

Discrete Mathematics in Computer Science November 18/20, 2024 — C4. Further Topics in Graph Theory C4.1 Subgraphs C4.2 Isomorphism C4.3 Planarity and Minors



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Subgraphs

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Subgraphs

### Subgraphs

Definition (subgraph) A subgraph of a graph (V, E) is a graph (V', E')

with  $V' \subseteq V$  and  $E' \subseteq E$ .

A subgraph of a digraph (N, A) is a digraph (N', A') with  $N' \subseteq N$  and  $A' \subseteq A$ .

German: Teilgraph/Untergraph

Question: Can we choose V' and E' arbitrarily?

The subgraph relationship defines a partial order on graphs (and on digraphs).

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Induced Subgraphs (1)

Definition (induced subgraph) Let G = (V, E) be a graph, and let  $V' \subseteq V$ . The subgraph of G induced by V' is the graph (V', E')with  $E' = \{\{u, v\} \in E \mid u, v \in V'\}$ . We say that G' is an induced subgraph of G = (V, E) if G' is the subgraph of G induced by V' for any set of vertices  $V' \subseteq V$ .

German: induzierter Teilgraph (eines Graphen)











Subgraphs

#### Isomorphism

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Isomorphism

# C4.2 Isomorphism

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Isomorphism

- In many cases, the "names" of the vertices of a graph do not have any particular semantic meaning.
- Often, we care about the structure of the graph, i.e., the relationship between the vertices and edges, but not what we call the different vertices.
- ▶ This is captured by the concept of isomorphism.



## C4. Further Topics in Graph Theory Isomorphism – Definition Definition (Isomorphism) Let G = (V, E) and G' = (V', E') be graphs. An isomorphism from G to G' is a bijective function $\sigma : V \rightarrow V'$ such that for all $u, v \in V$ : $\{u, v\} \in E$ iff $\{\sigma(u), \sigma(v)\} \in E'$ . If there exists an isomorphism from G to G', we say that they are isomorphic, in symbols $G \cong G'$ . German: Isomorphismus, isomorph • derives from Ancient Greek for "equally shaped/formed" • analogous definition for digraphs omitted















▶ To prove that two graphs are isomorphic, it suffices to state an isomorphism and verify that it has the required properties.

- To prove that two graphs are not isomorphic, we must rule out all possible bijections.
  - ▶ With *n* vertices, there are *n*! bijections.
  - example n = 10: 10! = 3628800

Proving and Disproving Isomorphism

- A common disproof idea is to identify a graph invariant, i.e., a property of a graph that must be the same in isomorphic graphs, and show that it differs.
  - examples: number of vertices, number of edges, maximum/minimum degree, sorted sequence of all degrees, number of connected components



## Scientific Pop Culture

- Determining if two graphs are isomorphic is an algorithmic problem that has been famously resistant to studying its complexity.
- For more than 40 years, we have not known if polynomial algorithms exist, and we also do not know if it belongs to the famous class of NP-complete problems.
- In 2015, László Babai announced an algorithm with quasi-polynomial (worse than polynomial, better than exponential) runtime.

### Further Reading

Martin Grohe, Pascal Schweitzer. The Graph Isomorphism Problem. Communications of the ACM 63(11):128–134, November 2020. https://dl.acm.org/doi/10.1145/3372123

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## Symmetries, Automorphisms and Group Theory

- An isomorphism σ between a graph G and itself is called an automorphism or symmetry of G.
- For every graph, its symmetries are permutations of its vertices that form a mathematical structure called a group:
  - the identity function is a symmetry
  - the composition of two symmetries is a symmetry
  - the inverse of a symmetry is a symmetry

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Isomorphism

C4. Further Topics in Graph Theory

Planarity and Minors

# C4.3 Planarity and Minors

#### C4. Further Topics in Graph Theory Planarity and Minors C4. Further Topics in Graph Theory Planarity and Minors Planar Embeddings – Example Planarity B We often draw graphs as 2-dimensional pictures. ▶ When we do so, we usually try to draw them in such a way that different edges do not cross. В А This often makes the picture neater and the edges easier to visualize. A picture of a graph with no edge crossings is called a planar embedding. not a planar embedding planar embedding ► A graph for which a planar embedding exists is called planar. The complete graph over 4 vertices is planar. M. Helmert, G. Röger (University of Basel) Discrete Mathematics in Computer Science November 18/20, 2024 29 / 43 M. Helmert, G. Röger (University of Basel) Discrete Mathematics in Computer Science November 18/20, 2024 30 / 43 C4. Further Topics in Graph Theory C4. Further Topics in Graph Theory Planarity and Minors Planarity and Minors Planar Graphs – Discussion **Planar Graphs** Definition (planar) A graph G = (V, E) is called planar if there exists Planar graphs arise in many practical applications. a planar embedding of G, i.e., a picture of GMany computational problems are easier for planar graphs. in the Euclidean plane in which no two edges intersect. For example, every planar graph can be coloured with at most German: planar 4 colours (i.e., we can assign one of four colours to each vertex such that two neighbours always have different colours). Notes: For this reason, planarity is of great practical interest. We do not formally define planar embeddings, ▶ How can we recognize that a graph is planar? as this is nontrivial and not necessary for our discussion. ▶ How can we prove that a graph is **not** planar? In general, we may draw edges as arbitrary curves.

However, it is possible to show that a graph has a planar embedding iff it has a planar embedding where all edges are straight lines.



- The two non-planar graphs K<sub>5</sub> and K<sub>3,3</sub> are special: they are the smallest non-planar graphs.
- In fact, something much more powerful holds: a graph is planar iff it does not contain K<sub>5</sub> or K<sub>3,3</sub>.
- The notion of containment we need here is related to the notion of subgraphs that we introduced, but a bit more complex. We will discuss it next.







Theorem (Wagner's Theorem)

A graph is planar iff it does not contain  $K_5$  or  $K_{3,3}$  as a minor.

German: Satz von Wagner

Note: There exist linear algorithms for testing planarity.

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Planarity and Minors

### Minor

### Definition (minor)

We say that a graph G' is a minor of a graph G if it can be obtained from G through a sequence of transformations of the following kind:

- remove a vertex (of degree 0) from the graph
- emove an edge from the graph
- Output in the graph

German: Minor (plural: Minoren)

### Notes:

- If we only allowed the first two transformations, we would obtain the regular subgraph relationship.
- It follows that every subgraph is a minor, but the opposite is not true in general.

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Planarity and Minors

### The Graph Minor Theorem

### Theorem (Graph minor theorem)

Let  $\Pi$  be a minor-hereditary property of graphs.

Then there exists a finite set of forbidden minors  $F(\Pi)$  such that the following result holds:

A graph has property  $\Pi$  iff it does not have any graph from  $F(\Pi)$  as a minor.

German: Minorentheorem

### Examples:

- ▶ the forbidden minors for planarity are  $K_5$  and  $K_{3,3}$
- the (only) forbidden minor for acyclicity is K<sub>3</sub>, the complete graph with 3 vertices (a.k.a. the 3-cycle graph)

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Remarks on the Graph Minor Theorem (2)

- ▶ In principle, for every fixed graph *H*, we can test if *H* is a minor of a graph *G* in polynomial time in the size of *G*.
- This implies that every minor-hereditary property can be tested in polynomial time.
- ► However, the constant factors involved in the known general algorithms for testing minors (which depend on |*H*|) are so astronomically huge as to make them infeasible in practice.

