



| Planning and Optimi December 13, 2023 — G9. Pos | ization t-hoc Optimization | | |
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Example (Example Task) SAS⁺ task $\Pi = \langle V, I, O, \gamma \rangle$ with $\blacktriangleright V = \{A, B, C\}$ with dom $(v) = \{0, 1, 2, 3, 4\}$ for all $v \in V$ $\blacktriangleright I = \{A \mapsto 0, B \mapsto 0, C \mapsto 0\}$ $\flat O = \{inc_x^v \mid v \in V, x \in \{0, 1, 2\}\} \cup \{jump^v \mid v \in V\}$ $\flat inc_x^v = \langle v = x, v := x + 1, 1 \rangle$ $\flat jump^v = \langle \bigwedge_{v' \in V: v' \neq v} v' = 4, v := 3, 1 \rangle$ $\flat \gamma = A = 3 \land B = 3 \land C = 3$ \blacktriangleright Each optimal plan consists of three increment operators for

► Each optimal plan consists of three increment operators for each variable ~→ h*(I) = 9

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Each operator affects only one variable.

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Example Task (2)

- In projections on single variables we can reach the goal with a jump operator: h^{A}(I) = h^{B}(I) = h^{C}(I) = 1.
- In projections on more variables, we need for each variable three applications of increment operators to reach the abstract goal from the abstract initial state: h^{A,B}(I) = h^{A,C}(I) = h^{B,C}(I) = 6





Post-hoc Optimization

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The heuristic that generalizes this kind of reasoning

can be computed for any kind of heuristic ...

... as long as we are able to determine relevance of operators

but for PhO to work well, it's important that the set of

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is the Post-hoc Optimization Heuristic (PhO)

▶ if in doubt, it's always safe to assume

an operator is relevant for a heuristic

relevant operators is as small as possible

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Post-hoc Optimization

Operator Relevance in Abstractions

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Definition (Reminder: Affecting Transition Labels) Let \mathcal{T} be a transition system, and let ℓ be one of its labels. We say that ℓ affects \mathcal{T} if \mathcal{T} has a transition $s \stackrel{\ell}{\to} t$ with $s \neq t$.

Definition (Operator Relevance in Abstractions) An operator o is relevant for an abstraction α if o affects \mathcal{T}^{α} .

We can efficiently determine operator relevance for abstractions.

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Post-hoc Optimization

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(2) Post-box Optimization

G9. Post-hoc Optimization Linear Program (2)

For set of abstractions $\{\alpha_1, \ldots, \alpha_n\}$:

Variables Non-negative variables X_o for all operators $o \in O$

Objective Minimize $\sum_{o \in O} X_o$

Subject to $\sum_{o \in O:o \text{ relevant for } \alpha} X_o \ge h^{\alpha}(s) \quad \text{for } \alpha \in \{\alpha_1, \dots, \alpha_n\}$ $X_o \ge 0 \qquad \text{for all } o \in O$

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Post-hoc Optimization

Post-hoc Optimization

Example

- only operators o_1, o_2, o_3 and o_4 are relevant for h_1 and $h_1(s_0) = 11$
- only operators o_3 , o_4 , o_5 and o_6 are relevant for h_2 and $h_2(s_0) = 11$
- only operators o_1, o_2 and o_6 are relevant for h_3 and $h_3(s_0) = 8$

Which operators are relevant for exactly the same heuristics? What is the resulting partitioning?

Answer: $o_1 \sim o_2$ and $o_3 \sim o_4$ $\Rightarrow O/\sim = \{[o_1], [o_3], [o_5], [o_6]\}$

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PhO Heuristic

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Post-hoc Optimization

G9. Post-hoc Optimization

Post-hoc Optimization Heuristic: Admissibility

Theorem (Admissibility)

The post-hoc optimization heuristic is admissible.

Proof.

Let Π be a planning task and $\{\alpha_1, \ldots, \alpha_n\}$ be a set of abstractions. We show that there is a feasible variable assignment with objective value equal to the cost of an optimal plan.

Let π be an optimal plan for state *s* and let $cost_{\pi}(O')$ be the cost incurred by operators from $O' \subseteq O$ in π .

Setting each $X_{[o]}$ to $cost_{\pi}([o])$ is a feasible variable assignment: Constraints $X_{[o]} \ge 0$ are satisfied.



G9. Post-hoc Optimization Post-hoc Optimization Heuristic: Admissibility

Theorem (Admissibility)

The post-hoc optimization heuristic is admissible.

Proof (continued).

For each $\alpha \in {\alpha_1, ..., \alpha_n}$, π is a solution in the abstract transition system and the sum in the corresponding constraint equals the cost of the state-changing abstract state transitions (i.e., not accounting for self-loops). As $h^{\alpha}(s)$ corresponds to the cost of an optimal solution in the abstraction, the inequality holds.

For this assignment, the objective function has value $h^*(s)$ (cost of π), so the objective value of the LP is admissible.

Post-hoc Optimization



Reminder: The Canonical Heuristic Function

If for a set of patterns no operator affects more than one pattern, the sum of the heuristic estimates is admissible.

Definition (Canonical Heuristic Function)

Let C be a pattern collection for an FDR planning task. The canonical heuristic $h^{\mathcal{C}}$ for pattern collection \mathcal{C} is defined as

$$h^{\mathcal{C}}(s) = \max_{\mathcal{D} \in \textit{cliques}(\mathcal{C})} \sum_{P \in \mathcal{D}} h^{P}(s),$$

where $cliques(\mathcal{C})$ is the set of all maximal cliques in the compatibility graph for C.

For a given pattern collection, the canonical heuristic is the best possible admissible heuristic not using cost partitioning.

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G9. Post-hoc Optimization

Combining Estimates from Abstraction Heuristics

Post-Hoc optimization combines multiple admissible heuristic estimates into one.

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- We have already heard of two other such approaches for abstraction heuristics.
 - ▶ the canonical heuristic (for PDBs), and
 - optimal cost partitioning (not covered in detail).
- ► How does PhO compare to these?

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Compariso

G9. Post-hoc Optimization Compariso What about Optimal Cost Partitioning for Abstractions? Optimal cost partitioning for abstractions... ... uses a state-specific LP to find the best possible cost partitioning, and sums up the heuristic estimates. ...dominates the canonical heuristic, i.e. for the same pattern collection, it never gives lower estimates than $h^{\mathcal{C}}$. ▶ ... is very expensive to compute (recomputing all abstract goal distances in every state).









Theorem

Consider the dual D of the LP solved by the post-hoc optimization heuristic in state s for a given set of abstractions. If we restrict the variables in D to integers, the objective value is the canonical heuristic value $h^{C}(s)$.

Corollary

The post-hoc optimization heuristic dominates the canonical heuristic for the same set of abstractions.

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Comparisor

h^{PhO} vs $h^{\mathcal{C}}$

For the canonical heuristic, we need to find all maximal cliques, which is an NP-hard problem.

- The post-hoc optimization heuristic dominates the canonical heuristic and can be computed in polynomial time.
- The post-hoc optimization heuristic solves an LP in each state.
- With post-hoc optimization, a large number of small patterns works well.

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Summary

- Post-hoc optimization heuristic constraints express admissibility of heuristics
- exploits (ir-)relevance of operators for heuristics
- explores the middle ground between canonical heuristic and optimal cost partitioning.
- For the same set of abstractions, the post-hoc optimization heuristic dominates the canonical heuristic.
- ► The computation can be done in polynomial time.

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G9.4 Summary

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Summarv

Comparison

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Summarv