# Planning and Optimization

E11. Merge-and-Shrink: Properties and Shrink Strategies

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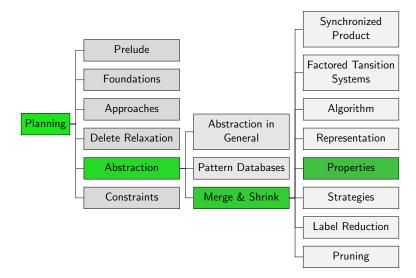
## Reminder: Generic Algorithm Template

## Generic Merge & Shrink Algorithm for planning task Π

```
F := F(\Pi)
while |F| > 1:
          select type \in \{merge, shrink\}
          if type = merge:
                     select \mathcal{T}_1, \mathcal{T}_2 \in F
                     F := (F \setminus \{\mathcal{T}_1, \mathcal{T}_2\}) \cup \{\mathcal{T}_1 \otimes \mathcal{T}_2\}
          if type = shrink:
                     select \mathcal{T} \in \mathcal{F}
                     choose an abstraction mapping \beta on \mathcal{T}
                     F := (F \setminus \{\mathcal{T}\}) \cup \{\mathcal{T}^{\beta}\}
return the remaining factor \mathcal{T}^{\alpha} in F
```

# Heuristic Properties

#### Content of the Course



## Properties of Merge-and-Shrink Heuristics

To understand merge-and-shrink abstractions better, we are interested in the properties of the resulting heuristic:

- Is it admissible  $(h^{\alpha}(s) \leq h^*(s))$  for all states s?
- Is it consistent  $(h^{\alpha}(s) \le c(o) + h^{\alpha}(t)$  for all trans.  $s \xrightarrow{o} t)$ ?
- Is it perfect  $(h^{\alpha}(s) = h^*(s))$  for all states s?

Because merge-and-shrink is a generic procedure, the answers may depend on how exactly we instantiate it:

- size limits
- merge strategy
- shrink strategy

## Merge-and-Shrink as Sequence of Transformations

- $lue{}$  Consider a run of the merge-and-shrink construction algorithm with n iterations of the main loop.
- Let  $F_i$  (0 ≤ i ≤ n) be the FTS F after i loop iterations.
- Let  $\mathcal{T}_i$  ( $0 \le i \le n$ ) be the transition system represented by  $F_i$ , i.e.,  $\mathcal{T}_i = \bigotimes F_i$ .
- In particular,  $F_0 = F(\Pi)$  and  $F_n = \{\mathcal{T}_n\}$ .
- For SAS<sup>+</sup> tasks  $\Pi$ , we also know  $\mathcal{T}_0 = \mathcal{T}(\Pi)$ .

For a formal study, it is useful to view merge-and-shrink construction as a sequence of transformations from  $\mathcal{T}_i$  to  $\mathcal{T}_{i+1}$ .

(We do it in a bit more general fashion than necessary for merge and shrink steps only, to also cover some improvements we will see later.)

#### **Transformations**

#### Definition (Transformation)

Let  $\mathcal{T} = \langle S, L, c, T, s_0, S_{\star} \rangle$  and  $\mathcal{T}' = \langle S', L', c', T', s'_0, S'_{\star} \rangle$  be transition systems.

Let  $\sigma: S \to S'$  map the states of  $\mathcal{T}$  to the states of  $\mathcal{T}'$  and  $\lambda: L \to L'$  map the labels of  $\mathcal{T}$  to the labels of  $\mathcal{T}'$ .

The tuple  $\tau = \langle \mathcal{T}, \sigma, \lambda, \mathcal{T}' \rangle$  is called a transformation from  $\mathcal{T}$  to  $\mathcal{T}'$ . We also write it as  $\mathcal{T} \xrightarrow{\sigma, \lambda} \mathcal{T}'$ .

The transformation  $\tau$  induces the heuristic  $h^{\tau}$  for  $\mathcal{T}$  defined as  $h^{\tau}(s) = h^*_{\mathcal{T}'}(\sigma(s))$ .

Example: If  $\alpha$  is an abstraction mapping for transition system  $\mathcal{T}$ , then  $\mathcal{T} \xrightarrow{\alpha, \mathrm{id}} \mathcal{T}^{\alpha}$  is a transformation.

#### Conservative Transformations

### Definition (Conservative Transformation)

Let  $\mathcal{T}$  and  $\mathcal{T}'$  be transition systems with label sets L and L' and cost functions c and c', respectively.

A transformation  $\langle \mathcal{T}, \sigma, \lambda, \mathcal{T}' \rangle$  is conservative if

- $c'(\lambda(\ell)) \le c(\ell)$  for all  $\ell \in L$ ,
- for all transitions  $\langle s, \ell, t \rangle$  of  $\mathcal{T}$  there is a transition  $\langle \sigma(s), \lambda(\ell), \sigma(t) \rangle$  of  $\mathcal{T}'$ , and
- for all goal states s of  $\mathcal{T}$ , state  $\sigma(s)$  is a goal state of  $\mathcal{T}'$ .

Example: If  $\alpha$  is an abstraction mapping for transition system  $\mathcal{T}$ , then  $\mathcal{T} \xrightarrow{\alpha, \mathrm{id}} \mathcal{T}^{\alpha}$  is a conservative transformation.

# Conservative Transformations: Heuristic Properties (1)

#### Theorem

If  $\tau$  is a conservative transformation from transition system  $\mathcal{T}$  to transition system  $\mathcal{T}'$  then  $h^{\tau}$  is a safe, consistent, goal-aware and admissible heuristic for  $\mathcal{T}$ .

#### Proof.

We prove goal-awareness and consistency, the other properties follow from these two.

Goal-awareness: For all goal states  $s_{\star}$  of  $\mathcal{T}$ , state  $\sigma(s_{\star})$  is a goal state of  $\mathcal{T}'$  and therefore  $h^{\tau}(s_{\star}) = h^{\tau}_{\mathcal{T}'}(\sigma(s_{\star})) = 0$ .

# Conservative Transformations: Heuristic Properties (2)

## Proof (continued).

Consistency: Let c and c' be the label cost functions of  $\mathcal{T}$  and  $\mathcal{T}'$ , respectively. Consider state s of  $\mathcal{T}$  and transition  $\langle s, \ell, t \rangle$ . As  $\mathcal{T}'$  has a transition  $\langle \sigma(s), \lambda(\ell), \sigma(t) \rangle$ , it holds that

$$egin{aligned} h^{ au}(s) &= h^*_{\mathcal{T}'}(\sigma(s)) \ &\leq c'(\lambda(\ell)) + h^*_{\mathcal{T}'}(\sigma(t)) \ &= c'(\lambda(\ell)) + h^{ au}(t) \ &\leq c(\ell) + h^{ au}(t) \end{aligned}$$

The second inequality holds due to the requirement on the label costs.

#### **Exact Transformations**

#### Definition (Exact Transformation)

Let  $\mathcal{T}$  and  $\mathcal{T}'$  be transition systems with label sets L and L' and cost functions c and c', respectively.

A transformation  $\langle \mathcal{T}, \sigma, \lambda, \mathcal{T}' \rangle$  is exact if it is conservative and

- if  $\langle s', \ell', t' \rangle$  is a transition of  $\mathcal{T}'$  then for all  $s \in \sigma^{-1}(s')$  there is a transition  $\langle s, \ell, t \rangle$  of  $\mathcal{T}$  with  $t \in \sigma^{-1}(t')$  and  $\ell \in \lambda^{-1}(\ell')$ ,
- ② if s' is a goal state of  $\mathcal{T}'$  then all states  $s \in \sigma^{-1}(s')$  are goal states of  $\mathcal{T}$ , and
- **3**  $c(\ell) = c'(\lambda(\ell))$  for all  $\ell \in L$ .

→ no "new" transitions and goal states, no cheaper labels

## Heuristic Properties with Exact Transformations (1)

#### $\mathsf{Theorem}$

If  $\tau$  is an exact transformation from transition system  $\mathcal{T}$  to transition system  $\mathcal{T}'$  then  $\mathbf{h}^{\tau}$  is the perfect heuristic  $\mathbf{h}^*$  for  $\mathcal{T}$ .

#### Proof.

As the transformation is conservative,  $h^{\tau}$  is admissible for  $\mathcal{T}$  and therefore  $h_{\mathcal{T}}^*(s) \geq h^{\tau}(s)$ .

For the other direction, we show that for every state s' of  $\mathcal{T}'$  and goal path  $\pi'$  for s', there is for each  $s \in \sigma^{-1}(s')$  a goal path in  $\mathcal{T}$  that has the same cost.

## Heuristic Properties with Exact Transformations (2)

## Proof (continued).

Proof via induction over the length of  $\pi'$ .

 $|\pi'| = 0$ : If s' is a goal state of  $\mathcal{T}'$  then each  $s \in \sigma^{-1}(s')$  is a goal state of  $\mathcal{T}$  and the empty path is a goal path for s in  $\mathcal{T}$ .

 $|\pi'|=i+1\text{: Let }\pi'=\langle s',\ell',t'\rangle\pi'_{t'}\text{, where }\pi'_{t'}\text{ is a goal path of length }i\text{ from }t'\text{. Then there is for each }t\in\sigma^{-1}(t')\text{ a goal path }\pi_t$  of the same cost in  $\mathcal T$  (by ind. hypothesis). Furthermore, for all  $s\in\sigma^{-1}(s')$  there is a state  $t\in\sigma^{-1}(t')$  and a label  $\ell\in\lambda^{-1}(\ell')$  such that  $\mathcal T$  has a transition  $\langle s,\ell,t\rangle$ . The path  $\pi=\langle s,\ell,t\rangle\pi_t$  is a solution for s in  $\mathcal T$ . As  $\ell$  and  $\ell'$  must have the same cost and  $\pi_t$  and  $\pi'_{t'}$  have the same cost,  $\pi$  has the same cost as  $\pi'$ .

## Composing Transformations

Merge-and-shrink performs many transformations in sequence. We can formalize this with a notion of composition:

- Given  $\tau = \mathcal{T} \xrightarrow{\sigma, \lambda} \mathcal{T}'$  and  $\tau' = \mathcal{T}' \xrightarrow{\sigma', \lambda'} \mathcal{T}''$ , their composition  $\tau'' = \tau' \circ \tau$  is defined as  $\tau'' = \mathcal{T} \xrightarrow{\sigma' \circ \sigma, \lambda' \circ \lambda} \mathcal{T}''$ .
- If  $\tau$  and  $\tau'$  are conservative, then  $\tau' \circ \tau$  is conservative.
- If  $\tau$  and  $\tau'$  are exact, then  $\tau' \circ \tau$  is exact.

## Merge-and-Shrink Transformations

### F: factored transition system

#### Replacement with Synchronized Product is Conservative and Exact

Let  $\mathcal{T}_1, \mathcal{T}_2 \in F$  with  $\mathcal{T}_1 \neq \mathcal{T}_2$ .

Let  $F' := (X \setminus \{\mathcal{T}_1, \mathcal{T}_2\}) \cup \{\mathcal{T}_1 \otimes \mathcal{T}_2\}.$ 

Then there is an exact transformation  $\langle \otimes F, \sigma, id, \otimes F' \rangle$ .

Up to the isomorphism we know from the synchronized product, we can use  $\sigma = id$ .

#### Abstraction is Conservative

Let  $\alpha$  be an abstraction of  $\mathcal{T}_i \in F$  and let  $F' := (F \setminus \{\mathcal{T}_i\}) \cup \{\mathcal{T}_i^{\alpha}\}$ . The transformation  $\langle \otimes F, \sigma, \mathrm{id}, \otimes F' \rangle$  with  $\sigma(\langle s_1, \ldots, s_n \rangle) = \langle s_1, \ldots, s_{i-1}, \alpha(s_i), s_{i+1}, \ldots, s_n \rangle$  is conservative.

(Proofs omitted.)

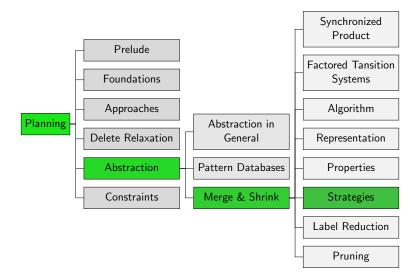
## Properties of Merge-and-Shrink Heuristics

We can conclude the following properties of merge-and-shrink heuristics for SAS<sup>+</sup> tasks:

- The heuristic is always admissible and consistent (because it is induced by a a composition of conservative transformations).
- If all shrink transformation used are exact, the heuristic is perfect (because it is induced by a composition of exact transformations).

# Shrink Strategies

#### Content of the Course



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```
F := F(\Pi)
while |F| > 1:
          select type \in \{merge, shrink\}
          if type = merge:
                     select \mathcal{T}_1, \mathcal{T}_2 \in F
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          if type = shrink:
                     select \mathcal{T} \in \mathcal{F}
                     choose an abstraction mapping \beta on \mathcal{T}
                     F := (F \setminus \{\mathcal{T}\}) \cup \{\mathcal{T}^{\beta}\}
return the remaining factor \mathcal{T}^{\alpha} in F
```

### Remaining Questions:

- Which abstractions to select for merging? 

  merge strategy
- How to shrink an abstraction? ~> shrink strategy

# Shrink Strategies

#### How to shrink an abstraction?

We cover two common approaches:

- *f*-preserving shrinking
- bisimulation-based shrinking

## *f*-preserving Shrink Strategy

## *f*-preserving Shrink Strategy

Repeatedly combine abstract states with identical abstract goal distances (*h* values) and identical abstract initial state distances (*g* values).

Rationale: preserves heuristic value and overall graph shape

#### Tie-breaking Criterion

Prefer combining states where g + h is high. In case of ties, combine states where h is high.

Rationale: states with high g + h values are less likely to be explored by  $A^*$ , so inaccuracies there matter less

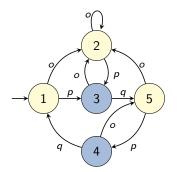
#### Bisimulation

#### Definition (Bisimulation)

Let  $\mathcal{T}=\langle S,L,c,\mathcal{T},s_0,S_\star\rangle$  be a transition system. An equivalence relation  $\sim$  on S is a bisimulation for  $\mathcal{T}$  if for every  $\langle s,\ell,s'\rangle\in\mathcal{T}$  and every  $t\sim s$  there is a transition  $\langle t,\ell,t'\rangle\in\mathcal{T}$  with  $t'\sim s'$ .

A bisimulation  $\sim$  is goal-respecting if  $s \sim t$  implies that either  $s, t \in S_{\star}$  or  $s, t \notin S_{\star}$ .

# Bisimulation: Example



 $\sim$  with equivalence classes  $\{\{1,2,5\},\{3,4\}\}$  is a goal-respecting bisimulation.

### Bisimulation Abstractions

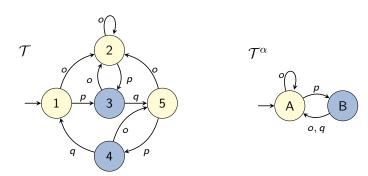
#### Definition (Abstractions as Bisimulation)

Let  $\mathcal{T} = \langle S, L, c, T, s_0, S_{\star} \rangle$  be a transition system and  $\alpha : S \to S'$  be an abstraction of  $\mathcal{T}$ . The abstraction induces the equivalence relation  $\sim_{\alpha}$  as  $s \sim_{\alpha} t$  iff  $\alpha(s) = \alpha(t)$ .

We say that  $\alpha$  is a (goal-respecting) bisimulation for  $\mathcal{T}$  if  $\sim_{\alpha}$  is a (goal-respecting) bisimulation for  $\mathcal{T}$ .

## Abstraction as Bisimulations: Example

Abstraction  $\alpha$  with  $\alpha(1) = \alpha(2) = \alpha(5) = A$  and  $\alpha(3) = \alpha(4) = B$  is a goal-respecting bisimulation for  $\mathcal{T}$ .



## Goal-respecting Bisimulations are Exact

#### $\mathsf{Theorem}$

Let F be a factored transition system and  $\alpha$  be an abstraction of  $\mathcal{T}_i \in F$ .

If  $\alpha$  is a goal-respecting bisimulation then the transformation  $\langle \otimes F, \sigma, id, \otimes F' \rangle$  with

- $\sigma(\langle s_1,\ldots,s_n\rangle)=\langle s_1,\ldots,s_{i-1},\alpha(s_i),s_{i+1},\ldots,s_n\rangle$  and
- $F' := (F \setminus \{\mathcal{T}_i\}) \cup \{\mathcal{T}_i^{\alpha}\}$

is exact.

(Proofs omitted.)

Shrinking with bisimulation preserves the heuristic estimates.

## Bisimulations: Discussion

- As all bisimulations preserve all relevant information, we are interested in the coarsest such abstraction (to shrink as much as possible).
- There is always a unique coarsest bisimulation for  $\mathcal{T}$  and it can be computed efficiently (from the explicit representation).
- In some cases, computing the bisimulation is still too expensive or it cannot sufficiently shrink a transition system.

# Summary

## Summary

- Merge-and-shrink abstractions can be analyzed by viewing them as a sequence of transformations.
- We only use conservative transformations, and hence merge-and-shrink heuristics for SAS<sup>+</sup> tasks are admissible and consistent.
- Merge-and-shrink heuristics for SAS<sup>+</sup> tasks that only use exact transformations are perfect.
- Bisimulation is an exact shrinking method.