Planning and Optimization

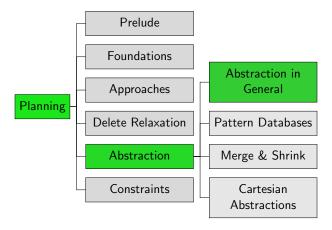
E5. Abstractions: Additive Abstractions

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Content of the Course



Additivity
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Orthogonality of Abstractions

Definition (Orthogonal)

Let α_1 and α_2 be abstractions of transition system \mathcal{T} .

We say that α_1 and α_2 are orthogonal if for all transitions $s \xrightarrow{\ell} t$ of \mathcal{T} , we have $\alpha_1(s) = \alpha_1(t)$ or $\alpha_2(s) = \alpha_2(t)$.

Affecting Transition Labels

Definition (Affecting Transition Labels)

Let \mathcal{T} be a transition system, and let ℓ be one of its labels.

We say that ℓ affects \mathcal{T} if \mathcal{T} has a transition $s \stackrel{\ell}{\to} t$ with $s \neq t$.

Theorem (Affecting Labels vs. Orthogonality)

Let α_1 and α_2 be abstractions of transition system \mathcal{T} . If no label of \mathcal{T} affects both \mathcal{T}^{α_1} and \mathcal{T}^{α_2} , then α_1 and α_2 are orthogonal.

(Easy proof omitted.)

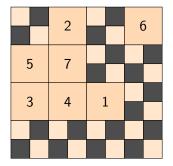
Orthogonal Abstractions: Example

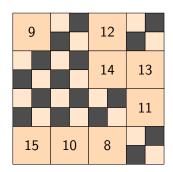
	2		6
5	7		
3	4	1	

9		12	
		14	13
			11
15	10	8	

Are the abstractions orthogonal?

Orthogonal Abstractions: Example





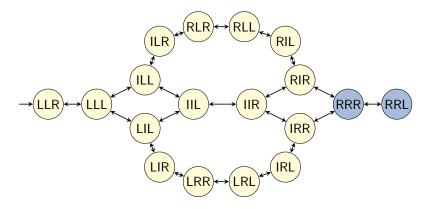
Are the abstractions orthogonal?

Orthogonality and Additivity

Theorem (Additivity for Orthogonal Abstractions)

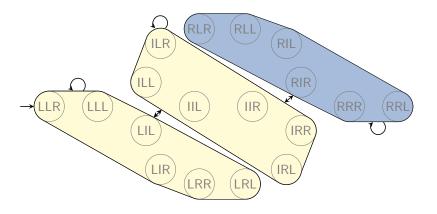
Let $h^{\alpha_1}, \ldots, h^{\alpha_n}$ be abstraction heuristics of the same transition system such that α_i and α_j are orthogonal for all $i \neq j$.

Then $\sum_{i=1}^{n} h^{\alpha_i}$ is a safe, goal-aware, admissible and consistent heuristic for Π .

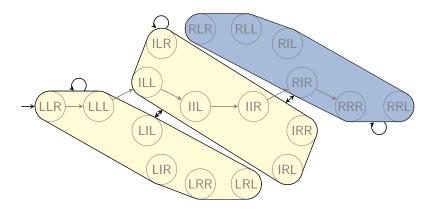


transition system ${\mathcal T}$

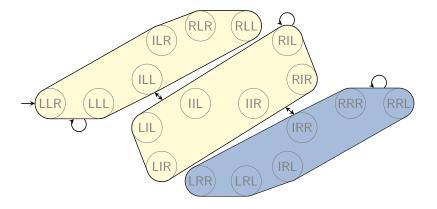
state variables: first package, second package, truck



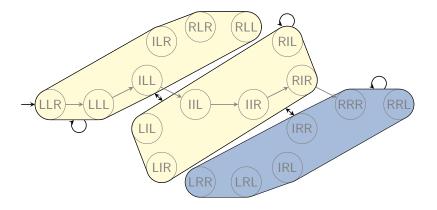
abstraction α_1 abstraction: only consider value of first package



abstraction α_1 abstraction: only consider value of first package



abstraction α_2 (orthogonal to α_1) abstraction: only consider value of second package



abstraction α_2 (orthogonal to α_1) abstraction: only consider value of second package

Proof.

We prove goal-awareness and consistency; the other properties follow from these two.

Let $\mathcal{T} = \langle S, L, c, T, s_0, S_\star \rangle$ be the concrete transition system.

Let
$$h = \sum_{i=1}^{n} h^{\alpha_i}$$
.

Proof.

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Let $\mathcal{T} = \langle S, L, c, T, s_0, S_\star \rangle$ be the concrete transition system.

Let
$$h = \sum_{i=1}^{n} h^{\alpha_i}$$
.

Goal-awareness: For goal states $s \in S_{\star}$,

$$h(s) = \sum_{i=1}^{n} h^{\alpha_i}(s) = \sum_{i=1}^{n} 0 = 0$$
 because all individual abstraction heuristics are goal-aware.

Proof (continued).

Consistency: Let $s \xrightarrow{o} t \in T$. We must prove $h(s) \leq c(o) + h(t)$.

Proof (continued).

Consistency: Let $s \stackrel{o}{\to} t \in T$. We must prove $h(s) \le c(o) + h(t)$.

Because the abstractions are orthogonal, $\alpha_i(s) \neq \alpha_i(t)$

for at most one $i \in \{1, \dots, n\}$.

Proof (continued).

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Case 1: $\alpha_i(s) = \alpha_i(t)$ for all $i \in \{1, ..., n\}$.

Proof (continued).

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Case 1:
$$\alpha_i(s) = \alpha_i(t)$$
 for all $i \in \{1, \ldots, n\}$.

Then
$$h(s) = \sum_{i=1}^{n} h^{\alpha_i}(s)$$

 $= \sum_{i=1}^{n} h^*_{\mathcal{T}^{\alpha_i}}(\alpha_i(s))$
 $= \sum_{i=1}^{n} h^*_{\mathcal{T}^{\alpha_i}}(\alpha_i(t))$
 $= \sum_{i=1}^{n} h^{\alpha_i}(t)$
 $= h(t) < c(o) + h(t).$

. .

Proof (continued).

Case 2: $\alpha_i(s) \neq \alpha_i(t)$ for exactly one $i \in \{1, ..., n\}$.

Let $k \in \{1, ..., n\}$ such that $\alpha_k(s) \neq \alpha_k(t)$.

Proof (continued).

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Case 2: \alpha_i(s) \neq \alpha_i(t) for exactly one i \in \{1, ..., n\}.
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Let $k \in \{1, \ldots, n\}$ such that $\alpha_k(s) \neq \alpha_k(t)$.

Then
$$h(s) = \sum_{i=1}^{n} h^{\alpha_i}(s)$$

 $= \sum_{i \in \{1,...,n\} \setminus \{k\}} h^*_{\mathcal{T}^{\alpha_i}}(\alpha_i(s)) + h^{\alpha_k}(s)$
 $\leq \sum_{i \in \{1,...,n\} \setminus \{k\}} h^*_{\mathcal{T}^{\alpha_i}}(\alpha_i(t)) + c(o) + h^{\alpha_k}(t)$
 $= c(o) + \sum_{i=1}^{n} h^{\alpha_i}(t)$
 $= c(o) + h(t)$,

where the inequality holds because $\alpha_i(s) = \alpha_i(t)$ for all $i \neq k$ and h^{α_k} is consistent.

Outlook

Using Abstraction Heuristics in Practice

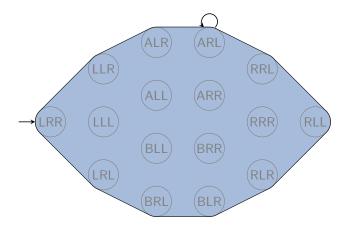
In practice, there are conflicting goals for abstractions:

- we want to obtain an informative heuristic, but
- want to keep its representation small.

Abstractions have small representations if

- there are few abstract states and
- there is a succinct encoding for α .

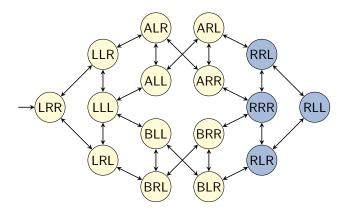
Counterexample: One-State Abstraction



One-state abstraction: $\alpha(s) := \text{const.}$

- + very few abstract states and succinct encoding for lpha
- completely uninformative heuristic

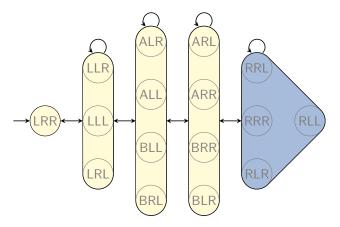
Counterexample: Identity Abstraction



Identity abstraction: $\alpha(s) := s$.

- + perfect heuristic and succinct encoding for lpha
- too many abstract states

Counterexample: Perfect Abstraction



Perfect abstraction: $\alpha(s) := h^*(s)$.

- + perfect heuristic and usually few abstract states
- usually no succinct encoding for α

Automatically Deriving Good Abstraction Heuristics

Abstraction Heuristics for Planning: Main Research Problem

Automatically derive effective abstraction heuristics for planning tasks.

we will study three state-of-the-art approaches in the following chapters

Summary

Summary

Summary

- Abstraction heuristics from orthogonal abstractions can be added without losing admissibility or consistency.
- One sufficient condition for orthogonality is that all abstractions are affected by disjoint sets of labels.
- Practically useful abstractions are those which give informative heuristics, yet have a small representation.
- Coming up with good abstractions automatically is the main research challenge when applying abstraction heuristics in planning.