Algorithms and Data Structures C3. Disjoint-set Data Structure/Union-Find

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Algorithms and Data Structures

May 7, 2025 — C3. Disjoint-set Data Structure/Union-Find

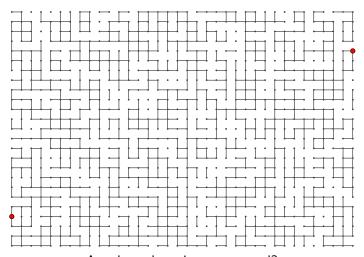
C3.1 Union-Find

C3.2 Connected Components and Equivalence Classes

C3.3 Summary

C3.1 Union-Find

Questions



Are the red vertices connected? How many connected components does the graph have?

Connected Components as Disjoint Sets

Set of conn. components as collection of disjoint sets of objects.

- One set for all vertices of one connected component.
- Operations:
 - Union: Given two objects, merge the sets that contain them into one.
 - Introduce a new edge between the given vertices, connecting their connected components.
 - Find: Given an object, return a representative of the set that contains it.
 - Given a vertex, return a representative vertex for its connected component.
 - Must return the same representative for all objects in the set.
 - ▶ The representative may only change if set gets merged.
 - Two objects are in the same set (two vertices are connected) if find returns the same representative for them.
 - ► Count: Return the number of sets
 Return the number of connected components.

Union-Find Data Type

```
class UnionFind:
1
       # Initialization for n objects (with names 0, \ldots, n-1).
2
      def __init__(n: int) -> None
3
4
       # Merge the sets containing objects v and w.
5
      def union(v: int, w: int) -> None
6
       # Representative for set containing v.
8
       # May change if set is merged by call of union,
9
10
       # but not otherwise.
      def find(v: int) -> int
11
12
       # Number of sets.
13
      def count() -> int
14
```

(Somewhat) Naive Algorithm: Quick-Find

- For *n* objects: Array representative of length *n*.
- \triangleright Entry at position i is representative of the set containing i.
- Initially, every object is (alone) in its own set, and thus its representative.
- Update the array in every call of union.

Quick-Find Data Structure

```
1 class QuickFind:
       def __init__(self, no_nodes):
2
           self.components = no_nodes
3
           self.representative = list(range(no_nodes))
4
5
       def count(self):
6
                                           [0, 1, ..., no_nodes-1]
           return self.components
7
8
       def find(self, v):
9
           return self.representative[v]
10
```

Quick-Find Data Structure (Continued)

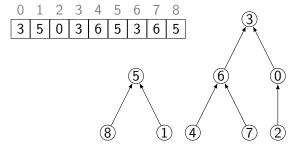
```
def union(self, v, w):
20
          repr_v = self.find(v)
21
          repr_w = self.find(w)
22
           if repr_v == repr_w: # already in same component
23
               return
24
           # replace all occurrences of repr_v in
25
           # self.representative with repr_w
26
          for i in range(len(self.representative)):
27
               if self.representative[i] == repr_v:
28
                   self.representative[i] = repr_w
29
           self.components -= 1 # we merged two components
30
```

Running time?

- ► Cost model = number of array accesses
- one access for every call of find
- between n + 3 and 2n + 1 accesses for every call of union that merges two components

Better: Quick-Union aka Disjoint-set Forest

- (implicit) tree for representing each set
- represented as array with parent nodes as entries (root: reference to itself)



Root node serves as representative of the set.

Quick-Union Data Structure

```
1 class QuickUnion:
      def __init__(self, no_nodes):
2
           self.parent = list(range(no_nodes))
3
           self.components = no_nodes
4
5
      def find(self, v):
6
           while self.parent[v] != v:
7
               v = self.parent[v]
8
           return v
9
10
      def union(self, v, w):
11
           repr_v = self.find(v)
12
           repr_w = self.find(w)
13
           if repr_v == repr_w: # already in same component
14
               return
15
           self.parent[repr_v] = repr_w
16
           self.components -= 1
17
18
       # count as in QuickFind
19
```

First Improvement

- ▶ Problem with Quick-Union: Trees can degenerate into chains.
 - \rightarrow find requires linear time in the size of the set.
- ▶ Idea: In union the root of the tree with lower height becomes a child of the root of the higher tree.

Ranked Quick-Union Algorithm

```
1 class RankedQuickUnion:
       def init (self. no nodes):
2
           self.parent = list(range(no_nodes))
3
           self.components = no_nodes
4
           self.rank = [0] * no_nodes # [0, ..., 0]
5
6
       def union(self, v, w):
7
           repr_v = self.find(v)
8
           repr_w = self.find(w)
9
10
           if repr_v == repr_w:
11
               return
           if self.rank[repr_w] < self.rank[repr_v]:</pre>
12
               self.parent[repr_w] = repr_v
13
14
           else:
               self.parent[repr_v] = repr_w
15
16
               if self.rank[repr_v] == self.rank[repr_w]:
                    self.rank[repr_w] += 1
17
           self.components -= 1
18
19
       # connected, count and find as in QuickUnion
20
```

Second Improvement

Path Compression

- Idea: During find, reconnect all traversed nodes to the root.
- We do not update the height of the tree during path compression.
 - Value of rank can deviate from the actual height.
 - That's why it is called rank and not height.

Ranked Quick-Union Algorithm with Path Compression

```
1 class RankedQuickUnionWithPathCompression:
      def __init__(self, no_nodes):
2
           self.parent = list(range(no_nodes))
3
           self.components = no_nodes
4
           self.rank = [0] * no_nodes # [0, ..., 0]
5
6
7
      def find(self, v):
           if self.parent[v] == v:
8
9
               return v
           root = self.find(self.parent[v])
10
           self.parent[v] = root
11
           return root
12
13
       # connected, count and union as in RankedQuickUnion
14
```

Discussion

- With all improvements, we achieve almost constant amortized cost for all operations.
- ► More precisely: [Tarjan 1975]
 - ▶ m calls of find for n objects (and at most n-1 calls of union, merging two components)
 - $ightharpoonup O(m\alpha(m,n))$ array accesses
 - \triangleright α is inverse of a variant of the Ackermann function
 - In practise is $\alpha(m, n) \leq 3$.
- Nevertheless: there cannot be a union-find structure that guarantees linear running time.
 - (under cell-probe model, only accounting for memory access)

Comparison to Exploration-based Approach

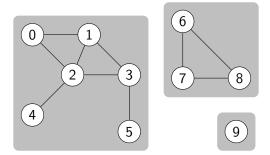
- Chapter C2: Algorithm ConnectedComponents, based on graph exploration.
- After the precomputation, queries only require constant time.
- In practise, disjoint-set forests are often faster, because for many applications, we do not have to build up the full graph.
- ▶ If the graph has already been built up, graph exploration can be better.
- Another advantage of union find:
 - Online approach
 - ► We can easily introduce further edges.

C3.2 Connected Components and Equivalence Classes

Reminder: Connected Components

Undirected graph

Two vertices u and v are in the same connected component if there is a path between u and v (= vertices u and v are connected).



Connected Components: Properties

- ► The connected components define a partition of the vertices:
 - Every vertex is in a connected component.
 - ▶ No vertex is in more than one connected component.
- "is connected with" is an equivalence relation.
 - reflexive: Every vertex is connected with itself.
 - **symmetric:** If *u* is connected with *v*, then *v* is connected with *u*.
 - transitive: If u is connected with v, and v with w, then u is connected with w.

Partition in General

Definition (Partition)

A partition of a finite set M is a set P of non-empty subsets of M, such that

- every element of M is in some set in P: $\bigcup_{S \in P} S = M$, and
- ▶ that sets in P are pairwise disjoint: $S \cap S' = \emptyset$ for $S, S' \in P$ with $S \neq S'$.

The sets in *P* are called blocks.

$$M = \{e_1, \ldots, e_5\}$$

- $ightharpoonup P_1 = \{\{e_1, e_4\}, \{e_3\}, \{e_2, e_5\}\}\$ is a partition of M.
- $ightharpoonup P_2 = \{\{e_1, e_4, e_5\}, \{e_3\}\}\$ is not a partition of M.
- $ightharpoonup P_3 = \{\{e_1, e_4, e_5\}, \{e_3\}, \{e_2, e_5\}\}$ is not a partition of M.
- $ightharpoonup P_4 = \{\{e_1\}, \{e_2\}, \{e_3\}, \{e_4\}, \{e_5\}\}\$ is a partition of M.

Equivalence Relations in General

Definition (Equivalence Relation)

An equivalence relation over set M is a symmetric, transitive and reflexive relation $R \subseteq M \times M$.

We write $a \sim b$ for $(a, b) \in R$ and say that a is equivalent to b.

- **>** symmetric: $a \sim b$ implies $b \sim a$
- **transitive**: $a \sim b$ and $b \sim c$ implies $a \sim c$
- reflexive: for all $e \in M$: $e \sim e$

Equivalence Classes

Definition (Equivalence Classes)

Let R be an equivalence relation over M.

The equivalence class of $a \in M$ is the set

$$[a] = \{b \in M \mid a \sim b\}.$$

- ► The set of all equivalence classes is a partition of *M*.
- Vice versa: For partition P define $R = \{(x,y) \mid \exists B \in P : x,y \in B\}$ (i.e. $x \sim y$ if and only if x and y are in the same block). Then R is an equivalence relation.
- ► We can consider blocks in partitions as equivalence classes and vice versa.

Union-Find and Equivalences

- ► Given: finite set M, sequence s of equivalences $a \sim b$ over M
- Consider equivalences as edges in a graph with set M of vertices.
- ► The connected components correspond to the equivalence classes of the finest equivalence relation that considers all equivalences from s.
 - no "unnecessary" equivalences.

Can use union-find data structures to determine equivalence classes.

C3.3 Summary

Summary

- A union-find data structure maintains a collection of disjoint sets.
 - union: merge two sets.
 - find: identify the set containing an object and return its representative.
- Good implementation: Disjoint-set forest with improvements to keep the height of the trees low:
 - Union adjoins the shorter tree to the taller tree.
 - Find reconnects traversed nodes to the root (path compression).
- ► Applications:
 - Connected components
 - Finest equivalence relation