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Traversing Graphs

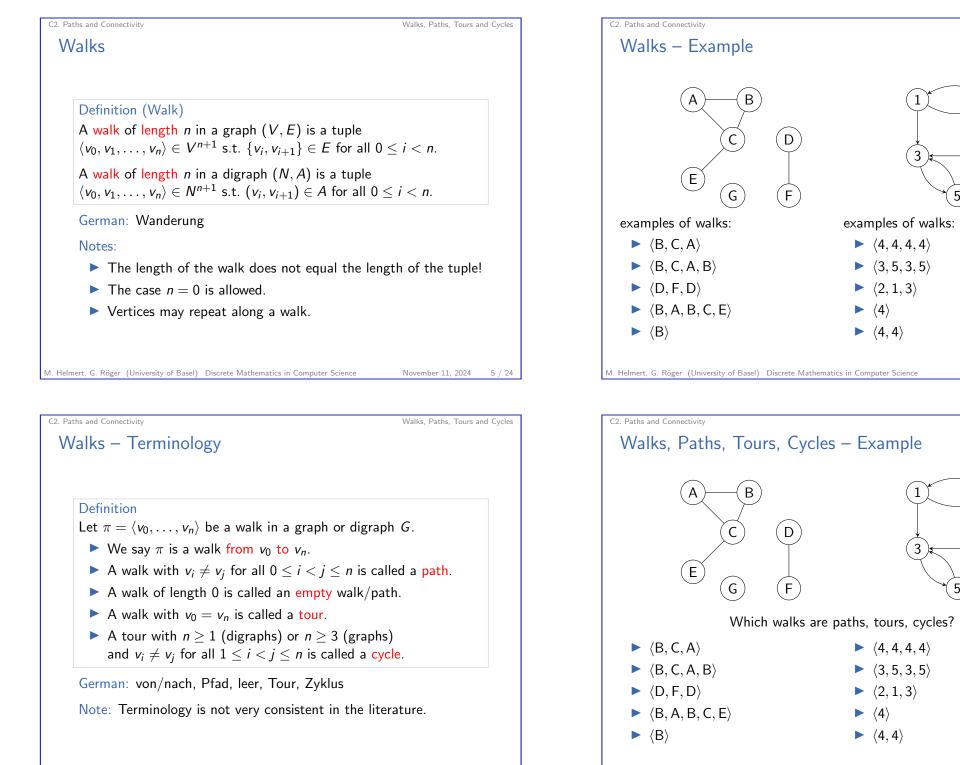
C2. Paths and Connectivity

- When dealing with graphs, we are often not just interested in the neighbours, but also in the neighbours of neighbours, the neighbours of neighbours of neighbours, etc.
- Similarly, for digraphs we often want to follow longer chains of successors (or chains of predecessors).

### Examples:

- circuits: follow predecessors of signals to identify possible causes of faulty signals
- pathfinding: follow edges/arcs to find paths
- control flow graphs: follow arcs to identify dead code
- computer networks: determine if part of the network is unreachable

Walks, Paths, Tours and Cycles



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Reachability

# C2.2 Reachability

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C2. Paths and Connectivity

Reachability as Closure

Recall the *n*-fold composition  $R_n$  of a relation R over set S (Chapter B4):

- ►  $R_0 = \{(x, x) \mid x \in S\}$
- ▶  $R_n = R \circ R_{n-1}$  for  $n \ge 1$

### Theorem

Let G be a graph or digraph. Then:  $(u, v) \in S_G^n$  iff there exists a walk of length n from u to v.

### Corollary

Let G be a graph or digraph. Then  $R_G = \bigcup_{n=0}^{\infty} (S_G)_n$ .

In other words, the reachability relation is the reflexive transitive closure of the successor relation.

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Reachability

# C2. Paths and Connectivity

# Reachability

Definition (successor and reachability)

Let G be a graph (digraph).

The successor relation  $S_G$  and reachability relation  $R_G$  are relations over the vertices/nodes of G defined as follows:

- ▶  $(u, v) \in S_G$  iff  $\{u, v\}$  is an edge ((u, v) is an arc) of G
- (u, v)  $\in \mathsf{R}_G$  iff there exists a walk from u to v

If  $(u, v) \in \mathsf{R}_{\mathsf{G}}$ , we say that v is reachable from u.

German: Nachfolger-/Erreichbarkeitsrelation, erreichbar

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Reachability as Closure – Proof (1)

### Proof.

To simplify notation, we assume G = (N, A) is a digraph. Graphs are analogous. Proof by induction over n.

### induction base (n = 0):

By definition of the 0-fold composition, we have  $(u, v) \in (S_G)_0$  iff u = v, and a walk of length 0 from u to v exists iff u = v. Hence, the two conditions are equivalent.

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### C2. Paths and Connectivity

# Reachability as Closure - Proof (2)

### Proof (continued). induction step $(n \rightarrow n+1)$ : $(\Rightarrow)$ : Let $(u, v) \in (S_G)_{n+1}$ . By definition of $R_{n+1}$ , we get $(u, v) \in S_G \circ (S_G)_n$ . By definition of $\circ$ there exists w with $(u, w) \in (S_G)_n$ and $(w, v) \in S_G$ . From the induction hypothesis, there exists a length-n walk $\langle x_0, \ldots, x_n \rangle$ with $x_0 = u$ and $x_n = w$ . Then $\langle x_0, \ldots, x_n, v \rangle$ is a length-(n+1) walk from u to v. $(\Leftarrow)$ : Let $\langle x_0, \ldots, x_{n+1} \rangle$ be a length-(n+1) walk from u to v $(x_0 = u, x_{n+1} = v)$ . Then $(x_n, x_{n+1}) = (x_n, v) \in A$ . Also, $\langle x_0, \ldots, x_n \rangle$ is a length-*n* walk from $x_0$ to $x_n$ . From the IH we get $(u, x_n) = (x_0, x_n) \in (S_G)_n$ . Together with $(x_n, v) \in S_G$ this shows $(u, v) \in S_G \circ (S_G)_n = (S_G)_{n+1}$ A. Helmert, G. Röger (University of Basel) Discrete Mathematics in Computer Science November 11, 2024 13 / 24

C2. Paths and Connectivity

Connected Components

Reachability

Overview

- ▶ In this section, we study reachability of graphs in more depth.
- We show that it makes no difference whether we define reachability in terms of walks or paths, and that reachability in graphs is an equivalence relation.
- ▶ This leads to the connected components of a graph.
- ▶ In digraphs, reachability is not always an equivalence relation.
- However, we can define two variants of reachability that give rise to weakly or strongly connected components.

# C2.3 Connected Components

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Connected Components

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Connected Components

# Walks vs. Paths

### Theorem

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Let G be a graph or digraph.

There exists a path from u to v iff there exists a walk from u to v.

In other words, there is a path from u to v iff v is reachable from u.

### Proof.

 $(\Rightarrow)$ : obvious because paths are special cases of walks

( $\Leftarrow$ ): Proof by contradiction. Assume there exist u, v such that there exists a walk from u to v, but no path. Let  $\pi = \langle w_0, \ldots, w_n \rangle$ be such a counterexample walk of minimal length. Because  $\pi$  is not a path, some vertex/node must repeat. Select i and j with i < j and  $w_i = w_j$ . Then  $\pi' = \langle w_0, \ldots, w_i, w_{j+1}, \ldots, w_n \rangle$  also is a walk from u to v. If  $\pi'$  is a path, we have a contradiction.

### C2. Paths and Connectivity

### Connected Components

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# Reachability in Graphs is an Equivalence Relation

### Theorem

For every graph G, the reachability relation  $R_G$  is an equivalence relation.

In directed graphs, this result does not hold (easy to see).

### Proof.

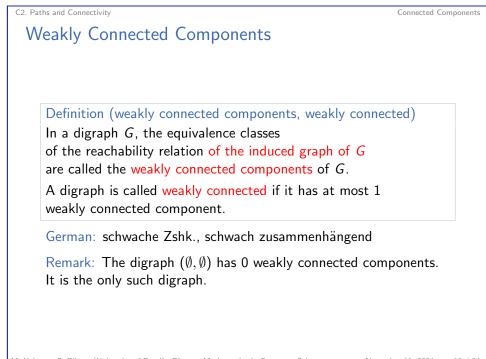
We already know reachability is reflexive and transitive. To prove symmetry:

### $(u, v) \in \mathsf{R}_{G}$

 $\Rightarrow$  there is a walk  $\langle w_0, \ldots, w_n \rangle$  from *u* to *v* 

- $\Rightarrow \langle w_n, \dots, w_0 
  angle$  is a walk from v to u
- $\Rightarrow$  (v, u)  $\in \mathsf{R}_{G}$

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### C2. Paths and Connectivity

## Connected Components

Definition (connected components, connected) In a graph G, the equivalence classes of the reachability relation of Gare called the connected components of G.

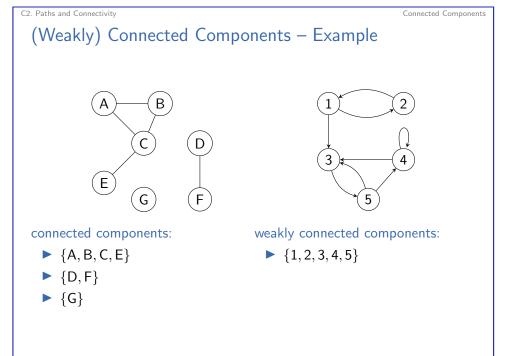
A graph is called **connected** if it has at most 1 connected component.

German: Zusammenhangskomponenten, zusammenhängend

Remark: The graph  $(\emptyset, \emptyset)$  has 0 connected components. It is the only such graph.

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# Mutual Reachability

Definition (mutually reachable)

Let G be a graph or digraph. Vertices/nodes u and v in G are called mutually reachable if v is reachable from u and u is reachable from v. We write  $M_G$  for the mutual reachability relation of G

German: gegenseitig erreichbar

Note: In graphs,  $M_G = R_G$ . (Why?)

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C2. Paths and Connectivity Connected Components Strongly Connected Components Definition (strongly connected components, strongly connected) In a digraph G, the equivalence classes of the mutual reachability relation are called the strongly connected components of G. A digraph is called strongly connected if it has at most 1 strongly connected component. German: starke Zshk., stark zusammenhängend Remark: The digraph  $(\emptyset, \emptyset)$  has 0 strongly connected components. It is the only such digraph. C2. Paths and Connectivity

# Mutual Reachability is an Equivalence Relation

### Theorem

For every digraph G, the mutual reachability relation  $M_G$  is an equivalence relation.

### Proof.

Note that  $(u, v) \in M_G$  iff  $(u, v) \in R_G$  and  $(v, u) \in R_G$ .

- ▶ reflexivity: for all v, we have  $(v, v) \in M_G$  because  $(v, v) \in R_G$
- ▶ symmetry: Let  $(u, v) \in M_G$ . Then  $(v, u) \in M_G$  is obvious.
- ▶ transitivity: Let  $(u, v) \in M_G$  and  $(v, w) \in M_G$ . Then:  $(u, v) \in R_G$ ,  $(v, u) \in R_G$ ,  $(v, w) \in R_G$ ,  $(w, v) \in R_G$ . Transitivity of  $R_G$  yields  $(u, w) \in R_G$  and  $(w, u) \in R_G$ , and hence  $(u, w) \in M_G$ .

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