

# Theory of Computer Science

## E1. Complexity Theory: Motivation and Introduction

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# Overview: Course

contents of this course:

A. background ✓

- ▷ mathematical foundations and proof techniques

B. logic ✓

- ▷ How can knowledge be represented?  
How can reasoning be automated?

C. automata theory and formal languages ✓

- ▷ What is a computation?

D. Turing computability ✓

- ▷ What can be computed at all?

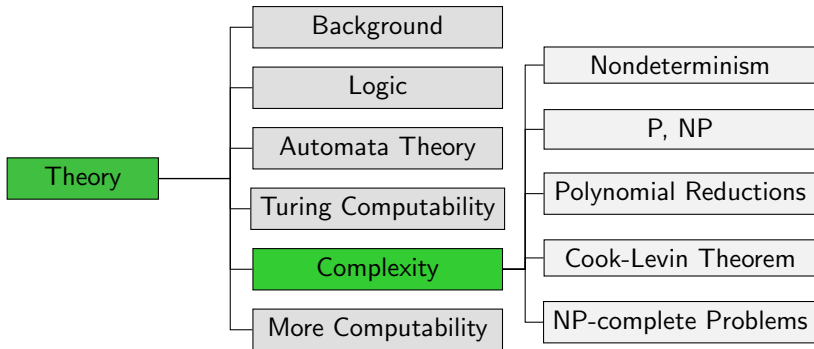
E. complexity theory

- ▷ What can be computed efficiently?

F. more computability theory

- ▷ Other models of computability

# Course Overview



# Motivation

# A Scenario (1)

## Example Scenario

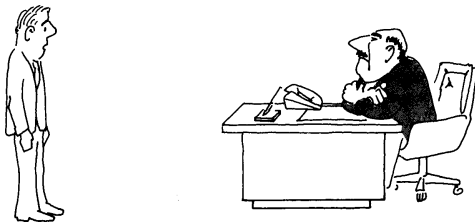
- You are a programmer at a logistics company.
- Your boss gives you the task of developing a program to optimize the route of a delivery truck:
  - The truck begins its route at the company depot.
  - It has to visit 50 stops.
  - You know the distances between all relevant locations (stops and depot).
  - Your program should compute a tour visiting all stops and returning to the depot on a **shortest route**.

## A Scenario (2)

### Example Scenario (ctd.)

- You work on the problem for weeks, but you do not manage to complete the task.
- All of your attempted programs
  - compute routes that are possibly suboptimal, or
  - do not terminate in reasonable time (say: within a month).
- What do you say to your boss?

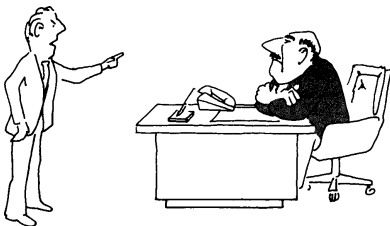
# What You Don't Want to Say



**“I can't find an efficient algorithm,  
I guess I'm just too dumb.”**

Source: M. Garey & D. Johnson, Computers and Intractability, Freeman 1979, p. 2

# What You Would Like to Say

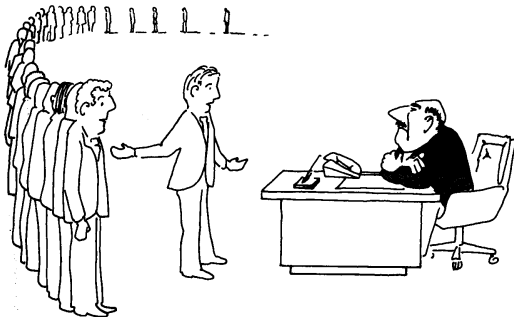


**“I can't find an efficient algorithm,  
because no such algorithm is possible!”**

Source: M. Garey & D. Johnson, *Computers and Intractability*, Freeman 1979, p. 2



# What Complexity Theory Allows You to Say



**“I can't find an efficient algorithm,  
but neither can all these famous people.”**

Source: M. Garey & D. Johnson, Computers and Intractability, Freeman 1979, p. 3

# Why Complexity Theory?

## Complexity Theory

**Complexity theory** tells us which problems can be solved **quickly** (“simple problems”) and which ones **cannot** (“hard problems”).

**German:** Komplexitätstheorie

- This is useful in practice because simple and hard problems require **different techniques** to solve.
- If we can show that a problem is hard we do not need to waste our time with the (futile) search for a “simple” algorithm.

# Why Reductions?

## Reductions

An important part of complexity theory are (polynomial) **reductions** that show how a given problem  $P$  can be reduced to another problem  $Q$ .

**German:** Reduktionen

- useful for **theoretical analysis** of  $P$  and  $Q$  because it allows us to transfer our knowledge between them
- often also useful for **practical algorithms for  $P$** :  
reduce  $P$  to  $Q$  and then use the best known algorithm for  $Q$

# Test Your Intuition! (1)

- The following slide lists some **graph problems**.
- The input is always a **directed graph**  $G = \langle V, E \rangle$ .
- **How difficult** are the problems in your opinion?
- Sort the problems from **easiest** (= requires least amount of time to solve) to **hardest** (= requires most time to solve)
- **no justification necessary**, just follow your intuition!
- **anonymous** and **not graded**

## Test Your Intuition! (2)

- 1 Find a **simple path** (= without cycle) from  $u \in V$  to  $v \in V$  with **minimal length**.
- 2 Find a **simple path** (= without cycle) from  $u \in V$  to  $v \in V$  with **maximal length**.
- 3 Determine whether  $G$  is **strongly connected** (every node is reachable from every other node).
- 4 Find a **cycle** (non-empty path from  $u$  to  $u$  for any  $u \in V$ ; multiple visits of nodes are allowed).
- 5 Find a **cycle** that visits **all** nodes.
- 6 Find a **cycle** that visits a **given node**  $u$ .
- 7 Find a path that **visits all nodes** without repeating a node.
- 8 Find a path that **uses all edges** without repeating an edge.

# How to Measure Runtime?

# How to Measure Runtime?

- **Time complexity** is a way to measure **how much time** it takes to solve a problem.
- How can we **define** such a measure appropriately?

German: Zeitkomplexität/Zeitaufwand

# Example Statements about Runtime

Example statements about runtime:

- “Running `sort /usr/share/dict/words` on the computer dakar takes 0.035 seconds.”
- “With a 1 MiB input file, `sort` takes at most 1 second on a modern computer.”
- “Quicksort is faster than sorting by insertion.”
- “Sorting by insertion is slow.”

↪ Very different statements with different **pros and cons**.



# Precise Statements vs. General Statements

## Example Statement about Runtime

“Running `sort /usr/share/dict/words` on the computer `dakar` takes 0.035 seconds.”

advantage: very **precise**

disadvantage: not **general**

- **input-specific:**

What if we want to sort other files?

- **machine-specific:**

What happens on a different computer?

- even **situation-specific:**

Will we get the same result tomorrow that we got today?

## General Statements about Runtime

In this course we want to make **general** statements about runtime. We accomplish this in three ways:

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## 1. General Inputs

Instead of **concrete** inputs, we talk about **general types** of input:

- **Example:** runtime to sort an input of size  $n$  in the **worst case**
- **Example:** runtime to sort an input of size  $n$  in the **average case**

**here:** runtime for input size  $n$  in the **worst case**

# General Statements about Runtime

In this course we want to make **general** statements about runtime. We accomplish this in three ways:

## 2. Ignoring Details

Instead of **exact formulas** for the runtime we specify the **order of magnitude**:

- **Example**: instead of saying that we need time  $[1.2n \log n] - 4n + 100$ , we say that we need time  $O(n \log n)$ .
- **Example**: instead of saying that we need time  $O(n \log n)$ ,  $O(n^2)$  or  $O(n^4)$ , we say that we need **polynomial** time.

**here**: What can be computed in **polynomial time**?

# General Statements about Runtime

In this course we want to make **general** statements about runtime. We accomplish this in three ways:

## 3. Abstract Cost Measures

Instead of the **runtime on a concrete computer** we consider a **more abstract** cost measure:

- **Example:** count the number of executed **machine code statements**
- **Example:** count the number of executed **Java byte code statements**
- **Example:** count the number of **element comparisons** of a sorting algorithms

**here:** count the computation steps of a **Turing machine** (**polynomially equivalent** to other measures)

# Decision Problems

# Decision Problems

- As before, we simplify our investigation by restricting our attention to **decision problems**.
- More complex computational problems can be solved with multiple queries for an appropriately defined decision problem (“playing 20 questions”).
- Formally, decision problems are **languages** (as before), but we use an informal **“given” / “question”** notation where possible.

## Example: Decision vs. General Problem (1)

### Definition (Hamilton Cycle)

Let  $G = \langle V, E \rangle$  be a (directed or undirected) graph.

A **Hamilton cycle** of  $G$  is a sequence of vertices in  $V$ ,

$\pi = \langle v_0, \dots, v_n \rangle$ , with the following properties:

- $\pi$  is a **path**: there is an edge from  $v_i$  to  $v_{i+1}$  for all  $0 \leq i < n$
- $\pi$  is a **cycle**:  $v_0 = v_n$
- $\pi$  is **simple**:  $v_i \neq v_j$  for all  $i \neq j$  with  $i, j < n$
- $\pi$  is **Hamiltonian**: all nodes of  $V$  are included in  $\pi$

**German:** Hamiltonkreis/Hamiltonzyklus



## Example: Decision vs. General Problem (2)

### Example (Hamilton Cycles in Directed Graphs)

**$\mathcal{P}$ :** general problem DIRHAMILTONCYCLEGEN

- **Input:** directed graph  $G = \langle V, E \rangle$
- **Output:** a Hamilton cycle of  $G$  or a message that none exists

**$\mathcal{D}$ :** decision problem DIRHAMILTONCYCLE

- **Given:** directed graph  $G = \langle V, E \rangle$
- **Question:** Does  $G$  contain a Hamilton cycle?

These problems are **polynomially equivalent**:

from a polynomial algorithm for one of the problems

one can construct a polynomial algorithm for the other problem.

(Without proof.)

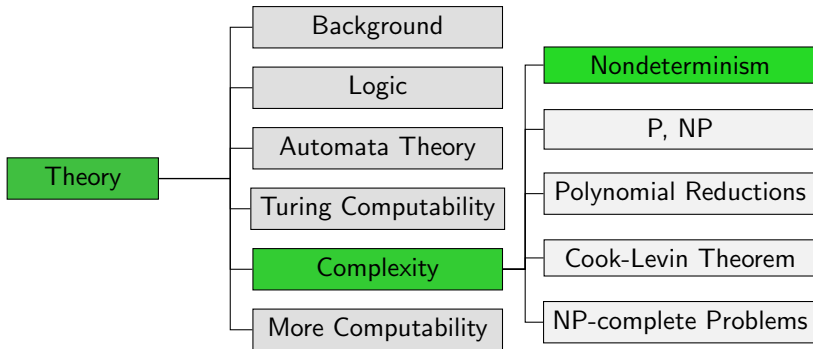
# Algorithms for Decision Problems

## Algorithms for decision problems:

- Where possible, we specify algorithms for decision problems in **pseudo-code**.
- Since they are only yes/no questions, we do not have to return a general result.
- Instead we use the statements
  - **ACCEPT** to **accept** the given input (“yes” answer) and
  - **REJECT** to **reject** it (“no” answer).
- Where we must be more formal, we use **Turing machines** and the notion of accepting from chapter C7.

# Nondeterminism

# Course Overview



# Nondeterminism

- To develop complexity theory, we need the algorithmic concept of **nondeterminism**.
- already known for **Turing machines** ( $\rightsquigarrow$  chapter C7):
  - An NTM can have **more than one possible successor configuration** for a given configuration.
  - Input  $x$  is accepted if there is **at least one possible computation** (configuration sequence) that leads to an end state.
- Here we analogously introduce nondeterminism for pseudo-code.

German: Nichtdeterminismus

# Nondeterministic Algorithms

## nondeterministic algorithms:

- All constructs of deterministic algorithms are also allowed in nondeterministic algorithms: **IF**, **WHILE**, etc.
- Additionally, there is a **nondeterministic assignment**:

**GUESS**  $x_i \in \{0, 1\}$

where  $x_i$  is a program variable.

German: nichtdeterministische Zuweisung

# Nondeterministic Algorithms: Acceptance

- Meaning of **GUESS**  $x_i \in \{0, 1\}$ :  
 $x_i$  is assigned **either** the value **0** **or** the value **1**.
- This implies that the behavior of the program on a given input is no longer uniquely defined: there are multiple possible execution paths.
- The program accepts a given input if **at least one execution path** leads to an **ACCEPT** statement.
- Otherwise, the input is rejected.

**Note:** **asymmetry** between accepting and rejecting!  
(cf. semi-decidability)

## More Complex GUESS Statements

- We will also guess more than one bit at a time:

**GUESS**  $x \in \{1, 2, \dots, n\}$

or more generally

**GUESS**  $x \in S$

for a set  $S$ .

- These are abbreviations and can be split into  $\lceil \log_2 n \rceil$  (or  $\lceil \log_2 |S| \rceil$ ) “atomic” **GUESS** statements.



# Example: Nondeterministic Algorithms (1)

## Example (DIRHAMILTONCYCLE)

**input:** directed graph  $G = \langle V, E \rangle$

*start* := an arbitrary node from  $V$

*current* := *start*

*remaining* :=  $V \setminus \{start\}$

**WHILE** *remaining*  $\neq \emptyset$ :

**GUESS** *next*  $\in$  *remaining*

**IF**  $\langle current, next \rangle \notin E$ :

**REJECT**

*remaining* := *remaining*  $\setminus$  {*next*}

*current* := *next*

**IF**  $\langle current, start \rangle \in E$ :

**ACCEPT**

**ELSE:**

**REJECT**

## Example: Nondeterministic Algorithms (2)

- With appropriate data structures, this algorithm solves the problem in  $O(n \log n)$  program steps, where  $n = |V| + |E|$  is the size of the input.
- How many steps would a **deterministic** algorithm need?

# Guess and Check

- The DIRHAMILTONCYCLE example illustrates a general design principle for nondeterministic algorithms:  
**guess and check**
- In general, nondeterministic algorithms can solve a problem by first guessing a “solution” and then verifying that it is indeed a solution. (In the example, these two steps are interleaved.)
- If solutions to a problem can be **efficiently verified**, then the problem can also be **efficiently solved** if nondeterminism may be used.

German: Raten und Prüfen

# The Power of Nondeterminism

- Nondeterministic algorithms are very powerful because they can “guess” the “correct” computation step.
- Or, interpreted differently: they go through many possible computations “in parallel”, and it suffices if **one** of them is successful.
- Can they solve problems efficiently (in polynomial time) which deterministic algorithms **cannot** solve efficiently?
- **This is the big question!**

# Summary

## Summary (1)

- **Complexity theory** deals with the question which problems can be solved **efficiently** and which ones cannot.
- **here:** focus on what can be computed **in polynomial time**
- To formalize this, we use Turing machines, but other formalisms are **polynomially equivalent**.
- We consider **decision problems**, but the results directly transfer to general computational problems.

## Summary (2)

important concept: **nondeterminism**

- **Nondeterministic algorithms** can “guess”,  
i. e., perform multiple computations “at the same time”.
- An input receives a “yes” answer if **at least one computation path** accepts it.
- in NTMs: with **nondeterministic transitions**  
( $\delta(q, a)$  contains multiple elements)
- in pseudo-code: with **GUESS statements**