

# Planning and Optimization

E8. Operator Counting

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— E8. Operator Counting

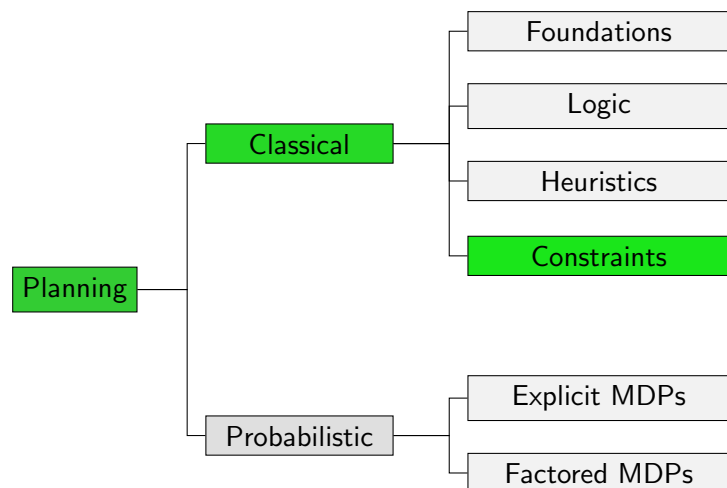
E8.1 Introduction

E8.2 Operator-counting Framework

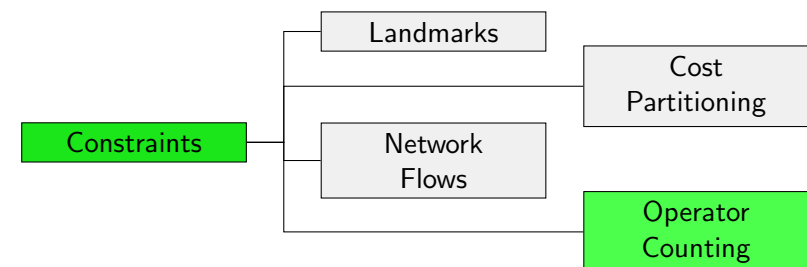
E8.3 Properties

E8.4 Summary

## Content of this Course



## Content of this Course: Constraints



## E8.1 Introduction

## Reminder: Flow Heuristic

In the previous chapter, we used **flow constraints** to describe how often operators must be used in each plan.

### Example (Flow Constraints)

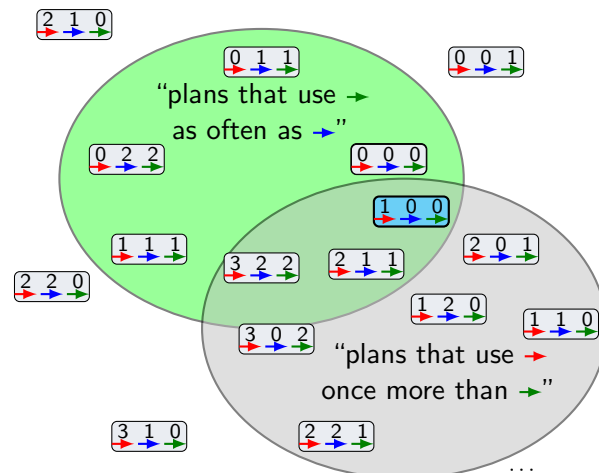
Let  $\Pi$  be a planning problem with operators  $\{o_{\text{red}}, o_{\text{green}}, o_{\text{blue}}\}$ . The flow constraint for some atom  $a$  is the constraint

$$1 + \text{Count}_{o_{\text{green}}} = \text{Count}_{o_{\text{red}}}$$

In natural language, this flow constraint expresses that every plan uses  $o_{\text{red}}$  once more than  $o_{\text{green}}$ .

## Reminder: Flow Heuristic

Let us now observe how each flow constraint alters the operator count solution space.



## E8.2 Operator-counting Framework

## Operator Counting

### Operator counting

- ▶ generalizes this idea to a framework that allows to **admissibly combine different heuristics**.
- ▶ uses **linear constraints** ...
- ▶ ... that describe **number of occurrences** of an operator ...
- ▶ ... and must be satisfied by **every plan**.
- ▶ provides declarative way to describe **knowledge about solutions**.
- ▶ allows **reasoning about solutions** to derive heuristic estimates.

## Operator-counting Constraint

### Definition (Operator-counting Constraints)

Let  $\Pi$  be a planning task with operators  $O$  and let  $s$  be a state. Let  $\mathcal{V}$  be the set of integer variables  $\text{Count}_o$  for each  $o \in O$ .

A linear inequality over  $\mathcal{V}$  is called an **operator-counting constraint** for  $s$  if for every plan  $\pi$  for  $s$  setting each  $\text{Count}_o$  to the number of occurrences of  $o$  in  $\pi$  is a feasible variable assignment.

## Operator-counting Heuristics

### Definition (Operator-counting IP/LP Heuristic)

The operator-counting integer program  $\text{IP}_C$  for a set  $C$  of operator-counting constraints for state  $s$  is

$$\text{Minimize } \sum_{o \in O} \text{cost}(o) \cdot \text{Count}_o \quad \text{subject to}$$

$$C \text{ and } \text{Count}_o \geq 0 \text{ for all } o \in O,$$

where  $O$  is the set of operators.

The **IP heuristic**  $h_C^{\text{IP}}$  is the objective value of  $\text{IP}_C$ , the **LP heuristic**  $h_C^{\text{LP}}$  is the objective value of its LP-relaxation.

If the IP/LP is infeasible, the heuristic estimate is  $\infty$ .

## Operator-counting Constraints

- ▶ Adding more constraints can only remove feasible solutions
- ▶ Fewer feasible solutions can only increase objective value
- ▶ Higher objective value means better informed heuristic

Are there operator-counting constraints other than flow constraints?



## Further Examples?

- ▶ The definition of operator-counting constraints can be extended to groups of constraints and auxiliary variables.
- ▶ With this extended definition we could also cover more heuristics, e.g., the perfect delete-relaxation heuristic  $h^+$ .

## E8.3 Properties

## Admissibility

### Theorem (Operator-counting Heuristics are Admissible)

The IP and the LP heuristic are *admissible*.

### Proof.

Let  $C$  be a set of operator-counting constraints for state  $s$  and  $\pi$  be an optimal plan for  $s$ . The number of operator occurrences of  $\pi$  are a feasible solution for  $C$ . As the IP/LP minimizes the total plan cost, the objective value cannot exceed the cost of  $\pi$  and is therefore an admissible estimate.  $\square$

## Dominance

### Theorem

Let  $C$  and  $C'$  be sets of operator-counting constraints for  $s$  and let  $C \subseteq C'$ . Then  $IP_C \leq IP_{C'}$  and  $LP_C \leq LP_{C'}$ .

### Proof.

Every feasible solution of  $C'$  is also feasible for  $C$ . As the LP/IP is a minimization problem, the objective value subject to  $C$  can therefore not be larger than the one subject to  $C'$ .  $\square$

Adding more constraints can only improve the heuristic estimate.

## Heuristic Combination

### Operator counting as heuristic combination

- ▶ Multiple operator-counting heuristics can be combined by computing  $h_C^{LP}/h_C^{IP}$  for the **union of their constraints**.
- ▶ This is an **admissible** combination.
  - ▶ Never worse than maximum of individual heuristics
  - ▶ Sometimes even better than their sum
- ▶ We already know a way of admissibly combining heuristics: cost partitioning.
  - ⇒ **How are they related?**

## Connection to Cost Partitioning

### Theorem

Let  $C_1, \dots, C_n$  be sets of operator-counting constraints for  $s$  and  $\mathcal{C} = \bigcup_{i=1}^n C_i$ . Then  $h_{\mathcal{C}}^{LP}$  is the **optimal general cost partitioning** over the heuristics  $h_{C_i}^{LP}$ .

Proof omitted.

## Comparison to Optimal Cost Partitioning



- ▶ some heuristics are **more compact** if expressed as operator counting
- ▶ some heuristics **cannot be expressed** as operator counting
- ▶ **operator counting IP** even better than optimal cost partitioning
- ▶ Cost partitioning maximizes, so heuristics must be encoded perfectly to guarantee admissibility. Operator counting minimizes, so missing information just makes the heuristic weaker.

## E8.4 Summary



## Summary

- ▶ Many heuristics can be formulated in terms of **operator-counting constraints**.
- ▶ The operator counting heuristic framework allows to **combine the constraints** and to reason on the entire encoded declarative knowledge.
- ▶ The heuristic estimate for the combined constraints **can be better than the one of the best ingredient heuristic** but never worse.
- ▶ Operator counting is **equivalent to optimal general cost partitioning** over individual constraints.

## Literature (1)

-  Florian Pommerening, Gabriele Röger and Malte Helmert.  
Getting the Most Out of Pattern Databases for Classical Planning.  
*Proc. IJCAI 2013*, pp. 2357–2364, 2013.  
**Introduces** post-hoc optimization and points out **relation to canonical heuristic**.
-  Blai Bonet.  
An Admissible Heuristic for SAS+ Planning Obtained from the State Equation.  
*Proc. IJCAI 2013*, pp. 2268–2274, 2013.  
**Suggests combination** of flow constraints and landmark constraints.

## Literature (2)

-  Tatsuya Imai and Alex Fukunaga.  
A Practical, Integer-linear Programming Model for the Delete-relaxation in Cost-optimal Planning.  
*Proc. ECAI 2014*, pp. 459–464, 2014.  
**IP formulation of  $h^+$** .
-  Florian Pommerening, Gabriele Röger, Malte Helmert and Blai Bonet.  
LP-based Heuristics for Cost-optimal Planning.  
*Proc. ICAPS 2014*, pp. 226–234, 2014.  
**Systematic introduction** of operator-counting framework.