

# Theory of Computer Science

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## Exercise meeting 9 — Solutions

### Exercise 9.1

Consider propositional formula  $\varphi = \neg(A \vee (\neg B \wedge C))$ .

- (a) Specify formula  $\chi_{\text{all}}$  as it is used in the polynomial reduction of SAT to 3SAT.

**Solution:**

Formula  $\chi_{\text{all}}$  over  $\{X_A, X_B, X_C, X_{\neg B}, X_{(\neg B \wedge C)}, X_{(A \vee (\neg B \wedge C))}, X_{\neg(A \vee (\neg B \wedge C))}\}$  is built from the following subformulas:

$$\begin{aligned}\chi_A &= (X_A \leftrightarrow A) \\ \chi_B &= (X_B \leftrightarrow B) \\ \chi_C &= (X_C \leftrightarrow C) \\ \chi_{\neg B} &= (X_{\neg B} \leftrightarrow \neg X_B) \\ \chi_{(\neg B \wedge C)} &= (X_{(\neg B \wedge C)} \leftrightarrow (X_{\neg B} \wedge X_C)) \\ \chi_{(A \vee (\neg B \wedge C))} &= (X_{(A \vee (\neg B \wedge C))} \leftrightarrow (X_A \vee X_{(\neg B \wedge C)})) \\ \chi_{\neg(A \vee (\neg B \wedge C))} &= (X_{\neg(A \vee (\neg B \wedge C))} \leftrightarrow \neg X_{(A \vee (\neg B \wedge C))})\end{aligned}$$

Then

$$\chi_{\text{all}} = \chi_A \wedge \chi_B \wedge \chi_C \wedge \chi_{\neg B} \wedge \chi_{(\neg B \wedge C)} \wedge \chi_{(A \vee (\neg B \wedge C))} \wedge \chi_{\neg(A \vee (\neg B \wedge C))},$$

always using the logically equivalent CNF formula that results from replacing the abbreviation  $\leftrightarrow$  with the corresponding formula, e.g.  $\chi_{(A \vee (\neg B \wedge C))} \equiv (X_{(A \vee (\neg B \wedge C))} \rightarrow (X_A \vee X_{(\neg B \wedge C)})) \wedge ((X_A \vee X_{(\neg B \wedge C)}) \rightarrow X_{(A \vee (\neg B \wedge C))}) \equiv (\neg X_{(A \vee (\neg B \wedge C))} \vee (X_A \vee X_{(\neg B \wedge C)})) \wedge (\neg(X_A \vee X_{(\neg B \wedge C)}) \vee X_{(A \vee (\neg B \wedge C))})$ .

- (b)  $\mathcal{I} = \{A \mapsto F, B \mapsto T, C \mapsto T\}$  is a model of  $\varphi$ . Specify the corresponding model of  $\chi_{\text{all}}$ .

**Solution:**

$$\begin{aligned}\mathcal{I}' &= \{X_A \mapsto F, X_B \mapsto T, X_C \mapsto T, X_{\neg B} \mapsto F, X_{(\neg B \wedge C)} \mapsto F, \\ &X_{(A \vee (\neg B \wedge C))} \mapsto F, X_{\neg(A \vee (\neg B \wedge C))} \mapsto T\}\end{aligned}$$

### Exercise 9.2

The decision problem SAT(satisfiability) is defined as follows:

*Given:* a propositional logic formula  $\varphi$

*Question:* Is  $\varphi$  satisfiable?

The general problem GENSAT(model generation) is defined as follows:

*Given:* a propositional logic formula  $\varphi$

*Output:* a model for  $\varphi$  or a message that none exists

Show that if there is a polynomial algorithm for SAT then there is a polynomial algorithm for GENSAT.

**Solution:**

We specify an algorithm that solves GENSAT. It uses transformations  $\psi[v \mapsto T]$  and  $\psi[v \mapsto F]$  that replace every occurrence of  $v$  with a small valid (e.g.  $v \vee \neg v$ ) and unsatisfiable (e.g.  $v \wedge \neg v$ ) formula, respectively. Then

- $\mathcal{I}'$  is a model of  $\psi[v \mapsto T]$  iff  $\mathcal{I}$  with  $\mathcal{I}(v) = T$  and  $\mathcal{I}(v') = \mathcal{I}'(v')$  for  $v' \neq v$  is a model of  $\psi$  and
- $\mathcal{I}'$  is a model of  $\psi[v \mapsto F]$  iff  $\mathcal{I}$  with  $\mathcal{I}(v) = F$  and  $\mathcal{I}(v') = \mathcal{I}'(v')$  for  $v' \neq v$

Moreover, if  $\psi$  is satisfiable and  $\psi[v \mapsto T]$  is unsatisfiable then  $\psi[v \mapsto F]$  is satisfiable.

The algorithm proceeds as follows:

Call the algorithm for SAT on input  $\varphi$ . If it is unsatisfiable, output that it has no model.

Otherwise, we successively build a model  $\mathcal{I}$  for  $\varphi$ , starting with  $\varphi' := \varphi$ , as follows:

While there is still an unassigned variable  $v$ , call the SAT algorithm for  $\varphi'[v \mapsto T]$ . If the answer is yes, set  $\mathcal{I}(v) = T$  and continue with  $\varphi' := \varphi'[v \mapsto T]$ , otherwise set  $\mathcal{I}(v) = F$  and continue with  $\varphi' := \varphi'[v \mapsto F]$ .

Since the number of variables is bound by the size of  $\varphi$ , there is only a polynomial number of iterations. The size of the last formula  $\varphi'$  is at most  $k$  times larger than  $\varphi$  for some constant  $k$  ( $k = 2$  if we only count variable occurrences to determine the size). Hence, if every call to SAT is possible in polynomial time then the overall runtime is polynomial.