

Planning and Optimization

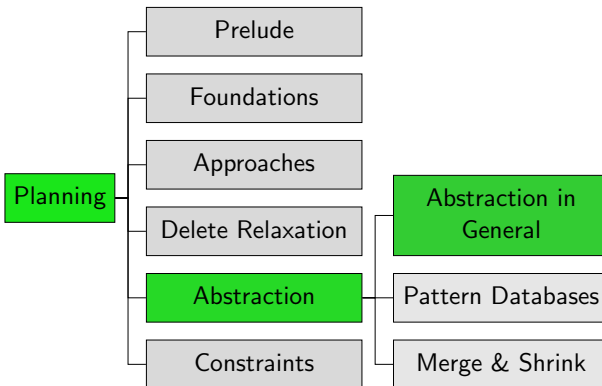
E5. Abstractions: Additive Abstractions

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Content of the Course



Additivity

Orthogonality of Abstractions

Definition (Orthogonal)

Let α_1 and α_2 be abstractions of transition system \mathcal{T} .

We say that α_1 and α_2 are **orthogonal** if for all transitions $s \xrightarrow{\ell} t$ of \mathcal{T} , we have $\alpha_1(s) = \alpha_1(t)$ or $\alpha_2(s) = \alpha_2(t)$.

Affecting Transition Labels

Definition (Affecting Transition Labels)

Let \mathcal{T} be a transition system, and let ℓ be one of its labels.

We say that ℓ **affects** \mathcal{T} if \mathcal{T} has a transition $s \xrightarrow{\ell} t$ with $s \neq t$.

Theorem (Affecting Labels vs. Orthogonality)

Let α_1 and α_2 be abstractions of transition system \mathcal{T} .

*If no label of \mathcal{T} affects both \mathcal{T}^{α_1} and \mathcal{T}^{α_2} ,
then α_1 and α_2 are orthogonal.*

(Easy proof omitted.)

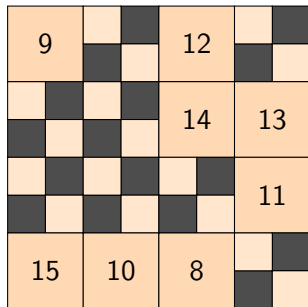
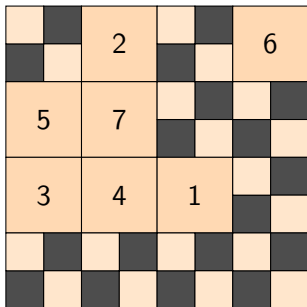
Orthogonal Abstractions: Example

| | | | |
|---|---|---|---|
| | 2 | | 6 |
| 5 | 7 | | |
| 3 | 4 | 1 | |
| | | | |

| | | | |
|----|----|----|----|
| 9 | | 12 | |
| | | 14 | 13 |
| | | | 11 |
| 15 | 10 | 8 | |

Are the abstractions orthogonal?

Orthogonal Abstractions: Example



Are the abstractions orthogonal?

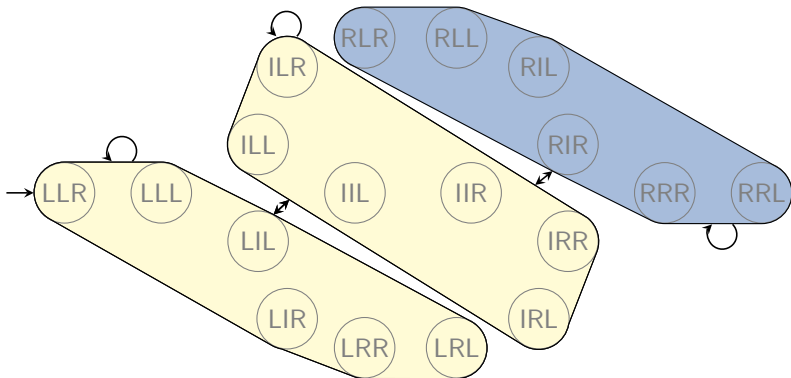
Orthogonality and Additivity

Theorem (Additivity for Orthogonal Abstractions)

Let $h^{\alpha_1}, \dots, h^{\alpha_n}$ be abstraction heuristics of the same transition system such that α_i and α_j are orthogonal for all $i \neq j$.

Then $\sum_{i=1}^n h^{\alpha_i}$ is a safe, goal-aware, admissible and consistent heuristic for Π .

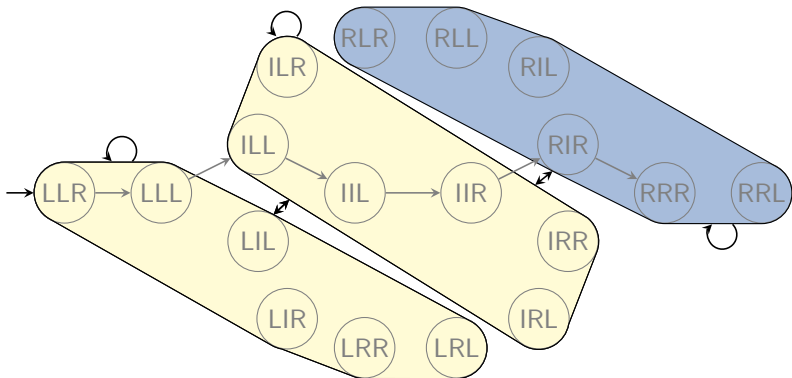
Orthogonality and Additivity: Example



abstraction α_1

abstraction: only consider value of first package

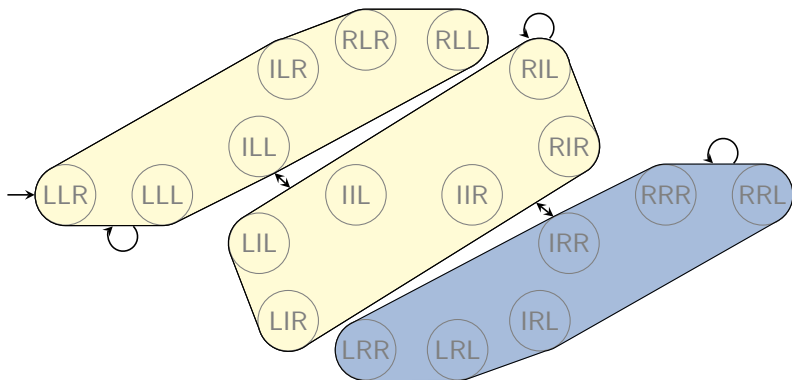
Orthogonality and Additivity: Example



abstraction α_1

abstraction: only consider value of first package

Orthogonality and Additivity: Example



abstraction α_2 (orthogonal to α_1)

abstraction: only consider value of second package

Orthogonality and Additivity: Proof (1)

Proof.

We prove goal-awareness and consistency;
the other properties follow from these two.

Let $\mathcal{T} = \langle S, L, c, T, s_0, S_\star \rangle$ be the concrete transition system.

Let $h = \sum_{i=1}^n h^{\alpha_i}$.

Orthogonality and Additivity: Proof (1)

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Goal-awareness: For goal states $s \in S_\star$,

$h(s) = \sum_{i=1}^n h^{\alpha_i}(s) = \sum_{i=1}^n 0 = 0$ because all individual
abstraction heuristics are goal-aware.

...

Orthogonality and Additivity: Proof (2)

Proof (continued).

Consistency: Let $s \xrightarrow{o} t \in \mathcal{T}$. We must prove $h(s) \leq c(o) + h(t)$.

Orthogonality and Additivity: Proof (2)

Proof (continued).

Consistency: Let $s \xrightarrow{o} t \in \mathcal{T}$. We must prove $h(s) \leq c(o) + h(t)$.

Because the abstractions are orthogonal, $\alpha_i(s) \neq \alpha_i(t)$

for **at most one** $i \in \{1, \dots, n\}$.

Orthogonality and Additivity: Proof (2)

Proof (continued).

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Case 1: $\alpha_i(s) = \alpha_i(t)$ for all $i \in \{1, \dots, n\}$.

Orthogonality and Additivity: Proof (2)

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Case 1: $\alpha_i(s) = \alpha_i(t)$ for all $i \in \{1, \dots, n\}$.

$$\begin{aligned} \text{Then } h(s) &= \sum_{i=1}^n h^{\alpha_i}(s) \\ &= \sum_{i=1}^n h_{\mathcal{T}^{\alpha_i}}^*(\alpha_i(s)) \\ &= \sum_{i=1}^n h_{\mathcal{T}^{\alpha_i}}^*(\alpha_i(t)) \\ &= \sum_{i=1}^n h^{\alpha_i}(t) \\ &= h(t) \leq c(o) + h(t). \end{aligned}$$

...

Orthogonality and Additivity: Proof (3)

Proof (continued).

Case 2: $\alpha_i(s) \neq \alpha_i(t)$ for exactly one $i \in \{1, \dots, n\}$.

Let $k \in \{1, \dots, n\}$ such that $\alpha_k(s) \neq \alpha_k(t)$.

Orthogonality and Additivity: Proof (3)

Proof (continued).

Case 2: $\alpha_i(s) \neq \alpha_i(t)$ for exactly one $i \in \{1, \dots, n\}$.

Let $k \in \{1, \dots, n\}$ such that $\alpha_k(s) \neq \alpha_k(t)$.

$$\begin{aligned} \text{Then } h(s) &= \sum_{i=1}^n h^{\alpha_i}(s) \\ &= \sum_{i \in \{1, \dots, n\} \setminus \{k\}} h_{\mathcal{T}^{\alpha_i}}^*(\alpha_i(s)) + h^{\alpha_k}(s) \\ &\leq \sum_{i \in \{1, \dots, n\} \setminus \{k\}} h_{\mathcal{T}^{\alpha_i}}^*(\alpha_i(t)) + c(o) + h^{\alpha_k}(t) \\ &= c(o) + \sum_{i=1}^n h^{\alpha_i}(t) \\ &= c(o) + h(t), \end{aligned}$$

where the inequality holds because $\alpha_i(s) = \alpha_i(t)$ for all $i \neq k$ and h^{α_k} is consistent. □

Outlook

Using Abstraction Heuristics in Practice

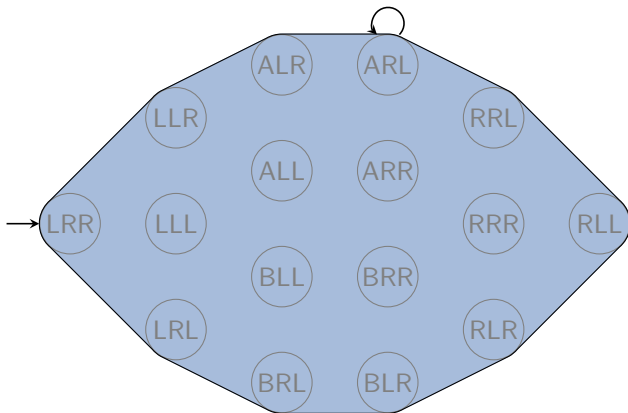
In practice, there are conflicting goals for abstractions:

- we want to obtain an **informative heuristic**, but
- want to keep its **representation small**.

Abstractions have small representations if

- there are **few abstract states** and
- there is a **succinct encoding for α** .

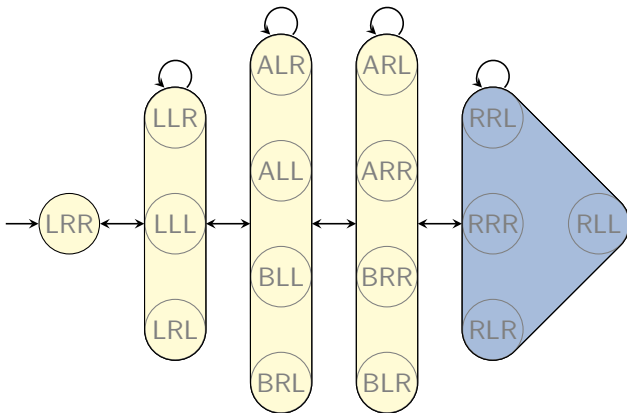
Counterexample: One-State Abstraction



One-state abstraction: $\alpha(s) := \text{const.}$

- + very few abstract states and succinct encoding for α
- completely uninformative heuristic

Counterexample: Perfect Abstraction



Perfect abstraction: $\alpha(s) := h^*(s)$.

- + perfect heuristic and usually few abstract states
- usually no succinct encoding for α

Automatically Deriving Good Abstraction Heuristics

Abstraction Heuristics for Planning: Main Research Problem

Automatically derive effective abstraction heuristics
for planning tasks.

↪ we will study two state-of-the-art approaches
in the following chapters

Summary

Summary

- Abstraction heuristics from **orthogonal** abstractions can be **added** without losing admissibility or consistency.
- One sufficient condition for orthogonality is that all abstractions are **affected** by **disjoint** sets of **labels**.
- Practically useful abstractions are those which give **informative heuristics**, yet have a **small representation**.
- Coming up with **good abstractions automatically** is the main research challenge when applying abstraction heuristics in planning.