Proof System

Example

Inference Rules:

$$\frac{\star \quad \diamond}{\square} \mathbf{A} \quad \overline{\diamond} \mathbf{B} \quad \frac{\diamond}{\star} \mathbf{C} \quad \frac{\square}{\circ} \quad \frac{\star}{\circ} \quad \frac{\diamond}{\circ} \mathbf{D}$$

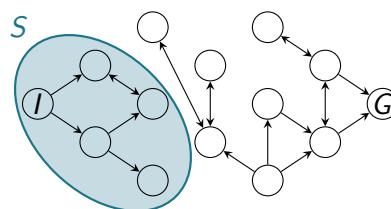
Show \circ :

#	statement	justification
(1)	\diamond	from B
(2)	\star	from C with (1)
(3)	\square	from A with (2) and (1)
(4)	\circ	from D with (3), (2) and (1)

Unsolvability Proof System

First Certificate Attempt

How can we show that a planning task is unsolvable?



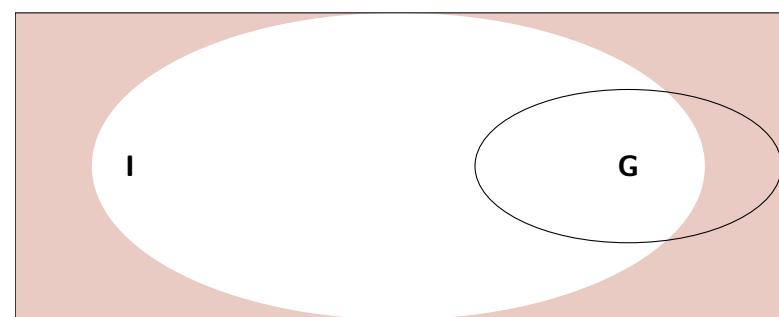
Inductive Certificate [E et al 2017]

An inductive certificate for a STRIPS planning task

$\Pi = \langle \mathbf{V}, \mathbf{A}, \mathbf{I}, \mathbf{G} \rangle$ is a set of states S with the following properties:

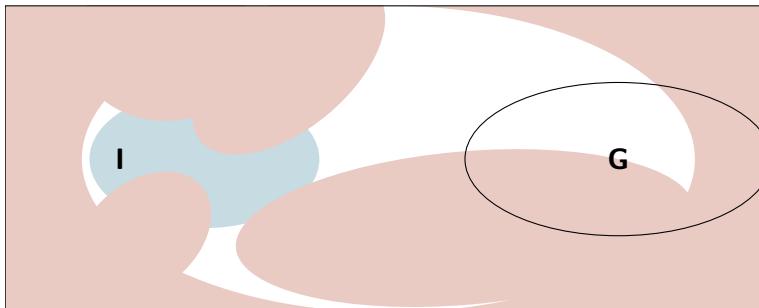
- ▶ $\mathbf{I} \in S$
- ▶ S contains no goal state
- ▶ $S[\mathbf{A}] \subseteq S$, where $S[\mathbf{A}] = \{s' \mid s[a] = s' \text{ for some } a \in \mathbf{A}\}$

How Planners Show Unsolvability



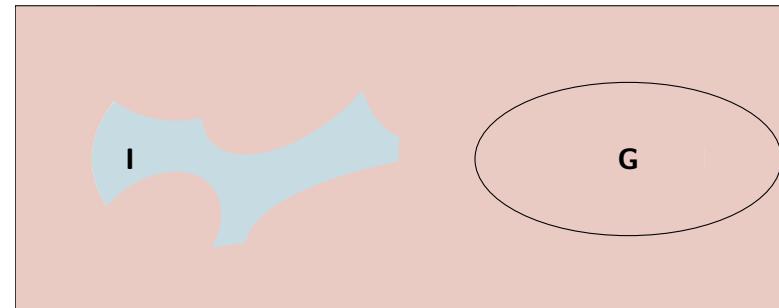
preprocessing

How Planners Show Unsolvability



heuristic search with dead-end pruning

How Planners Show Unsolvability



- ▶ Uninteresting search space areas get pruned [incrementally](#)
- ▶ Later pruning steps can use knowledge from previous ones.
- ▶ Distilling these steps into a singular argument is difficult.

→ Proof systems can capture this type of incremental reasoning.

Proof System Objects

- ▶ state sets S represented as
 - ▶ BDD
 - ▶ (dual)-Horn formula
 - ▶ 2CNF formula
 - ▶ explicit enumeration
 - ▶ ...
- ▶ action sets A represented as ID enumeration

Types of Knowledge

Dead State

A state s is dead if no plan traverses s , i.e. there is no plan $\pi = \langle a_1, \dots, a_n \rangle$ and $1 \leq i \leq n$ with $s = I[a_1] \dots [a_i]$.

→ captures idea of pruned states (in both directions)

statements in the proof system:

- ▶ S dead (all $s \in S$ dead)
- ▶ $E \sqsubseteq E'$ (where E and E' are sets of states or actions)
- ▶ unsolvable

Inference Rules - Showing Deadness

Empty set Dead

$$\frac{}{\emptyset \text{ dead}} \mathbf{ED}$$

Union Dead

$$\frac{S \text{ dead} \quad S' \text{ dead}}{S \cup S' \text{ dead}} \mathbf{UD}$$

Subset Dead

$$\frac{S' \text{ dead} \quad S \sqsubseteq S'}{S \text{ dead}} \mathbf{SD}$$

Inference Rules - Showing Unsolvability

Conclusion Initial

$$\frac{\{I\} \text{ dead}}{\text{unsolvable}} \mathbf{CI}$$

Conclusion Goal

$$\frac{S_G \text{ dead}}{\text{unsolvable}} \mathbf{CG}$$

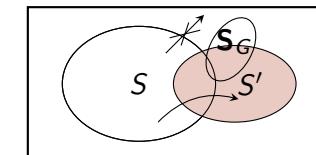
Inference Rules - Showing Deadness

$$\frac{\begin{array}{c} \mathbf{Progression} \\ \mathbf{Goal} \end{array} \quad S[\mathbf{A}] \sqsubseteq S \cup S' \quad S' \text{ dead} \quad S \cap S_G \text{ dead}}{S \text{ dead}} \mathbf{PG}$$

$$\frac{\begin{array}{c} \mathbf{Progression} \\ \mathbf{Initial} \end{array} \quad S[\mathbf{A}] \sqsubseteq S \cup S' \quad S' \text{ dead} \quad \{I\} \sqsubseteq S}{\overline{S} \text{ dead}} \mathbf{PI}$$

$$\frac{\begin{array}{c} \mathbf{Regression} \\ \mathbf{Goal} \end{array} \quad [\mathbf{A}]S \sqsubseteq S \cup S' \quad S' \text{ dead}}{\overline{S} \text{ dead}} \mathbf{RG}$$

$$\frac{\begin{array}{c} \mathbf{Regression} \\ \mathbf{Initial} \end{array} \quad [\mathbf{A}]S \sqsubseteq S \cup S' \quad S' \text{ dead} \quad \{I\} \sqsubseteq \overline{S}}{S \text{ dead}} \mathbf{RI}$$



Inference Rules - Set Theory

Union Left

$$\frac{}{E \sqsubseteq (E' \cup E)} \mathbf{UL}$$

Intersection Right

$$\frac{}{(E \cap E') \sqsubseteq E} \mathbf{IR}$$

Subset Union

$$\frac{E \sqsubseteq E'' \quad E' \sqsubseteq E''}{(E \cup E') \sqsubseteq E''} \mathbf{SU}$$

Subset Intersection

$$\frac{E \sqsubseteq E' \quad E \sqsubseteq E''}{E \sqsubseteq (E' \cap E'')} \mathbf{SI}$$

Subset Transitivity

$$\frac{E \sqsubseteq E' \quad E' \sqsubseteq E''}{E \sqsubseteq E''} \mathbf{ST}$$

...

Inference Rules - Progression and Regression

Action Union

$$\frac{S[A] \sqsubseteq S' \quad S[A'] \sqsubseteq S'}{S[A \cup A'] \sqsubseteq S'} \text{AU}$$

Progression Transitivity

$$\frac{S[A] \sqsubseteq S'' \quad S' \sqsubseteq S}{S'[A] \sqsubseteq S''} \text{PT}$$

Progression to Regression

$$\frac{S[A] \sqsubseteq S'}{[A]\bar{S}' \sqsubseteq \bar{S}} \text{PR}$$

...

Is this enough?

How can we show $S[A] \sqsubseteq S$ or similar statements?

- ▶ depends on planning task and contents of S
- ▶ requires *semantic* analysis
- ▶ set theory rules only syntactical

→ new source of information: [basic statements](#)

Basic Statements

$$\mathbf{B1} \cap L_R \subseteq \bigcup L'_R$$

$$\mathbf{B2} (\bigcap X_R)[A] \cap \bigcap L_R \subseteq \bigcup L'_R$$

$$\mathbf{B3} [A](\bigcap X_R) \cap \bigcap L_R \subseteq \bigcup L'_R$$

$$\mathbf{B4} L_R \subseteq L'_R$$

$$\mathbf{B5} A \subseteq A'$$

X_R state set variable
(represented by formalism R)

L_R state set literal
(either X_R or \bar{X}_R)

A action set

- ▶ In **B1-B3** all sets must be represented by the *same* formalism.
- ▶ Unions and intersections are *bounded*.
- ▶ We only support pro-/regression for set *variables*.
- ▶ **B4** enables us to *mix* formalisms.

Soundness and Completeness

Given a STRIPS planning tasks $\Pi = \langle \mathbf{V}, \mathbf{A}, \mathbf{I}, \mathbf{G} \rangle$, there is an proof in the proof system for Π iff Π is unsolvable.

Proof

Soundness: This follows from the correctness of the inference rules and basic statements.

Completeness: Consider \mathcal{R}^Π , the set of states reachable from \mathbf{I} .

#	statement	justification
(1)	\emptyset dead	ED
(2)	$\mathcal{R}^\Pi[A] \sqsubseteq \mathcal{R}^\Pi \cup \emptyset$	B2
(3)	$\mathcal{R}^\Pi \cap \mathbf{S}_G \sqsubseteq \emptyset$	B1
(4)	$\mathcal{R}^\Pi \cap \mathbf{S}_G$ dead	SD with (1) and (3)
(5)	\mathcal{R}^Π dead	PG with (2), (1) and (4)
(6)	$\{\mathbf{I}\} \sqsubseteq \mathcal{R}^\Pi$	B1
(7)	$\{\mathbf{I}\}$ dead	SD with (5) and (6)
(8)	unsolvable	CI with (7)

Efficient Verification

Formalisms & Operations

How can we analyze whether basic statements can be verified efficiently?

- ➊ check each formalism separately
- ➋ check what **operations** a formalism **R** must support
 - ▶ **SE** (sentential entailment): Given **R**-formulas φ and ψ , test whether $\varphi \models \psi$.
 - ▶ **\wedge BC** (bounded conjunction): Given **R**-formulas φ and ψ , construct an **R**-formula representing $\varphi \wedge \psi$.
 - ▶ **toCNF** (transform to CNF): Given **R**-formula φ , construct a CNF formula that is equivalent to φ .
 - ▶ ... [Darwiche & Marquis 2002]

Verifying Statements

The verifier needs to verify each step of the proof.

- ▶ inference rules
 - ▶ universally true
 - ▶ check if rule is applied correctly ([syntax](#))
 - easy to verify
- ▶ basic statements
 - ▶ sets must be interpreted ([semantic](#))
 - depends on set representation formalism

Efficient Verification of B1

To verify $\bigcap X_R \subseteq \bigcup X'_R$ efficiently **R** must efficiently support:

	$ \bigcap X_R = 0$	$ \bigcap X_R = 1$	$ \bigcap X_R > 1$
$ \bigcup X'_R = 0$		CO	CO, \wedgeBC toDNF
$ \bigcup X'_R = 1$	VA	SE	SE, \wedgeBC toDNF, IM
$ \bigcup X'_R > 1$	VA, \veeBC toCNF	SE, \veeBC toCNF, CE	SE, \wedgeBC, \veeBC toDNF, IM, \veeBC toCNF, CE, \wedgeBC

- ▶ multiple rows indicate different possible options
- ▶ for **B1**: move negated literals to the “correct” side

Efficient Verification of B1 - Example

	$ \cap X_R = 0$	$ \cap X_R = 1$	$ \cap X_R > 1$
$ \cup X'_R = 0$		CO	CO, \wedgeBC toDNF
$ \cup X'_R = 1$	VA	SE	SE, \wedgeBC toDNF, IM
$ \cup X'_R > 1$	VA, \veeBC toCNF	SE, \veeBC toCNF, CE	SE, \wedgeBC, \veeBC toDNF, IM, \veeBC toCNF, CE, \wedgeBC

Example

For sets S_1 to S_5 (all represented with \mathbf{R}), the statement $S_1 \cap \overline{S_2} \subseteq S_3 \cup S_4 \cup S_5$ can be verified efficiently iff \mathbf{R} supports

- ▶ **SE** (sentential entailment) and **\vee BC**(bounded disjunction), or
- ▶ **toCNF** (transform to CNF) and **CE** (clausal entailment).

Concrete Formalisms

What do BDDs, (dual-)Horn formulas, 2CNF formulas and explicit enumeration support?

- ▶ Basic statements **B1-B3** are fully supported by all formalisms.
- ▶ Basic statement **B4** between those formalisms is supported in most cases with the following exceptions:
 - ▶ $\varphi_R \models \neg\psi'_R$ where R and R' are a combination of BDD, (dual-)Horn and 2CNF
 - ▶ $\varphi_{(\text{dual-})\text{Horn}/2\text{CNF}} \models \psi_{\text{BDD}}$