Foundations of Artificial Intelligence E4. Propositional Logic: DPLL Algorithm

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DPLL on Horn Formulas

Summary 00

Propositional Logic: Overview

Chapter overview: propositional logic

- E1. Syntax and Semantics
- E2. Equivalence and Normal Forms
- E3. Reasoning and Resolution
- E4. DPLL Algorithm
- E5. Local Search and Outlook

Systematic Search: DPL

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Motivation

Propositional Logic: Motivation

- Propositional logic allows for the representation of knowledge and for deriving conclusions based on this knowledge.
- many practical applications can be directly encoded, e.g.
 - constraint satisfaction problems of all kinds
 - circuit design and verification
- many problems contain logic as ingredient, e.g.
 - automated planning
 - general game playing
 - description logic queries (semantic web)

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Propositional Logic: Algorithmic Problems

main problems:

- reasoning (Φ ⊨ φ?):
 Does the formula φ logically follow from the formulas Φ?
- equivalence ($\varphi \equiv \psi$):

Are the formulas φ and ψ logically equivalent?

• satisfiability (SAT):

Is formula φ satisfiable? If yes, find a model.

German: Schlussfolgern, Äquivalenz, Erfüllbarkeit

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The Satisfiability Problem

The Satisfiability Problem (SAT)

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given:
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propositional formula in conjunctive normal form (CNF)

usually represented as pair $\langle V, \Delta \rangle$:

- V set of propositional variables (propositions)
- ∆ set of clauses over V
 (clause = set of literals v or ¬v with v ∈ V)

find:

- satisfying interpretation (model)
- or proof that no model exists

SAT is a famous NP-complete problem (Cook 1971; Levin 1973).

Relevance of SAT

- The name "SAT" is often used for the satisfiability problem for general propositional formulas (instead of restriction to CNF).
- General SAT can be reduced to CNF case in linear time.
- All previously mentioned problems can be reduced to SAT or its complement UNSAT (is a given CNF formula unsatisfiable?) in linear time.
- $\rightsquigarrow\,$ SAT algorithms important and intensively studied

this and next chapter: SAT algorithms

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SAT vs. CSP

SAT can be considered a constraint satisfaction problem:

- CSP variables = propositions
- domains = $\{\mathbf{F}, \mathbf{T}\}$
- constraints = clauses

However, we often have constraints that affect > 2 variables.

Due to this relationship, all ideas for CSPs are applicable to SAT:

- search
- inference
- variable and value orders

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The DPLL Algorithm

The DPLL algorithm (Davis/Putnam/Logemann/Loveland) corresponds to backtracking with inference for CSPs.

- recursive call DPLL(Δ, I)
 for clause set Δ and partial interpretation I
- result is a model of Δ that extends *I*; unsatisfiable if no such model exists
- first call $DPLL(\Delta, \emptyset)$

inference in DPLL:

- simplify: after assigning value d to variable v, simplify all clauses that contain v
 forward checking (for constraints of arbitrary arity)
- unit propagation: variables that occur in clauses without other variables (unit clauses) are assigned immediately
 minimum remaining values variable order

splitting rule

The DPLL Algorithm: Pseudo-Code

function DPLL(Δ , *I*): if $\bot \in \Delta$: [empty clause exists ↔ unsatisfiable] return unsatisfiable else if $\Delta = \emptyset$: [no clauses left \rightarrow interpretation I satisfies formula] return / else if there exists a unit clause $\{v\}$ or $\{\neg v\}$ in Δ : [unit propagation] Let v be such a variable, d the truth value that satisfies the clause. $\Delta' := \operatorname{simplify}(\Delta, v, d)$ return DPLL($\Delta', I \cup \{v \mapsto d\}$) else: Select some variable v which occurs in Δ . for each $d \in \{F, T\}$ in some order: $\Delta' := \operatorname{simplify}(\Delta, v, d)$ $I' := \mathsf{DPLL}(\Delta', I \cup \{v \mapsto d\})$ if $I' \neq$ unsatisfiable return /' return unsatisfiable

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Summary

The DPLL Algorithm: simplify

function simplify(Δ , v, d)

Let ℓ be the literal for v that is satisfied by $v \mapsto d$. $\Delta' := \{C \mid C \in \Delta \text{ such that } \ell \notin C\}$ $\Delta'' := \{C \setminus \{\overline{\ell}\} \mid C \in \Delta'\}$ return Δ''

- Remove clauses containing ℓ

 → clause is satisfied by v → d
- Remove *ℓ* from remaining clauses
 → clause has to be satisfied with another variable

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Example (1)

$\Delta = \{\{X, Y, \neg Z\}, \{\neg X, \neg Y\}, \{Z\}, \{X, \neg Y\}\}$

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Example (1)

$$\Delta = \{\{X, Y, \neg Z\}, \{\neg X, \neg Y\}, \{Z\}, \{X, \neg Y\}\}$$

• unit propagation: $Z \mapsto \mathbf{T}$

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Example (1)

$$\Delta = \{\{X, Y, \neg Z\}, \{\neg X, \neg Y\}, \{Z\}, \{X, \neg Y\}\}$$

• unit propagation: $Z \mapsto \mathbf{T}$ $\{\{X, Y\}, \{\neg X, \neg Y\}, \{X, \neg Y\}\}$

Example (1)

$$\Delta = \{\{X, Y, \neg Z\}, \{\neg X, \neg Y\}, \{Z\}, \{X, \neg Y\}\}$$

- unit propagation: $Z \mapsto \mathbf{T}$ $\{\{X, Y\}, \{\neg X, \neg Y\}, \{X, \neg Y\}\}$
- splitting rule:

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Example (1)

$$\Delta = \{\{X, Y, \neg Z\}, \{\neg X, \neg Y\}, \{Z\}, \{X, \neg Y\}\}$$

- unit propagation: $Z \mapsto \mathbf{T}$ $\{\{X, Y\}, \{\neg X, \neg Y\}, \{X, \neg Y\}\}$
- splitting rule:

2a. $X \mapsto \mathbf{F}$ $\{\{Y\}, \{\neg Y\}\}$

Example (1)

$$\Delta = \{\{X, Y, \neg Z\}, \{\neg X, \neg Y\}, \{Z\}, \{X, \neg Y\}\}$$

- unit propagation: $Z \mapsto \mathbf{T}$ $\{\{X, Y\}, \{\neg X, \neg Y\}, \{X, \neg Y\}\}$
- splitting rule:

2a. $X \mapsto \mathbf{F}$ $\{\{Y\}, \{\neg Y\}\}\$ 3a. unit propagation: $Y \mapsto \mathbf{T}$ $\{\bot\}$

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Example (1)

$$\Delta = \{\{X, Y, \neg Z\}, \{\neg X, \neg Y\}, \{Z\}, \{X, \neg Y\}\}$$

- unit propagation: $Z \mapsto \mathbf{T}$ $\{\{X, Y\}, \{\neg X, \neg Y\}, \{X, \neg Y\}\}$
- Splitting rule:
- 2a. $X \mapsto \mathbf{F}$ $\{\{Y\}, \{\neg Y\}\}\$ 3a. unit propagation: $Y \mapsto \mathbf{T}$ $\{\bot\}$ 2b. $X \mapsto \mathbf{T}$ $\{\{\neg Y\}\}\$

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Example (1)

$$\Delta = \{\{X, Y, \neg Z\}, \{\neg X, \neg Y\}, \{Z\}, \{X, \neg Y\}\}$$

- unit propagation: $Z \mapsto \mathbf{T}$ $\{\{X, Y\}, \{\neg X, \neg Y\}, \{X, \neg Y\}\}$
- splitting rule:

2a. $X \mapsto \mathbf{F}$
 $\{\{Y\}, \{\neg Y\}\}$ 2b. $X \mapsto \mathbf{T}$
 $\{\{\neg Y\}\}$ 3a. unit propagation: $Y \mapsto \mathbf{T}$
 $\{\bot\}$ 3b. unit propagation: $Y \mapsto \mathbf{F}$
 $\{\}$

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Example (1)

$$\Delta = \{\{X, Y, \neg Z\}, \{\neg X, \neg Y\}, \{Z\}, \{X, \neg Y\}\}$$

- unit propagation: $Z \mapsto T$ {{X, Y}, { $\neg X, \neg Y$ }, { $X, \neg Y$ }}
- splitting rule:

2a. $X \mapsto \mathbf{F}$
 $\{\{Y\}, \{\neg Y\}\}$ 2b. $X \mapsto \mathbf{T}$
 $\{\{\neg Y\}\}$ 3a. unit propagation: $Y \mapsto \mathbf{T}$
 $\{\bot\}$ 3b. unit propagation: $Y \mapsto \mathbf{F}$
 $\{\}$

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Example (2)

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Example (2)

$\Delta = \{\{W, \neg X, \neg Y, \neg Z\}, \{X, \neg Z\}, \{Y, \neg Z\}, \{Z\}\}$

• unit propagation: $Z \mapsto \mathbf{T}$

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Example (2)

$\Delta = \{\{W, \neg X, \neg Y, \neg Z\}, \{X, \neg Z\}, \{Y, \neg Z\}, \{Z\}\}$

• unit propagation: $Z \mapsto \mathbf{T}$ {{ $W, \neg X, \neg Y$ }, {X}, {Y}}

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Example (2)

- unit propagation: $Z \mapsto \mathbf{T}$ {{ $W, \neg X, \neg Y$ }, {X}, {Y}}
- unit propagation: $X \mapsto \mathbf{T}$ $\{\{W, \neg Y\}, \{Y\}\}$

Example (2)

- unit propagation: $Z \mapsto \mathbf{T}$ $\{\{W, \neg X, \neg Y\}, \{X\}, \{Y\}\}$
- unit propagation: $X \mapsto \mathbf{T}$ $\{\{W, \neg Y\}, \{Y\}\}$
- unit propagation: $Y \mapsto \mathbf{T}$ { $\{W\}$ }

Example (2)

- unit propagation: $Z \mapsto \mathbf{T}$ $\{\{W, \neg X, \neg Y\}, \{X\}, \{Y\}\}$
- unit propagation: $X \mapsto \mathbf{T}$ $\{\{W, \neg Y\}, \{Y\}\}$
- unit propagation: $Y \mapsto \mathbf{T}$ {{W}}
- unit propagation: $W \mapsto \mathbf{T}$ {}

Example (2)

- unit propagation: $Z \mapsto T$ { $\{W, \neg X, \neg Y\}, \{X\}, \{Y\}\}$
- unit propagation: $X \mapsto T$ $\{\{W, \neg Y\}, \{Y\}\}$
- unit propagation: $Y \mapsto T$ {{W}}
- unit propagation: $W \mapsto T$ {}

Properties of DPLL

- DPLL is sound and complete.
- DPLL computes a model if a model exists.
 - Some variables possibly remain unassigned in the solution *I*; their values can be chosen arbitrarily.
- time complexity in general exponential
- important in practice: good variable order and additional inference methods (in particular clause learning)
 - Best known SAT algorithms are based on DPLL.

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Horn Formulas

important special case: Horn formulas

Definition (Horn formula)

A Horn clause is a clause with at most one positive literal, i.e., of the form

```
\neg x_1 \lor \cdots \lor \neg x_n \lor y \text{ or } \neg x_1 \lor \cdots \lor \neg x_n
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(n = 0 \text{ is allowed.})
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A Horn formula is a propositional formula in conjunctive normal form that only consists of Horn clauses.

German: Hornformel

- foundation of logic programming (e.g., PROLOG)
- critical in many kinds of practical reasoning problems

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DPLL on Horn Formulas

Proposition (DPLL on Horn formulas)

If the input formula φ is a Horn formula, then the time complexity of DPLL is polynomial in the length of φ .

Proof.

properties:

- If Δ is a Horn formula, then so is simplify (Δ, v, d) . (Why?)
 - → all formulas encountered during DPLL search are Horn formulas if input is Horn formula
- Every Horn formula without empty or unit clauses is satisfiable:
 - all such clauses consist of at least two literals
 - Horn property: at least one of them is negative
 - assigning F to all variables satisfies formula

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Summary

DPLL on Horn Formulas (Continued)

Proof (continued).

- From 2. we can conclude:
 - if splitting rule applied, then current formula satisfiable, and
 - if a wrong decision is taken, then this will be recognized without applying further splitting rules (i.e., only by applying unit propagation and by deriving the empty clause).
- Hence the generated search tree for *n* variables can only contain at most *n* nodes where the splitting rule is applied (i.e., where the tree branches).
- It follows that the search tree is of polynomial size, and hence the runtime is polynomial.

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Summary



- satisfiability basic problem in propositional logic to which other problems can be reduced
- here: satisfiability for CNF formulas
- Davis-Putnam-Logemann-Loveland procedure (DPLL): systematic backtracking search with unit propagation as inference method
- DPLL successful in practice, in particular when combined with other ideas such as clause learning
- polynomial on Horn formulas
 - (= at most one positive literal per clause)