Planning and Optimization D4. Delete Relaxation: AND/OR Graphs

Malte Helmert and Gabriele Röger

Universität Basel

October 23, 2024

M. Helmert, G. Röger (Universität Basel)

M. Helmert, G. Röger (Universität Basel)

Planning and Optimization

October 23, 2024 1 / 30

October 23, 2024

Planning and Optimization

October 23, 2024 — D4. Delete Relaxation: AND/OR Graphs

D4.1 AND/OR Graphs

D4.2 Forced Nodes

D4.3 Most/Least Conservative Valuations

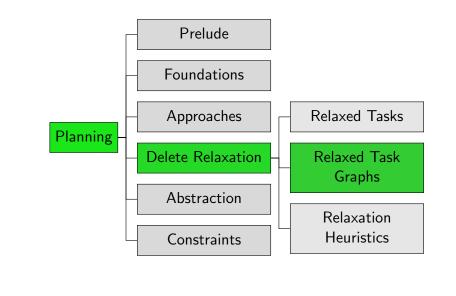
D4.4 Summary

M. Helmert, G. Röger (Universität Basel)

Planning and Optimization

October 23, 2024

Content of the Course



Planning and Optimization

D4. Delete Relaxation: AND/OR Graphs

AND/OR Graphs

D4.1 AND/OR Graphs

M. Helmert, G. Röger (Universität Basel)

Planning and Optimization

October 23, 2024

AND/OR Graphs: Motivation

AND/OR graphs.

Using Relaxations in Practice

How can we use relaxations for heuristic planning in practice?

Different possibilities:

- Implement an optimal planner for relaxed planning tasks and use its solution costs as estimates, even though optimal relaxed planning is NP-hard.
 - $\rightsquigarrow h^+$ heuristic
- ▶ Do not actually solve the relaxed planning task, but compute an approximation of its solution cost. $\rightarrow h^{\text{max}}$ heuristic, h^{add} heuristic, $h^{\text{LM-cut}}$ heuristic
- ► Compute a solution for relaxed planning tasks which is not necessarily optimal, but "reasonable". $\sim h^{FF}$ heuristic

M. Helmert, G. Röger (Universität Basel)

October 23, 2024

AND/OR Graphs

October 23, 2024

D4. Delete Relaxation: AND/OR Graphs AND/OR Graphs

M. Helmert, G. Röger (Universität Basel)

Definition (AND/OR Graph)

An AND/OR graph $\langle N, A, type \rangle$ is a directed graph $\langle N, A \rangle$ with a node label function $type: N \to \{\land, \lor\}$ partitioning nodes into

Most relaxation heuristics we will consider can be understood

in terms of computations on graphical structures called

Planning and Optimization

► We now introduce AND/OR graphs and study

▶ In the next chapter, we will relate AND/OR graphs

some of their major properties.

to relaxed planning tasks.

- ▶ AND nodes $(type(v) = \land)$ and
- $ightharpoonup OR nodes (type(v) = \lor).$

We write succ(n) for the successors of node $n \in N$, i.e., $succ(n) = \{ n' \in N \mid \langle n, n' \rangle \in A \}.$

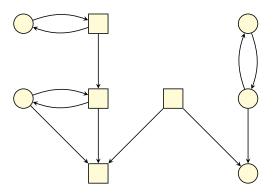
Note: We draw AND nodes as squares and OR nodes as circles.

Planning and Optimization

AND/OR Graphs

D4. Delete Relaxation: AND/OR Graphs

AND/OR Graph Example



M. Helmert, G. Röger (Universität Basel)

Planning and Optimization

October 23, 2024

M. Helmert, G. Röger (Universität Basel)

Planning and Optimization

October 23, 2024

AND/OR Graph Valuations

Definition (Consistent Valuations of AND/OR Graphs)

Let G be an AND/OR graph with nodes N.

A valuation or truth assignment of G is an interpretation $\alpha: N \to \{T, F\}$, treating the nodes as propositional variables.

We say that α is consistent if

- ▶ for all AND nodes $n \in \mathbb{N}$: $\alpha \models n$ iff $\alpha \models \bigwedge_{n' \in succ(n)} n'$.
- ▶ for all OR nodes $n \in N$: $\alpha \models n$ iff $\alpha \models \bigvee_{n' \in succ(n)} n'$.

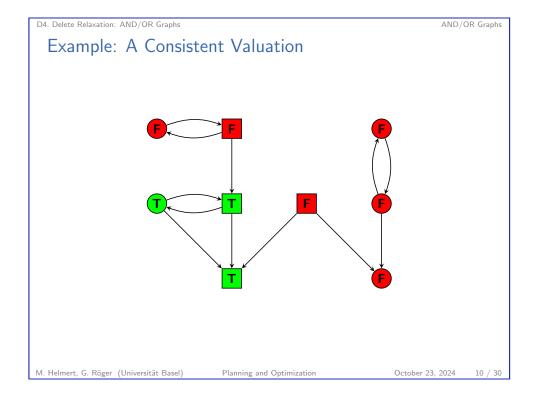
Note that $\bigwedge_{n' \in \emptyset} n' = \top$ and $\bigvee_{n' \in \emptyset} n' = \bot$.

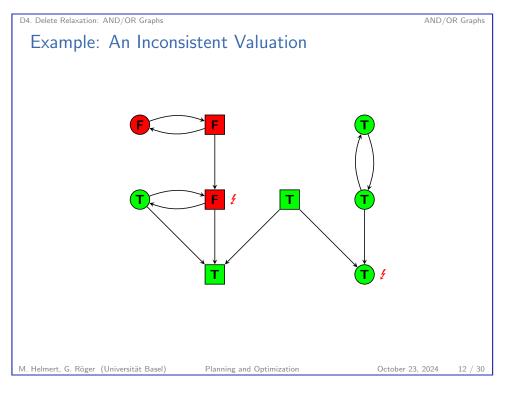
M. Helmert, G. Röger (Universität Basel)

Planning and Optimization

October 23, 2024 9

Example: Another Consistent Valuation T T T Planning and Optimization AND/OR Graphs AND/OR Graphs AND/OR Graphs AND/OR Graphs AND/OR Graphs AND/OR Graphs AND/OR Graphs





D4. Delete Relaxation: AND/OR Graphs

AND/OR Graphs

How Do We Find Consistent Valuations?

If we want to use valuations of AND/OR graphs algorithmically, a number of questions arise:

- ▶ Do consistent valuations exist for every AND/OR graph?
- ► Are they unique?
- ▶ If not, how are different consistent valuations related?
- Can consistent valuations be computed efficiently?

Our example shows that the answer to the second question is "no". In the rest of this chapter, we address the remaining questions.

M. Helmert, G. Röger (Universität Basel)

Planning and Optimization

October 23, 2024

13 / 30

D4. Delete Relaxation: AND/OR Graphs

Forced Nodes

D4.2 Forced Nodes

M. Helmert, G. Röger (Universität Basel)

Planning and Optimization

October 23, 2024

14 / 30

D4. Delete Relaxation: AND/OR Graphs

Forced Nodes

Forced Nodes

Definition (Forced True/False Nodes)

Let G be an AND/OR graph.

A node n of G is called forced true

if $\alpha(n) = \mathbf{T}$ for all consistent valuations α of G.

A node *n* of *G* is called forced false

if $\alpha(n) = \mathbf{F}$ for all consistent valuations α of G.

How can we efficiently determine that nodes are forced true/false?

→ We begin by looking at some simple rules.

D4. Delete Relaxation: AND/OR Graphs

Forced Nodes

Rules for Forced True Nodes

Proposition (Rules for Forced True Nodes)

Let n be a node in an AND/OR graph.

Rule T-(\land): If n is an AND node and all

of its successors are forced true, then n is forced true.

Rule T-(\vee): If n is an OR node and at least one of its successors is forced true, then n is forced true.

M. Helmert, G. Röger (Universität Basel)

Planning and Optimization

October 23, 2024

16 /

D4. Delete Relaxation: AND/OR Graphs

Forced Nodes

Rules for Forced False Nodes

Proposition (Rules for Forced False Nodes)

Let n be a node in an AND/OR graph.

Rule F-(\land): If n is an AND node and at least one of its successors is forced false, then n is forced false.

Rule \mathbf{F} -(\vee): If n is an OR node and all

of its successors are forced false, then n is forced false.

M. Helmert, G. Röger (Universität Basel)

Planning and Optimization

October 23, 2024

17 / 30

Example: Applying the Rules for Forced Nodes

(2) T (1) (1)

Planning and Optimization

D4. Delete Relaxation: AND/OR Graphs

Forced Nodes

Completeness of Rules for Forced Nodes

Theorem

If n is a node in an AND/OR graph that is forced true, then this can be derived by a sequence of applications of Rule \mathbf{T} -(\wedge) and Rule \mathbf{T} -(\vee).

Theorem

If n is a node in an AND/OR graph that is forced false, then this can be derived by a sequence of applications of Rule \mathbf{F} -(\wedge) and Rule \mathbf{F} -(\vee).

We prove the result for forced true nodes.

The result for forced false nodes can be proved analogously.

D4. Delete Relaxation: AND/OR Graphs

M. Helmert, G. Röger (Universität Basel)

Forced Node

October 23, 2024

Completeness of Rules for Forced Nodes: Proof (1)

Proof.

- Let α be a valuation where $\alpha(n) = \mathbf{T}$ iff there exists a sequence ρ_n of applications of Rules \mathbf{T} - (\wedge) and Rule \mathbf{T} - (\vee) that derives that n is forced true.
- ▶ Because the rules are monotonic, there exists a sequence ρ of rule applications that derives that n is forced true for all $n \in on(\alpha)$. (Just concatenate all ρ_n to form ρ .)
- By the correctness of the rules, we know that all nodes reached by ρ are forced true. It remains to show that none of the nodes not reached by ρ is forced true.
- We prove this by showing that α is consistent, and hence no nodes with $\alpha(n) = \mathbf{F}$ can be forced true.

. . .

M. Helmert, G. Röger (Universität Basel)

Planning and Optimization

October 23, 2024

M. Helmert, G. Röger (Universität Basel)

Planning and Optimization

October 23, 2024

1 20

D4. Delete Relaxation: AND/OR Graphs

Forced Nodes

Completeness of Rules for Forced Nodes: Proof (2)

Proof (continued).

Case 1: nodes n with $\alpha(n) = \mathbf{T}$

- In this case, ρ must have reached n in one of the derivation steps. Consider this derivation step.
- If n is an AND node, ρ must have reached all successors of n in previous steps, and hence $\alpha(n') = \mathbf{T}$ for all successors n'.
- If n is an OR node, ρ must have reached at least one successor of n in a previous step, and hence $\alpha(n') = \mathbf{T}$ for at least one successor n'.
- ln both cases, α is consistent for node n.

M. Helmert, G. Röger (Universität Basel)

Planning and Optimization

October 23, 2024

21 / 30

D4. Delete Relaxation: AND/OR Graphs

Forced Nodes

Completeness of Rules for Forced Nodes: Proof (3)

Proof (continued).

Case 2: nodes n with $\alpha(n) = \mathbf{F}$

- In this case, by definition of α no sequence of derivation steps reaches n. In particular, ρ does not reach n.
- If n is an AND node, there must exist some $n' \in succ(n)$ which ρ does not reach. Otherwise, ρ could be extended using Rule \mathbf{T} - (\land) to reach n. Hence, $\alpha(n') = \mathbf{F}$ for some $n' \in succ(n)$.
- If n is an OR node, there cannot exist any $n' \in succ(n)$ which ρ reaches. Otherwise, ρ could be extended using Rule \mathbf{T} -(\vee) to reach n. Hence, $\alpha(n') = \mathbf{F}$ for all $n' \in succ(n)$.
- ln both cases, α is consistent for node n.

M. Helmert, G. Röger (Universität Basel)

Planning and Optimization

October 23, 2024

22 / 20

D4. Delete Relaxation: AND/OR Graphs

Forced Node

. . .

Remarks on Forced Nodes

Notes:

- ► The theorem shows that we can compute all forced nodes by applying the rules repeatedly until a fixed point is reached.
- In particular, this also shows that the order of rule application does not matter: we always end up with the same result.
- ▶ In an efficient implementation, the sets of forced nodes can be computed in linear time in the size of the AND/OR graph.
- ► The proof of the theorem also shows that every AND/OR graph has a consistent valuation, as we explicitly construct one in the proof.

D4. Delete Relaxation: AND/OR Graphs

M. Helmert, G. Röger (Universität Basel)

Most/Least Conservative Valuations

D4.3 Most/Least Conservative Valuations

Most/Least Conservative Valuation

Most and Least Conservative Valuation

Definition (Most and Least Conservative Valuation)

Let G be an AND/OR graph with nodes N.

The most conservative valuation $\alpha_{\mathrm{mcv}}^{\mathcal{G}}: \mathcal{N} \to \{\mathbf{T}, \mathbf{F}\}$ and the least conservative valuation $\alpha_{\mathrm{lcv}}^{\mathcal{G}}: \mathcal{N} \to \{\mathbf{T}, \mathbf{F}\}$ of \mathcal{G} are defined as:

$$lpha_{
m mcv}^{\it G}(\it n) = egin{cases} {f T} & {
m if} \ \it n \ {
m is} \ {
m forced} \ {f t} & {
m otherwise} \ \\ lpha_{
m lcv}^{\it G}(\it n) = egin{cases} {f F} & {
m if} \ \it n \ {
m is} \ {
m forced} \ {
m false} \ {f T} & {
m otherwise} \ \end{cases}$$

Note: $\alpha_{\rm mcv}^{\it G}$ is the valuation constructed in the previous proof.

M. Helmert, G. Röger (Universität Basel)

Planning and Optimization

October 23, 2024

25 / 30

Theorem (Properties of Most/Least Conservative Valuations)

Properties of Most/Least Conservative Valuations

Let G be an AND/OR graph. Then:

- $\alpha_{\rm mcv}^{\it G}$ is consistent.

D4. Delete Relaxation: AND/OR Graphs

§ For all consistent valuations α of G, $on(\alpha_{\text{mcv}}^G) \subseteq on(\alpha) \subseteq on(\alpha_{\text{lcv}}^G)$.

M. Helmert, G. Röger (Universität Basel)

Planning and Optimization

October 23, 2024

D4. Delete Relaxation: AND/OR Graphs

Most/Least Conservative Valuation

Properties of MCV/LCV: Proof

Proof.

Part 1. was shown in the preceding proof. We showed that the valuation α considered in this proof is consistent and satisfies $\alpha(n)=\mathbf{T}$ iff n is forced true, which implies $\alpha=\alpha_{\mathrm{mcv}}^{G}$.

The proof of Part 2. is analogous, using the rules for forced false nodes instead of forced true nodes.

Part 3 follows directly from the definitions of forced nodes, α_{mcv}^G and α_{lcv}^G .

D4. Delete Relaxation: AND/OR Graphs

Most/Least Conservative Valuations

Properties of MCV/LCV: Consequences

This theorem answers our remaining questions about the existence, uniqueness, structure and computation of consistent valuations:

- Consistent valuations always exist and can be efficiently computed.
- ► All consistent valuations lie between the most and least conservative one.
- ► There is a unique consistent valuation iff $\alpha_{\text{mcv}}^{\mathcal{G}} = \alpha_{\text{lcv}}^{\mathcal{G}}$, or equivalently iff each node is forced true or forced false.

M. Helmert, G. Röger (Universität Basel)

Planning and Optimization

October 23, 2024

0

M. Helmert, G. Röger (Universität Basel)

lanning and Optimization

October 23, 2024

28 / 30

D4. Delete Relaxation: AND/OR Graphs Summary

D4.4 Summary

M. Helmert, G. Röger (Universität Basel)

Planning and Optimization

October 23, 2024

D4. Delete Relaxation: AND/OR Graphs

Summary

► AND/OR graphs are directed graphs with AND nodes and OR nodes.

- ▶ We can assign truth values to AND/OR graph nodes.
- ► Such valuations are called **consistent** if they match the intuitive meaning of "AND" and "OR".
- ► Consistent valuations always exist.
- ► Consistent valuations can be computed efficiently.
- ▶ All consistent valuations fall between two extremes:
 - ► the most conservative valuation, where only nodes that are forced to be true are true
 - ► the least conservative valuation, where all nodes that are not forced to be false are true

M. Helmert, G. Röger (Universität Basel)

Planning and Optimization

October 23, 2024

30 / 30