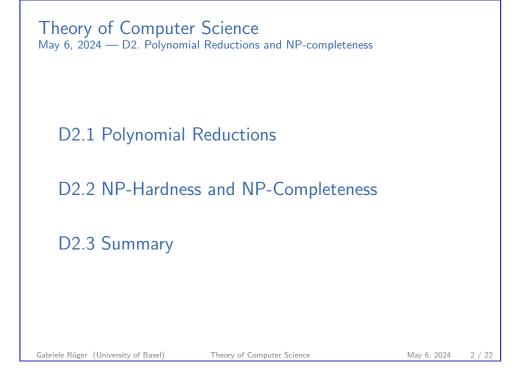
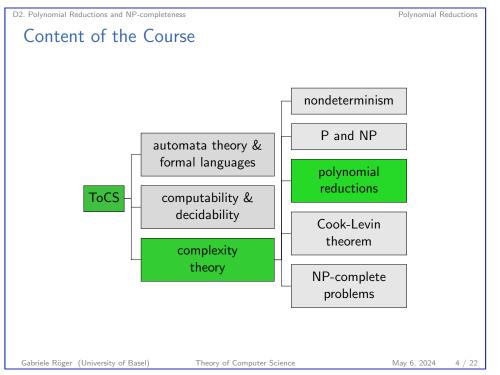


D2. Polynomial Reductions and NP-completeness

Polynomial Reductions

D2.1 Polynomial Reductions





D2. Polynomial Reductions and NP-completeness

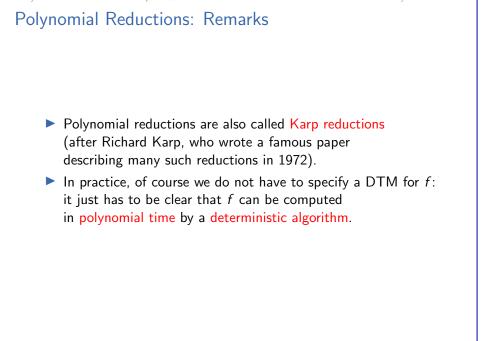
Polynomial Reductions: Idea

- The basic idea is that we solve a new problem by reducing it to a known problem.
- In complexity theory we want to use reductions that allow us to prove statements of the following kind: Problem A can be solved efficiently if problem B can be solved efficiently.
- For this, we need a reduction from A to B that can be computed efficiently itself (otherwise it would be useless for efficiently solving A).

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Polynomial Reductions

Definition (Polynomial Reduction) Let $A \subseteq \Sigma^*$ and $B \subseteq \Gamma^*$ be decision problems. We say that A can be polynomially reduced to B, written $A \leq_p B$, if there is a function $f : \Sigma^* \to \Gamma^*$ such that: • f can be computed in polynomial time by a DTM • i.e., there is a polynomial p and a DTM M such that Mcomputes f(w) in at most p(|w|) steps given input $w \in \Sigma^*$ • f reduces A to B• i.e., for all $w \in \Sigma^*$: $w \in A$ iff $f(w) \in B$ f is called a polynomial reduction from A to B

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Polynomial Reductions: Example (1)

Definition (HAMILTONCYCLE)

HAMILTONCYCLE is the following decision problem:

- Given: undirected graph $G = \langle V, E \rangle$
- Question: Does G contain a Hamilton cycle?

Reminder:

Definition (Hamilton Cycle)

A Hamilton cycle of G is a sequence of vertices in V,

- $\pi = \langle v_0, \ldots, v_n \rangle$, with the following properties:
- ▶ π is a path: there is an edge from v_i to v_{i+1} for all $0 \le i < n$

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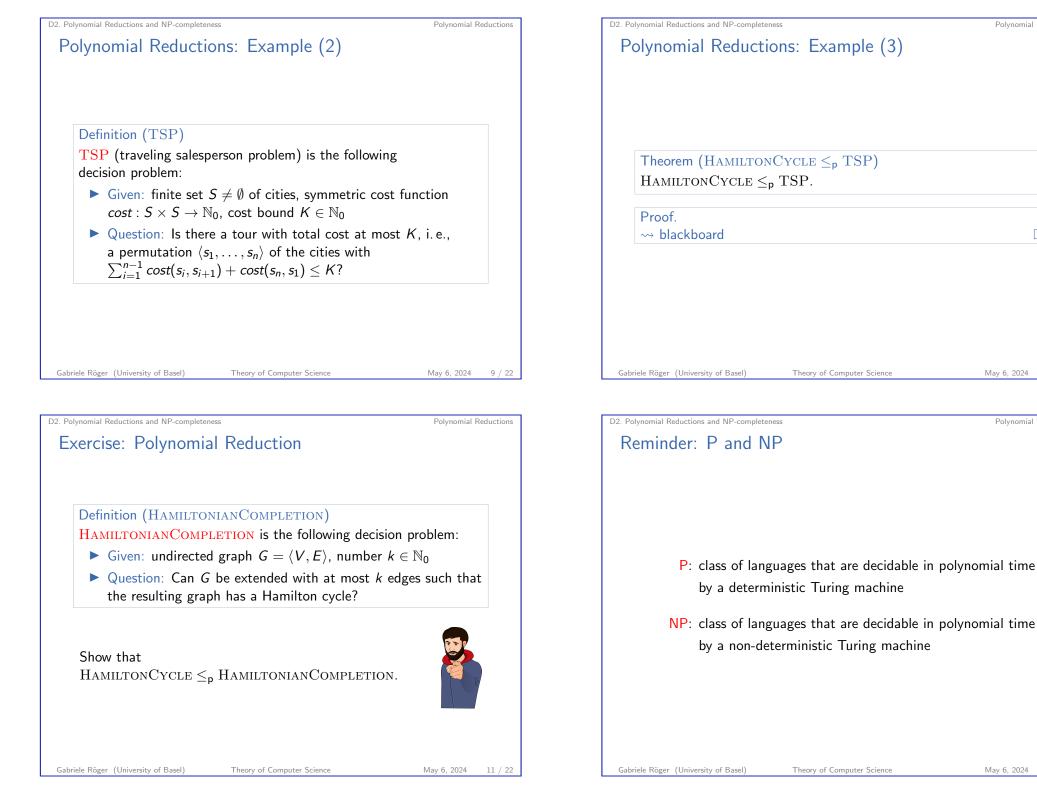
- $\blacktriangleright \pi$ is a cycle: $v_0 = v_n$
- ▶ π is simple: $v_i \neq v_j$ for all $i \neq j$ with i, j < n
- $\blacktriangleright \pi$ is Hamiltonian: all nodes of V are included in π

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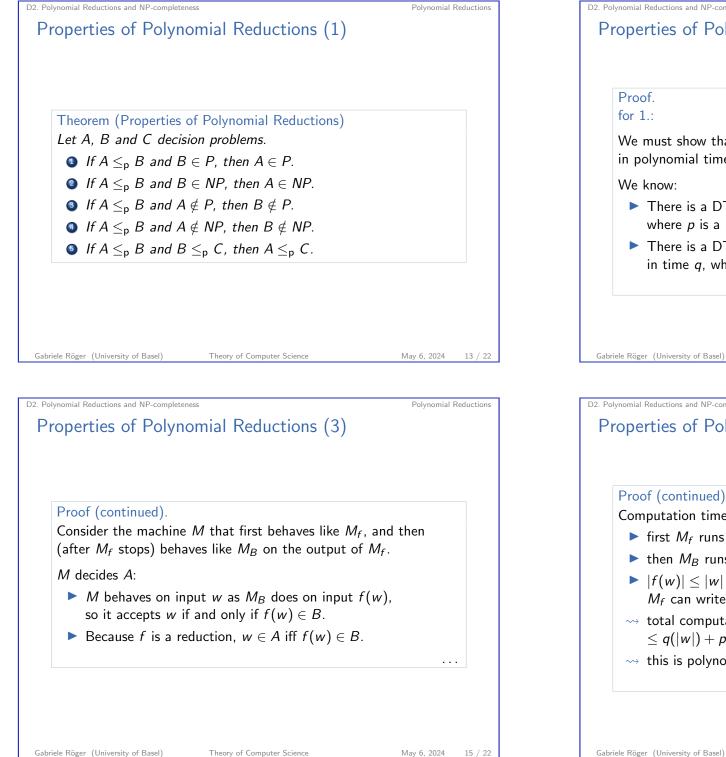


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Properties of Polynomial Reductions (2)

Proof.

for 1.:

We must show that there is a DTM deciding Ain polynomial time.

We know:

- ▶ There is a DTM M_B that decides B in time p, where p is a polynomial.
- **•** There is a DTM M_f that computes a reduction from A to B in time q, where q is a polynomial.

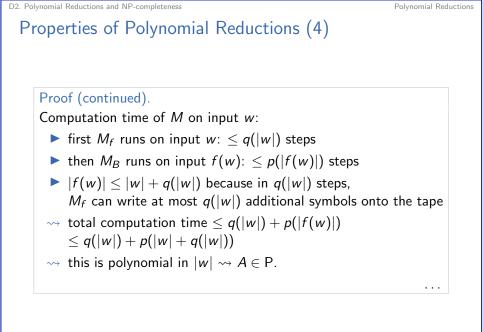
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Properties of Polynomial Reductions (5)

Proof (continued).

for 2.: analogous to 1., only that M_B and M are NTMs

of 3.+4.:

equivalent formulations of 1.+2. (contraposition)

of 5.:

Let $A \leq_{p} B$ with reduction f and $B \leq_{p} C$ with reduction g. Then $g \circ f$ is a reduction of A to C.

The computation time of the two computations in sequence is polynomial by the same argument used in the proof for 1.

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NP-Hardness and NP-Completeness

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NP-Hardness and NP-Completeness

Definition (NP-Hard, NP-Complete)

Let B be a decision problem.

B is called NP-hard if $A \leq_p B$ for all problems $A \in NP$.

B is called NP-complete if $B \in NP$ and *B* is NP-hard.

D2.2 NP-Hardness and NP-Completeness	

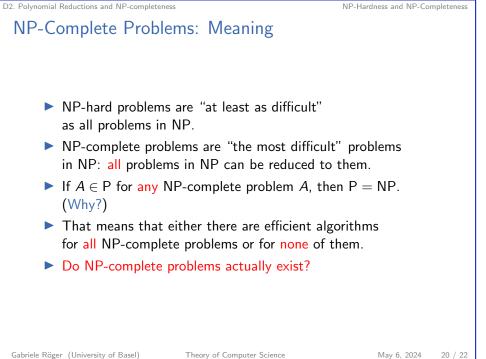
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