

Foundations of Artificial Intelligence

A4. Introduction: Rational Agents

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Introduction: Overview

Chapter overview: introduction

- A1. Organizational Matters
- A2. What is Artificial Intelligence?
- A3. AI Past and Present
- A4. Rational Agents
- A5. Environments and Problem Solving Methods

Systematic AI Framework

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so far we have seen that:

- AI systems applied to wide variety of challenges



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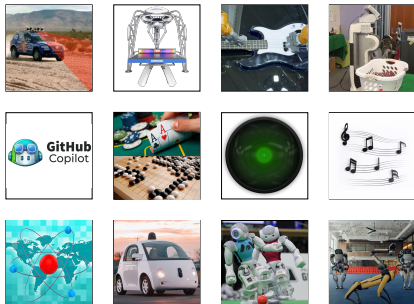
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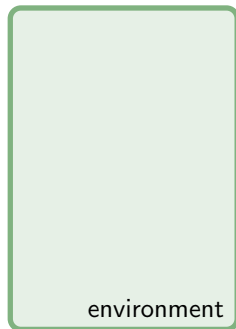
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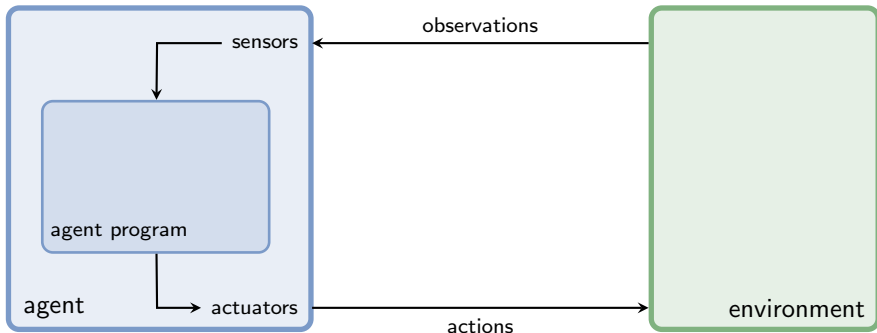
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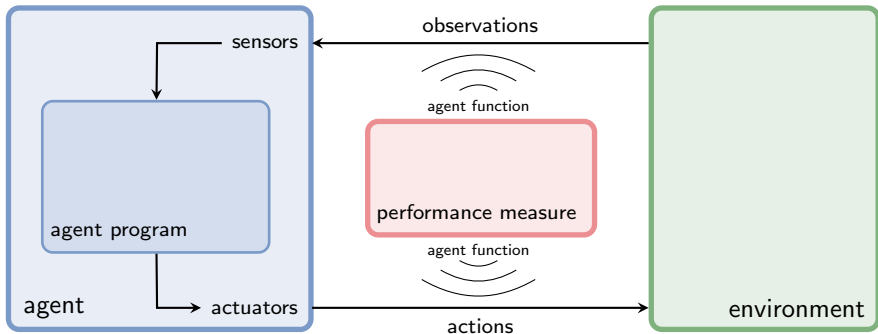
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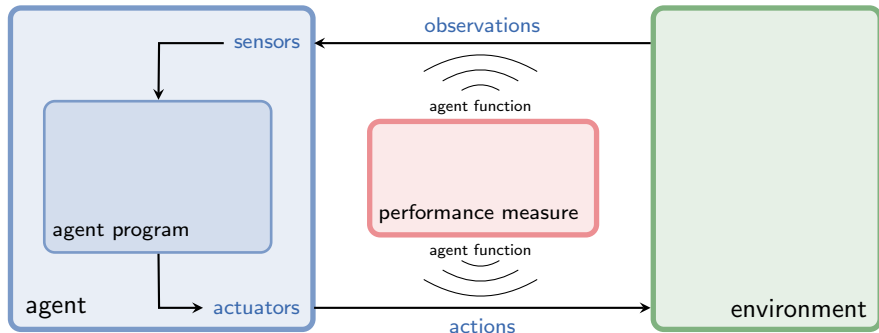
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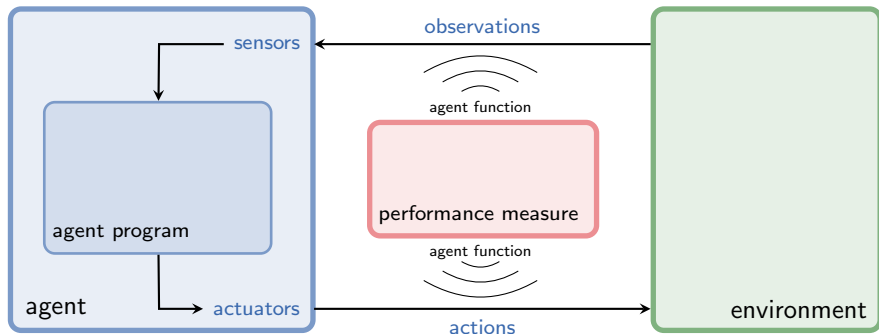
- captures this diversity of challenges
- includes an entity that acts in the environment
- determines if the agent acts rationally in the environment

Agent-Environment Interaction



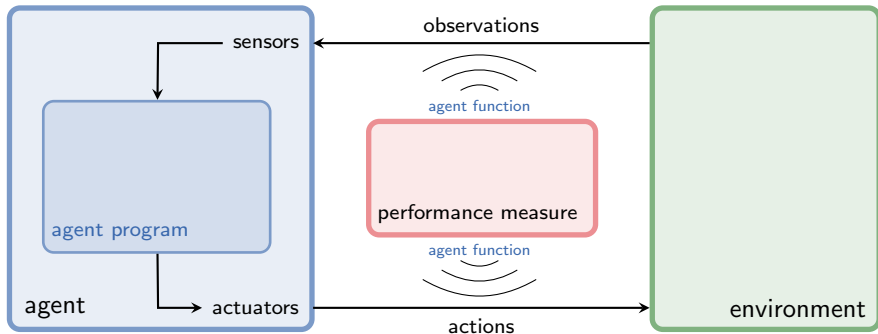
- **sensors**: physical entities that allow the agent to **observe**
- **observation**: data perceived by the agent's sensors
- **actuators**: physical entities that allow the agent to **act**
- **action**: abstract concept that affects the state of the environment

Agent-Environment Interaction



- **sensors** and **actuators** are not relevant for the course (↪ typically covered in courses on **robotics**)
- **observations** and **actions** describe the agent's capabilities (the **agent model**)

Formalizing an Agent's Behavior



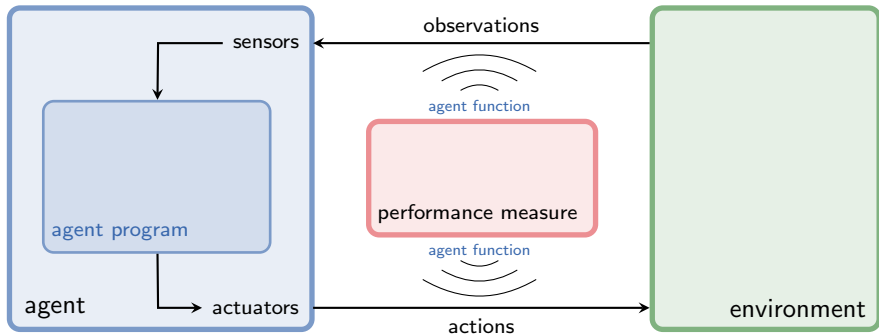
① as agent program:

- internal representation
- specifics possibly **unknown** to outside

② as agent function:

- external characterization

Formalizing an Agent's Behavior



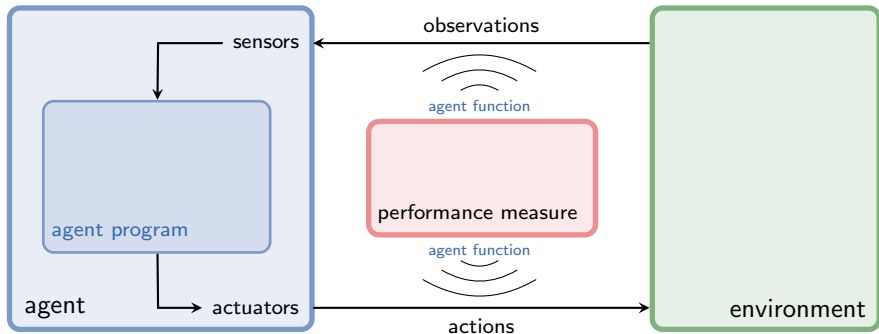
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Formalizing an Agent's Behavior



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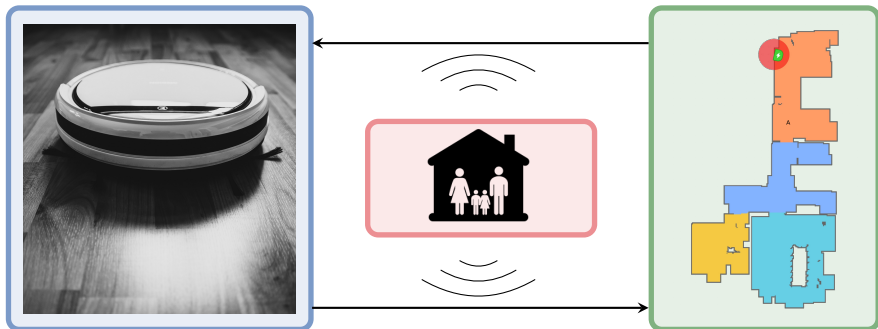
- internal representation
- specifics possibly **unknown** to outside
- takes **observation** as input
- outputs an **action**
- computed on physical machine (the **agent architecture**)

② as agent function:

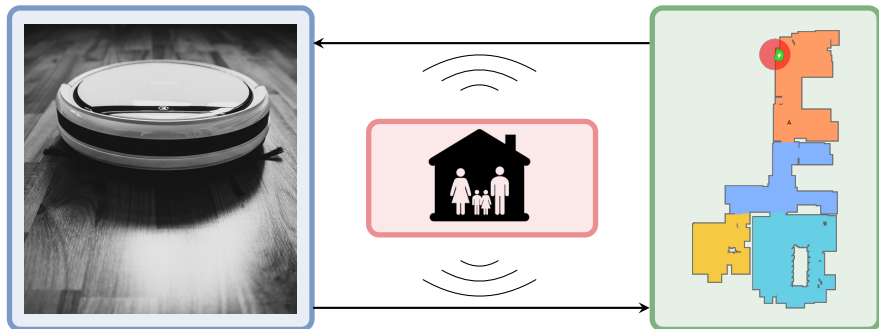
- external characterization
- maps **sequence of observations** to (probability distribution over) **actions**
- **abstract mathematical formalization**

Example

Vacuum Domain

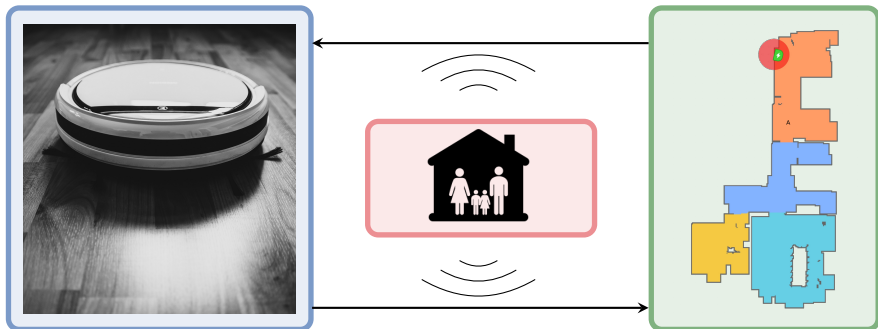


Vacuum Agent: Sensors and Actuators



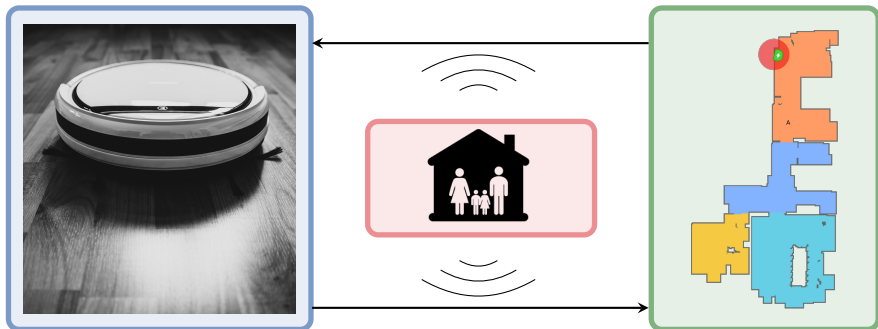
- **sensors:** cliff sensors, bump sensors, wall sensors, state of charge sensor, WiFi module
- **actuators:** wheels, cleaning system

Vacuum Agent: Observations and Actions



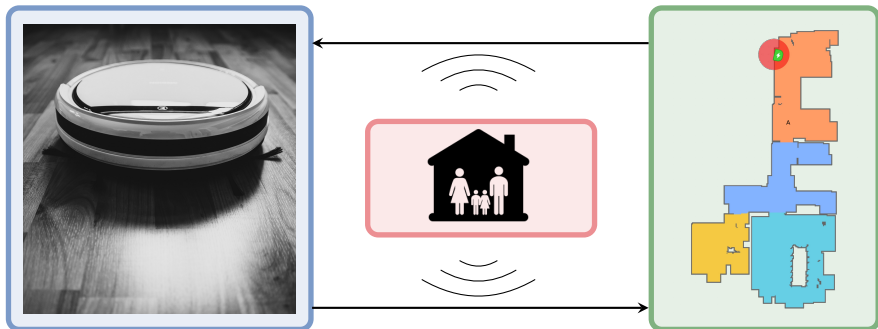
- **observations:** current location, dirt level of current room, presence of humans, battery charge
- **actions:** move-to-next-room, move-to-base, vacuum, wait

Vacuum Agent: Agent Program



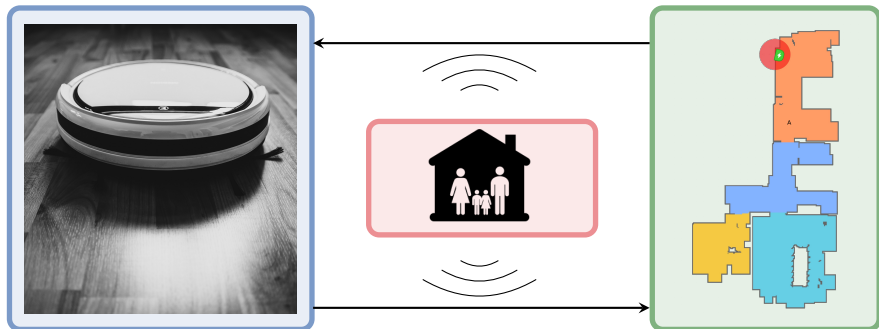
```
1 def vacuum-agent([location, dirt-level, owner-present, battery]):  
2   if battery ≤ 10%: return move-to-base  
3   else if owner-present = True: return move-to-next-room  
4   else if dirt-level = dirty: return vacuum  
5   else: return move-to-next-room
```

Vacuum Domain: Agent Function



observation sequence	action
$\langle [\text{blue, clean, False, 100\%}] \rangle$	<i>move-to-next-room</i>
$\langle [\text{blue, dirty, False, 100\%}] \rangle$	<i>vacuum</i>
$\langle [\text{blue, clean, True, 100\%}] \rangle$	<i>move-to-next-room</i>
...	...
$\langle [\text{blue, clean, False, 100\%}], [\text{blue, clean, False, 90\%}] \rangle$	<i>move-to-next-room</i>
$\langle [\text{blue, clean, False, 100\%}], [\text{blue, dirty, False, 90\%}] \rangle$	<i>vacuum</i>
...	...

Vacuum Domain: Performance Measure



potential influences on **performance measure**:

- dirt levels
- noise levels
- energy consumption
- safety

Rationality

Evaluating Agent Functions



What is the **right** agent function?

Rationality

rationality of an **agent** depends on **performance measure** (often: **utility**, **reward**, **cost**) and **environment**

Perfect Rationality

- for each possible **observation sequence**
- select an action which **maximizes**
- **expected value** of future performance
- given **available information** on **observation history**
- and **environment**

Perfect Rationality of Our Vacuum Agent

Is our vacuum agent **perfectly rational**?



Perfect Rationality of Our Vacuum Agent

Is our vacuum agent **perfectly rational**?



depends on performance measure and environment, e.g.:

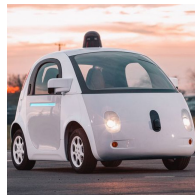
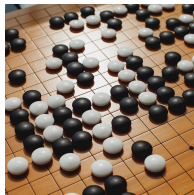
- Do actions reliably have the desired effect?
- Do we know the initial situation?
- Can new dirt be produced while the agent is acting?

Performance Measure

- specified by designer
- sometimes clear,
sometimes not so clear
- significant impact on
 - desired behavior
 - difficulty of problem

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Perfect Rationality of Our Vacuum Agent

consider **performance measure**:

- +1 utility for cleaning a dirty room

consider **environment**:

- actions and observations reliable
- world only changes through actions of the agent

our vacuum agent is **perfectly rational**

Perfect Rationality of Our Vacuum Agent

consider **performance measure**:

- -1 utility for each dirty room in each step

consider **environment**:

- actions and observations reliable
- world only changes through actions of the agent

our vacuum agent is **not perfectly rational**

Perfect Rationality of Our Vacuum Agent

consider **performance measure**:

- -1 utility for each dirty room in each step

consider **environment**:

- actions and observations reliable
- yellow room may spontaneously become dirty

our vacuum agent is **not perfectly rational**

Rationality: Discussion

- perfect rationality \neq omniscience
 - incomplete information (due to limited observations) reduces achievable utility
- perfect rationality \neq perfect prediction of future
 - uncertain behavior of environment (e.g., stochastic action effects) reduces achievable utility
- perfect rationality is rarely achievable
 - limited computational power \rightsquigarrow bounded rationality

Summary

Summary (1)

common metaphor for AI systems: **rational agents**

agent interacts with **environment**:

- sensors perceive **observations** about state of the environment
- actuators perform **actions** modifying the environment
- formally: **agent function** maps observation sequences to actions

Summary (2)

rational agents:

- try to maximize performance measure (utility)
- perfect rationality: achieve maximal utility in expectation given available information
- for “interesting” problems rarely achievable
 ↪ bounded rationality