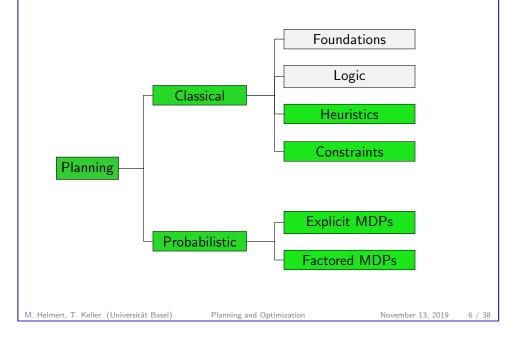
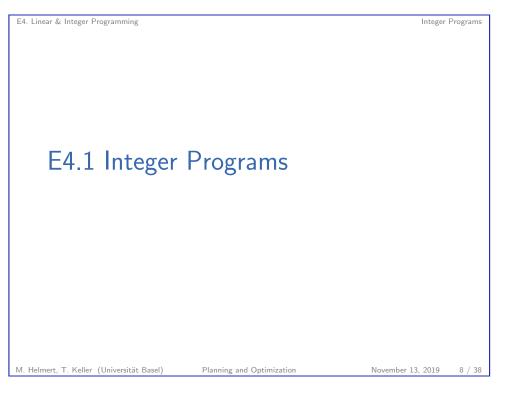
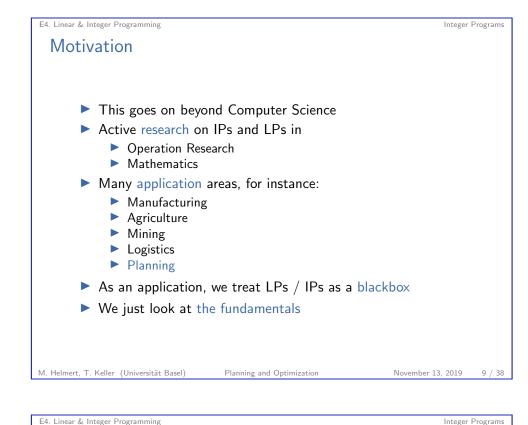


Content of this Course (Relevance)





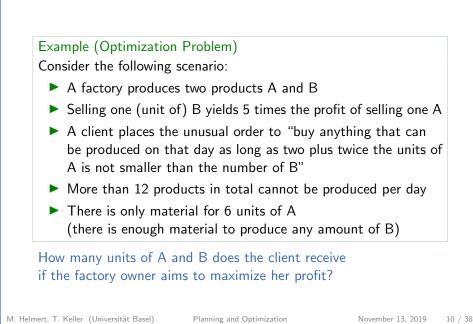


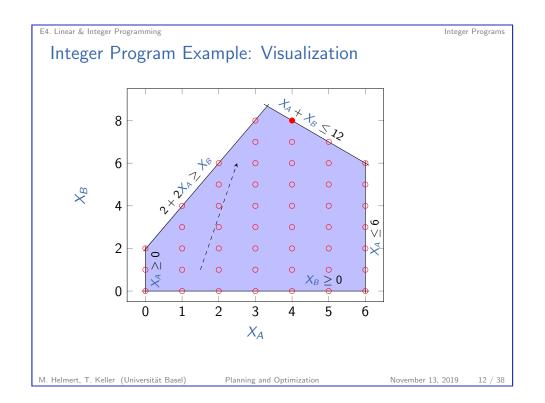
Integer Program: Example Let X_A and X_B be the (integer) number of produced A and B Example (Optimization Problem as Integer Program) maximize $X_A + 5X_B$ subject to $2 + 2X_A \ge X_B$ $X_A + X_B \le 12$ $X_A \le 6$ $X_A \ge 0, \quad X_B \ge 0$ \Rightarrow unique optimal solution: produce 4 A ($X_A = 4$) and 8 B ($X_B = 8$) for a profit of 44

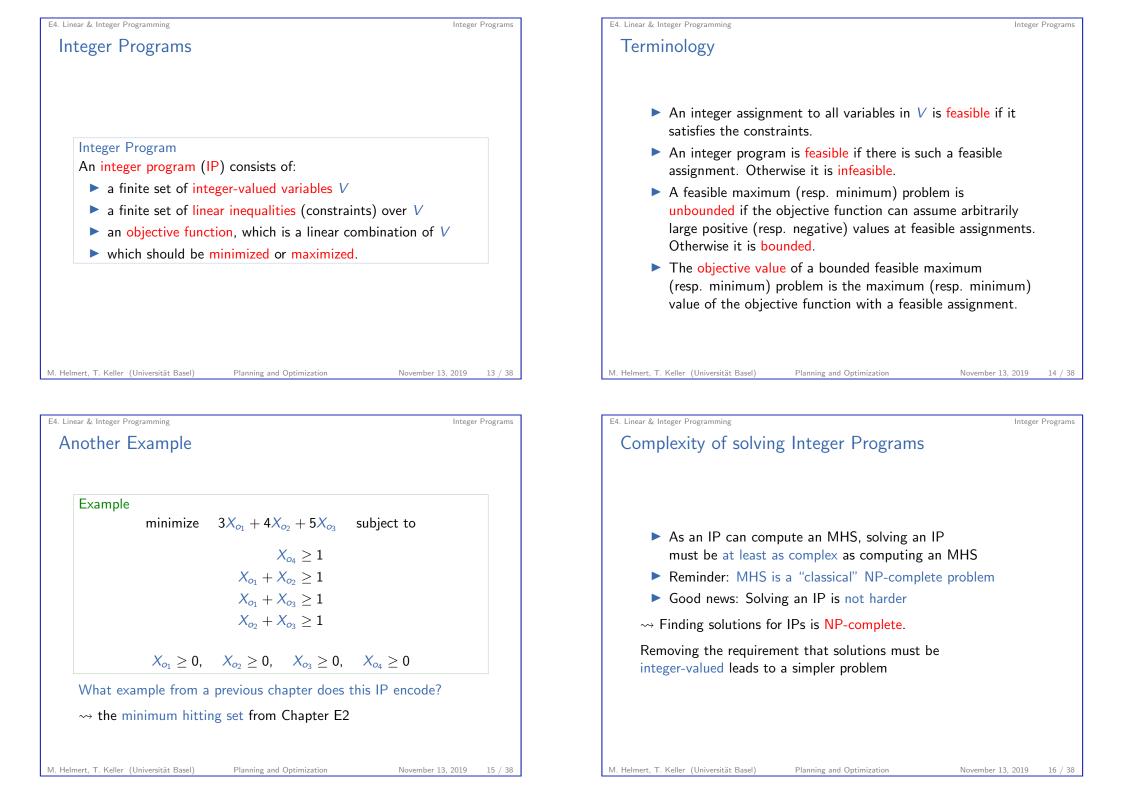
Planning and Optimization

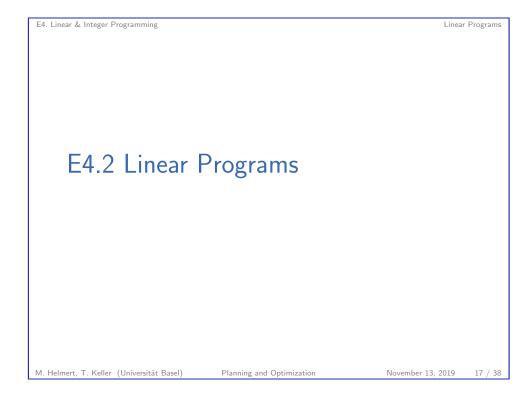
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E4. Linear & Integer Programming
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Motivation



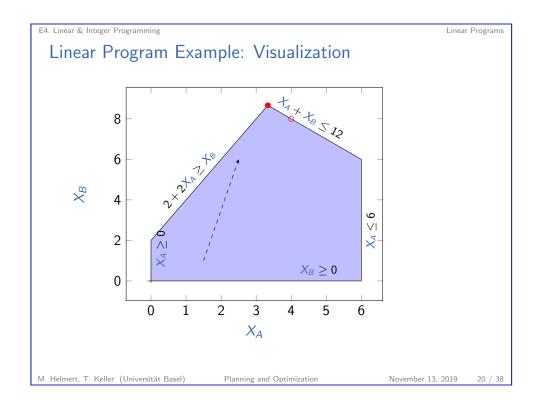


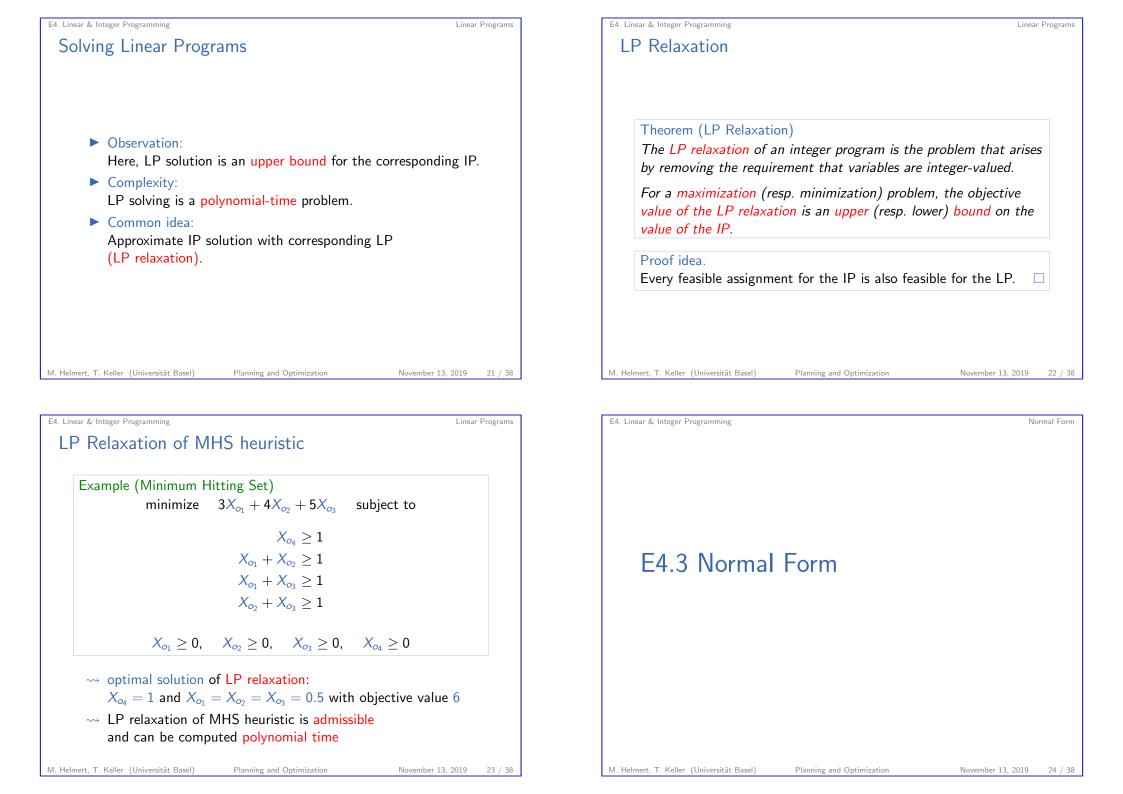


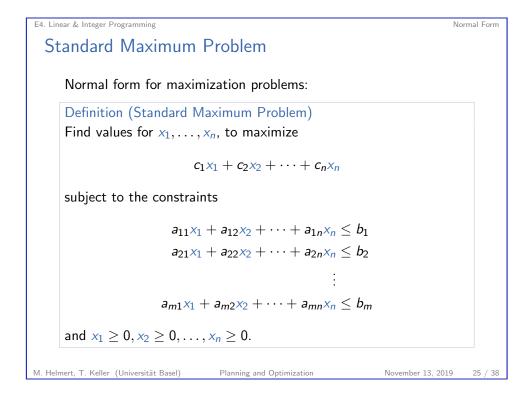


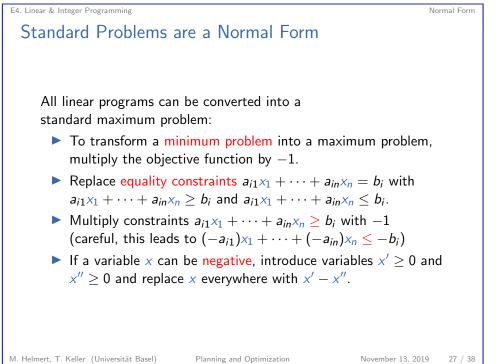
E4. Linear & Integer Programming Linear Programs Linear Program: Example Let X_A and X_B be the (real-valued) number of produced A and B Example (Optimization Problem as Linear Program) maximize $X_A + 5X_B$ subject to $2 + 2X_A > X_B$ $X_A + X_B \leq 12$ $X_{\Delta} < 6$ $X_A \geq 0, \quad X_B \geq 0$ \rightsquigarrow unique optimal solution: $X_A = 3\frac{1}{3}$ and $X_B = 8\frac{2}{3}$ with objective value $46\frac{2}{3}$ M. Helmert, T. Keller (Universität Basel) Planning and Optimization November 13, 2019 19 / 38

E4. Linear & Integer Programming Linear Programs Linear Programs Linear Program A linear program (LP) consists of: ► a finite set of real-valued variables V ▶ a finite set of linear inequalities (constraints) over V \blacktriangleright an objective function, which is a linear combination of V which should be minimized or maximized. We use the introduced IP terminology also for LPs. Mixed IPs (MIPs) are something between IPs and LPs: some variables are integer-value, some are real-valued. M. Helmert, T. Keller (Universität Basel) Planning and Optimization November 13, 2019 18 / 38

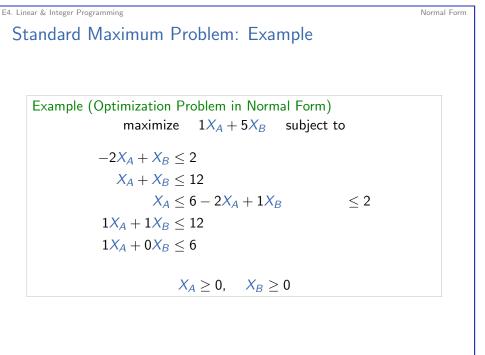






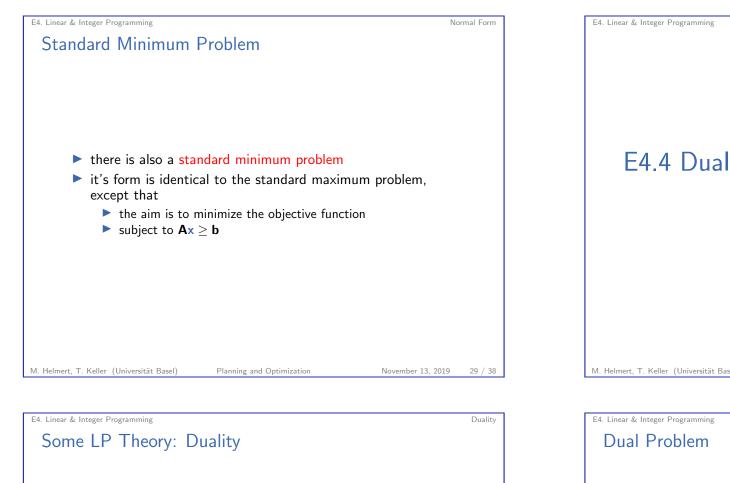


E4. Linear & Integer Programming Normal Form Standard Maximum Problem: Matrix and Vectors A standard maximum problem is often given by ▶ an *m*-vector $\mathbf{b} = \langle b_1, \ldots, b_m \rangle^T$ (bounds), ▶ an *n*-vector $\mathbf{c} = \langle c_1, \ldots, c_n \rangle^T$ (objective coefficients), \blacktriangleright and an $m \times n$ matrix $\mathbf{A} = \begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{pmatrix}$ (coefficients) ▶ Then the problem is to find a vector $\mathbf{x} = \langle x_1, \dots, x_n \rangle^T$ to maximize $\mathbf{c}^T \mathbf{x}$ subject to $\mathbf{A} \mathbf{x} < \mathbf{b}$ and $\mathbf{x} > \mathbf{0}$. M. Helmert, T. Keller (Universität Basel) Planning and Optimization November 13, 2019 26 / 38



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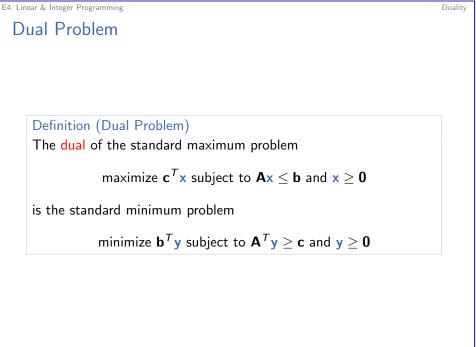
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Some LP theory: Every LP has an alternative view (its dual LP).

Primal	Dual
maximization (or minimization)	minimization (or maximization)
objective coefficients	bounds
bounds	objective coefficients
bounded variable	\geq -constraint
\leq -constraint	bounded variable
free variable	=-constraint
=-constraint	free variable
dual of dual: original LP	

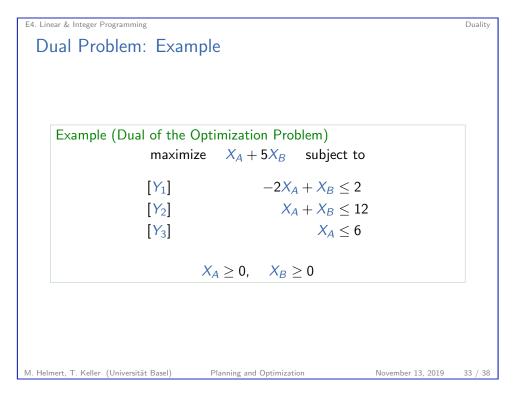




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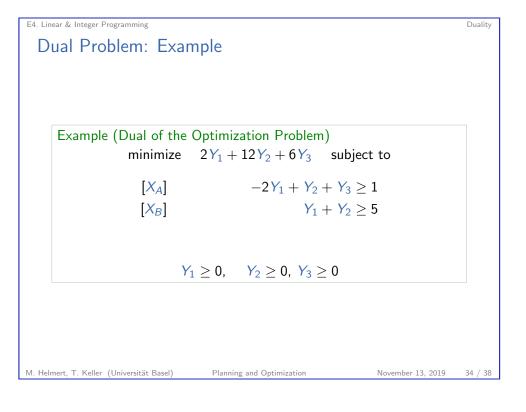
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Duality



E4. Linear & Integer Programming **Duality Theorem** Theorem (Duality Theorem) If a standard linear program is bounded feasible, then so is its dual, and their objective values are equal. (Proof omitted.) The dual provides a different perspective on a problem.

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Duality

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