Foundations of Artificial Intelligence D4. Constraint Satisfaction Problems: Arc Consistency

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D4.1 Inference

D4.2 Forward Checking

D4.3 Arc Consistency

D4.4 Summary

Constraint Satisfaction Problems: Overview

Chapter overview: constraint satisfaction problems

- ▶ D1–D2. Introduction
- D3–D5. Basic Algorithms
 - D3. Backtracking
 - D4. Arc Consistency
 - D5. Path Consistency
- ▶ D6–D7. Problem Structure

D4.1 Inference

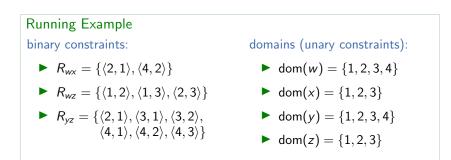
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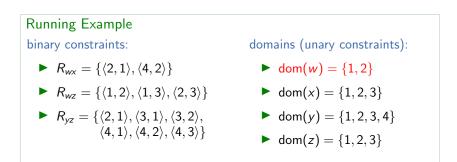
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Inference

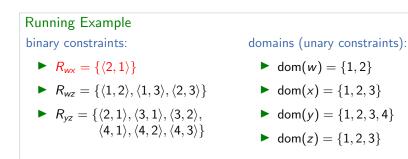
Inference Derive additional constraints (here: unary or binary) that are implied by the given constraints, i.e., that are satisfied in all solutions.



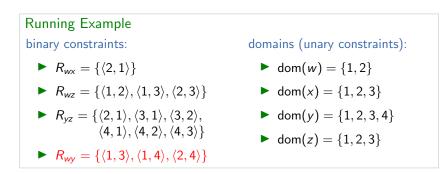
Can we use the constraint R_{wz} (w < z) to come up with a unary constraint R_w ?



Can we use the constraint R_{wz} (w < z) to come up with a unary constraint R_w ? \rightsquigarrow tighten domain with unary constraint (sometimes called node consistency)



How does this affect the binary constraint R_{WX} ?



Can we generate a "new" binary constraint from w < z and z < y? (i.e., tighten a trivial constraint)

Trade-Off Search vs. Inference

Inference formally For a given constraint network C, replace Cwith an equivalent, but tighter constraint network.

Trade-off:

- the more complex the inference, and
- the more often inference is applied,
- the smaller the resulting state space, but
- the higher the complexity per search node.

When to Apply Inference?

different possibilities to apply inference:

- once as preprocessing before search
- combined with search: before recursive calls during backtracking procedure
 - already assigned variable v → d corresponds to dom(v) = {d} → more inferences possible
 - during backtracking, derived constraints have to be retracted because they were based on the given assignment
 - \rightsquigarrow powerful, but possibly expensive

Backtracking with Inference

```
function BacktrackingWithInference(C, \alpha):
if \alpha is inconsistent with C:
       return inconsistent
if \alpha is a total assignment:
       return \alpha
\mathcal{C}' := \langle V, \operatorname{dom}', (R'_{uv}) \rangle := \operatorname{copy} \operatorname{of} \mathcal{C}
apply inference to \mathcal{C}'
if dom'(v) \neq \emptyset for all variables v:
       select some variable v for which \alpha is not defined
       for each d \in \text{copy of dom}'(v) in some order:
              \alpha' := \alpha \cup \{ \mathbf{v} \mapsto \mathbf{d} \}
              dom'(v) := \{d\}
              \alpha'' := \mathsf{BacktrackingWithInference}(\mathcal{C}', \alpha')
              if \alpha'' \neq \text{inconsistent}:
                      return \alpha''
return inconsistent
```

Backtracking with Inference: Discussion

- Inference is a placeholder: different inference methods can be applied.
- Inference methods can recognize unsolvability (given α) and indicate this by clearing the domain of a variable.
- ► Efficient implementations of inference are often incremental: the last assigned variable/value pair v → d is taken into account to speed up the inference computation.

D4.2 Forward Checking

Forward Checking

We start with a simple inference method:

Forward Checking Let α be a partial assignment. Inference: For all unassigned variables v in α , remove all values from the domain of v that are in conflict with already assigned variable/value pairs in α .

\rightsquigarrow definition of conflict as in the previous chapter

Incremental computation:

When adding v → d to the assignment, delete all pairs that conflict with v → d.

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Forward Checking: Example

Running ExampleRemoving values in conflict with $\alpha = \{w \mapsto 2\}$:binary constraints:domains: \triangleright $R_{wx} = \{\langle 2, 1 \rangle, \langle 4, 2 \rangle\}$ \blacktriangleright w is already assigned \triangleright $R_{wz} = \{\langle 1, 2 \rangle, \langle 1, 3 \rangle, \langle 2, 3 \rangle\}$ \flat dom $(x) = \{1, 2, 3\}$ \triangleright $R_{yz} = \{\langle 2, 1 \rangle, \langle 3, 1 \rangle, \langle 3, 2 \rangle, \\ \langle 4, 1 \rangle, \langle 4, 2 \rangle, \langle 4, 3 \rangle\}$ \flat dom $(y) = \{1, 2, 3, 4\}$ \flat dom $(z) = \{1, 2, 3\}$

Forward Checking: Example



Forward Checking: Discussion

properties of forward checking:

- correct inference method (retains equivalence)
- affects domains (= unary constraints), but not binary constraints
- consistency check at the beginning of the backtracking procedure no longer needed (Why?)
- cheap, but often still useful inference method
- \rightsquigarrow apply at least forward checking in the backtracking procedure

In the following, we will consider more powerful inference methods.

D4.3 Arc Consistency

Arc Consistency: Definition

Definition (Arc Consistent)
Let C = ⟨V, dom, (R_{uv})⟩ be a constraint network.
The variable v ∈ V is arc consistent with respect to another variable v' ∈ V, if for every value d ∈ dom(v) there exists a value d' ∈ dom(v') with ⟨d, d'⟩ ∈ R_{vv'}.
The constraint network C is arc consistent, if every variable v ∈ V is arc consistent with respect to every other variable v' ∈ V.

German: kantenkonsistent

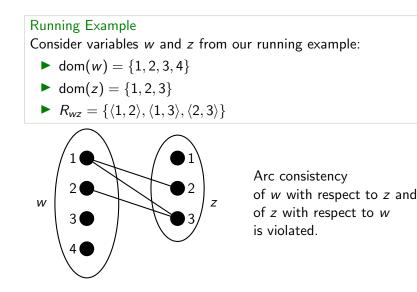
remarks:

- definition for variable pair is not symmetrical
- v always arc consistent with respect to v' if the constraint between v and v' is trivial

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Arc Consistency: Example



Enforcing Arc Consistency

- Enforcing arc consistency, i.e., removing values from dom(v) that violate the arc consistency of v with respect to v', is a correct inference method. (Why?)
- more powerful than forward checking (Why?)
 - Forward checking is a special case:
 enforcing arc consistency of all variables
 with respect to the just assigned variable
 corresponds to forward checking.
- We will next consider algorithms that enforce arc consistency.

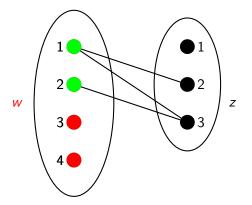
Processing Variable Pairs: revise

function revise(C, v, v'): $\langle V, \text{dom}, (R_{uv}) \rangle := C$ for each $d \in \text{dom}(v)$: if there is no $d' \in \text{dom}(v')$ with $\langle d, d' \rangle \in R_{vv'}$: remove d from dom(v)

input: constraint network C and two variables v, v' of Ceffect: v arc consistent with respect to v'. All violating values in dom(v) are removed. time complexity: $O(k^2)$, where k is maximal domain size D4. Constraint Satisfaction Problems: Arc Consistency

Arc Consistency

$revise(\mathcal{C}, w, z)$ in Running Example



Enforcing Arc Consistency: AC-1

```
function AC-1(C):

\langle V, \text{dom}, (R_{uv}) \rangle := C

repeat

for each nontrivial constraint R_{uv}:

revise(C, u, v)

revise(C, v, u)

until no domain has changed in this iteration
```

```
input: constraint network C
effect: transforms C into equivalent arc consistent network
time complexity: O(n \cdot e \cdot k^3), with n variables,
e nontrivial constraints and maximal domain size k
```

AC-1: Discussion

- AC-1 does the job, but is rather inefficient.
- Drawback: Variable pairs are often checked again and again although their domains have remained unchanged.
- These (redundant) checks can be saved.
- \rightsquigarrow more efficient algorithm: AC-3

Enforcing Arc Consistency: AC-3

idea: store potentially inconsistent variable pairs in a queue

```
function AC-3(C):
\langle V, \mathsf{dom}, (R_{\mu\nu}) \rangle := \mathcal{C}
queue := \emptyset
for each nontrivial constraint R_{\mu\nu}:
      insert \langle u, v \rangle into queue
      insert \langle v, u \rangle into queue
while queue \neq \emptyset:
       remove an arbitrary element \langle u, v \rangle from queue
      revise(\mathcal{C}, u, v)
      if dom(u) changed in the call to revise:
             for each w \in V \setminus \{u, v\} where R_{wu} is nontrivial:
                    insert \langle w, u \rangle into queue
```

AC-3: Discussion

- queue can be an arbitrary data structure that supports insert and remove operations (the order of removal does not affect the result)
- \rightsquigarrow use data structure with fast insertion and removal, e.g., stack
- AC-3 has the same effect as AC-1: it enforces arc consistency
- proof idea: invariant of the while loop: If ⟨u, v⟩ ∉ queue, then u is arc consistent with respect to v

AC-3: Time Complexity

Proposition (time complexity of AC-3)

Let C be a constraint network with e nontrivial constraints and maximal domain size k.

The time complexity of AC-3 is $O(e \cdot k^3)$.

AC-3: Time Complexity (Proof)

Proof.

Consider a pair $\langle u, v \rangle$ such that there exists a nontrivial constraint R_{uv} or R_{vu} . (There are at most 2*e* of such pairs.)

Every time this pair is inserted to the queue (except for the first time) the domain of the second variable has just been reduced.

This can happen at most k times.

Hence every pair $\langle u, v \rangle$ is inserted into the queue at most k + 1 times \rightsquigarrow at most O(ek) insert operations in total. This bounds the number of **while** iterations by O(ek), giving an overall time complexity of $O(ek) \cdot O(k^2) = O(ek^3)$.

D4.4 Summary

Summary: Inference

- inference: derivation of additional constraints that are implied by the known constraints
- vighter equivalent constraint network
- trade-off search vs. inference
- inference as preprocessing or integrated into backtracking

Summary: Forward Checking, Arc Consistency

- cheap and easy inference: forward checking
 - remove values that conflict with already assigned values
- more expensive and more powerful: arc consistency
 - iteratively remove values without a suitable "partner value" for another variable until fixed-point reached
 - efficient implementation of AC-3: O(ek³) with e: #nontrivial constraints, k: size of domain