

# Foundations of Artificial Intelligence

## A3. Introduction: AI Past and Present

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# Introduction: Overview

## Chapter overview: introduction

- A1. Organizational Matters
- A2. What is Artificial Intelligence?
- A3. AI Past and Present
- A4. Rational Agents
- A5. Environments and Problem Solving Methods

# A Short History of AI

## Precursors (Until ca. 1943)

1950

1960

1970

1980

1990

2000

...

Philosophy and mathematics ask similar questions that influence AI.

- Aristotle (384–322 BC)
- Leibniz (1646–1716)
- Hilbert program (1920s)



## Gestation (1943–1956)

1950

1960

1970

1980

1990

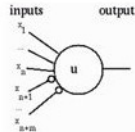
2000

...

Invention of electrical computers raised question:  
Can computers mimic the human mind?

# Gestation (1943–1956)

## Artificial Neurons



1950

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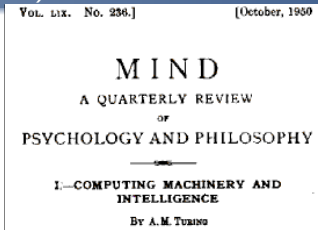
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W. McCulloch & W. Pitts (1943)

- first computational model of **artificial neuron**
- **network of neurons** can compute any computable function
- basis of **deep learning**

## Gestation (1943–1956)

Artificial  
Neurons



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Turing Test

Computing Machinery and Intelligence (A. Turing, 1950)

- famous for introducing **Turing test**
- (still) relevant discussion of **AI potential** and **requirements**
- suggests core AI aspects: **knowledge representation**, **reasoning**, **language understanding**, **learning**

# Gestation (1943–1956)

## Artificial Neurons

Dartmouth

1950

1960

1970

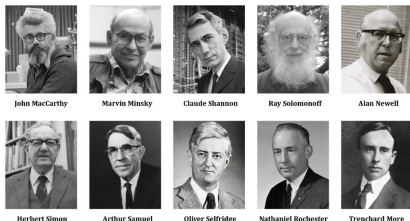
1980

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2000

...

Turing Test

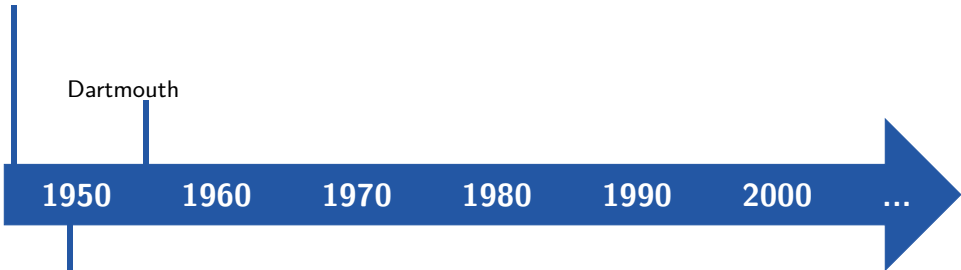


### Dartmouth workshop (1956)

- ambitious proposal: “An attempt will be made to find how to make machines use language, [...] solve kinds of problems now reserved for humans, and improve themselves.”
- J. McCarthy coins term **artificial intelligence**

# Early Enthusiasm (1952–1969)

Artificial  
Neurons



Dartmouth

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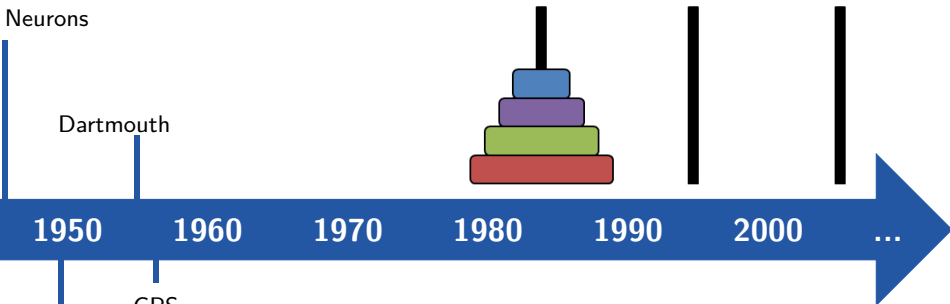
Turing Test

early enthusiasm (H. Simon, 1957):

“[...] there are now in the world machines that think, that learn and that create. Moreover, their ability to do these things is going to increase rapidly until – in the visible future – the range of problems they can handle will be coextensive with the range to which the human mind has been applied.”

# Early Enthusiasm (1952–1969)

Artificial  
Neurons



**General Problem Solver** (H. Simon & A. Newell, 1957)

- universal problem solving machine
- imitates human problem solving strategies
- in principle able to solve every formalized symbolic problem
- in practice, GPS solves simple tasks like towers of Hanoi

# Early Enthusiasm (1952–1969)

Artificial  
Neurons

RL for  
Checkers

Dartmouth



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Turing Test

GPS

Checkers AI (A. Samuel, 1959)

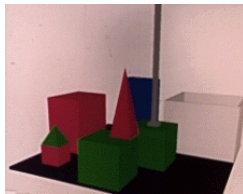
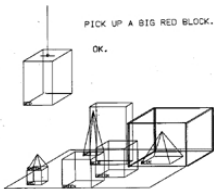
- popularized term **machine learning**
- learned to play at strong amateur level
- uses ideas of **reinforcement learning**

# Early Enthusiasm (1952–1969)

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Turing Test

GPS

Microworlds

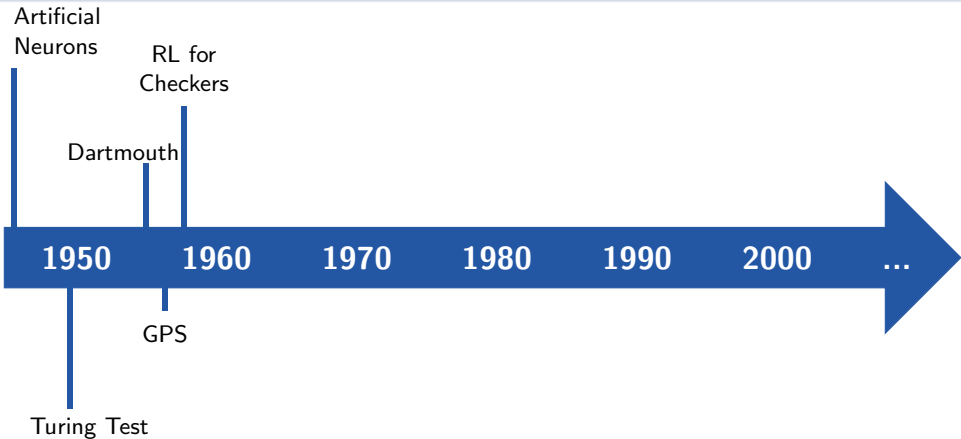
intelligence in **microworlds**, e.g. **SHRDLU** (T. Winograd, 1968)

- understands natural language
- communicates with user via teletype on **blocks world**
- graphical representation

↪ <https://hci.stanford.edu/winograd/shrdlu/>



# Early Enthusiasm (1952–1969)



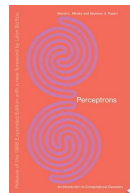
# A Dose of Reality (1966–1973)

Artificial  
Neurons

RL for  
Checkers

Dartmouth

Limitations



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Turing Test

GPS

Microworlds

- realization that unlimited computational power is illusion (birth of complexity theory, NP-completeness)
- AI systems (e.g., GPS, systems for micro worlds) *fail to scale*
- fundamental **limitations on basic structures** e.g., XOR problem of perceptrons

# Expert Systems (1969–1986)

Artificial  
Neurons

RL for  
Checkers

Dartmouth

Limitations

DISTRIBUTE-MB-DEVICES-3

```
IF:  the most current active context is distributing massbus devices
&   there is a single port disk drive that has not been assigned to a massbus
&   there are no unassigned dual port disk drives
&   the number of devices that each massbus should support is known
&   there is a massbus that has been assigned at least one disk drive and that should support additional
    disk drives
&   the type of cable needed to connect the disk drive to the previous device on the disk drive is known
THEN: assign the disk drive to the massbus
```

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GPS

Microworlds

Expert  
Systems

Turing Test

1980s: AI gold rush

- rule-based **expert systems** commercially successful
- (human) **expert knowledge** as input
- allows automatic reasoning on **larger problems** in **narrower applications**
- also: second heyday of **neural networks**

# Expert Systems (1969–1986)

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Expert  
Systems

example: R1/XCON (J. McDermott, 1978)

- **input:** desired properties of a VAX computer system according to customer specifications
- **output:** specification of the computer system
- **inference engine:** simple forward chaining of rules

# Expert Systems (1969–1986)

Artificial  
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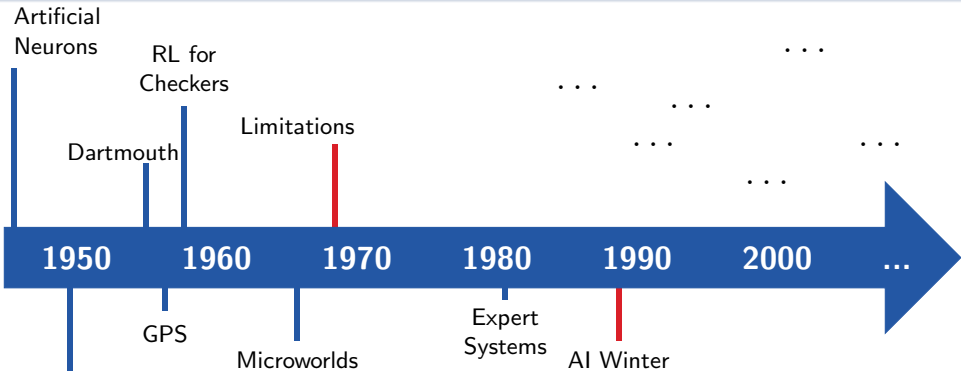
AI Winter

Turing Test

end of 1980s: AI Winter

- companies failed to deliver promises
- expert systems difficult to maintain
- expert systems susceptible to uncertainty

# Coming of Age (1990s and 2000s)



- advent of **probabilistic methods**
- **formalization** of AI techniques
- better understanding of **theoretical complexity**
- increased use of **mathematical methods**
- exploitation of large data sets (**big data**)

# Broad Visibility in Society (Since 2010s)

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Neurons

RL for  
Checkers

Dartmouth

Limitations



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Microworlds

Expert  
Systems

AI Winter

well known systems and famous breakthroughs, e.g.,

- broadly used systems (e.g., virtual assistants)
- AI systems act in real-world (e.g., self-driving cars)
- systems outperform humans in hard tasks (e.g., AlphaGo)
- AI and human-written text hard to distinguish (ChatGPT)

# Where are We Today?



# AI Approaching Maturity

## Russell & Norvig (1995)

Gentle revolutions have occurred in robotics, computer vision, machine learning, and knowledge representation.

A better understanding of the problems and their complexity properties, combined with increased mathematical sophistication, has led to workable research agendas and robust methods.

# Where are We Today?



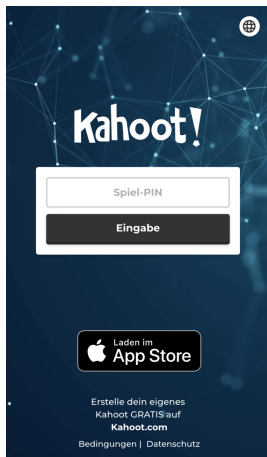
- many coexisting paradigms
  - reactive vs. deliberative
  - data-driven vs. model-driven
  - often hybrid approaches
- many methods, often borrowing from other research areas
  - logic, decision theory, statistics, ...
- different approaches
  - theoretical
  - algorithmic/experimental
  - application-oriented

# Focus on Algorithms and Experiments

Many AI problems are inherently difficult (NP-hard), but strong search techniques and heuristics often solve large problem instances regardless:

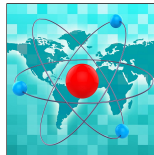
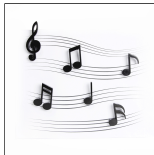
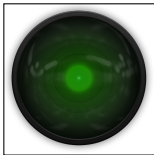
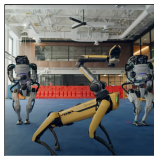
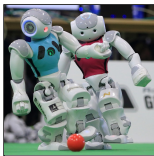
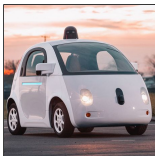
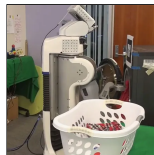
- **satisfiability in propositional logic**
  - 10,000 propositional variables or more via **conflict-directed clause learning**
- **constraint solvers**
  - good scalability via **constraint propagation** and automatic exploitation of **problem structure**
- **action planning**
  - $10^{100}$  search states and more by search using **automatically inferred heuristics**

# What Can AI Do Today?



<https://kahoot.it/>

# What Can AI Do Today? – Videos, Articles and AIs



# What Can AI Do Today?

results of our classroom poll:

- ✓ successfully complete an off-road car race
- ✗ beat a world champion table tennis player
- ✓ play guitar in a robot band
- ✓ do and fold the laundry
- ✓ drive safely in downtown Basel
- ✗ win a football match against a human team
- ✓ dance synchronously in a group of robots
- ✓ write code on the level of a CS student
- ✓ beat a world champion Chess, Go or Poker player
- ✓ create inspiring quotes
- ✓ compose music
- ✓ engage in a scientific conversation

# Summary

# Summary

- 1950s/1960s: beginnings of AI; early enthusiasm
- 1970s: micro worlds and knowledge-based systems
- 1980s: gold rush of expert systems followed by “AI winter”
- 1990s/2000s: AI comes of age; research becomes more rigorous and mathematical; mature methods
- 2010s: AI systems enter mainstream