

Foundations of Artificial Intelligence

42. Board Games: Alpha-Beta Search

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42.1 Alpha-Beta Search

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42.3 Summary

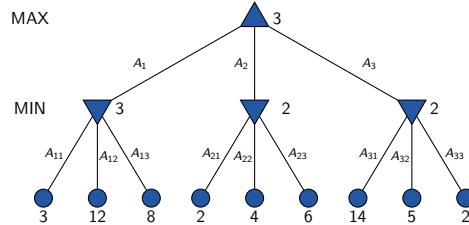
Board Games: Overview

chapter overview:

- ▶ 40. Introduction and State of the Art
- ▶ 41. Minimax Search and Evaluation Functions
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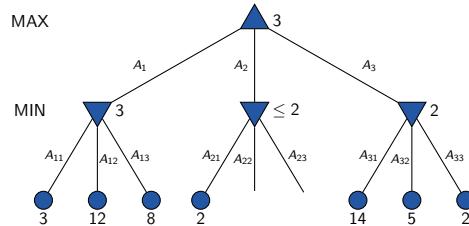
42.1 Alpha-Beta Search

Alpha-Beta Search



Can we save search effort?

We do not need to consider all the nodes!



Alpha-Beta Search: Idea

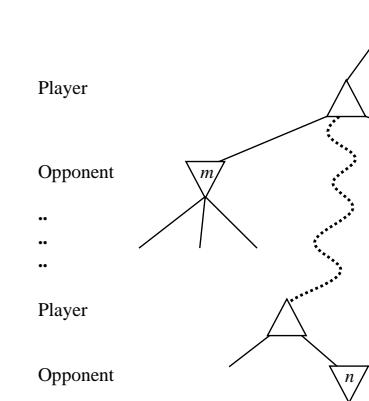
idea: Use two values α and β during minimax depth-first search, such that the following holds for every recursive call:

- ▶ If the utility value in the current subtree is $\leq \alpha$, then the subtree is **not interesting** because MAX will never enter it when playing perfectly.
- ▶ If the utility value in the current subtree is $\geq \beta$, then the subtree is **not interesting** because MIN will never enter it when playing perfectly.

If $\alpha \geq \beta$ in the subtree, then the subtree is not interesting and does not have to be searched further (α - β pruning).

Starting with $\alpha = -\infty$ and $\beta = +\infty$, alpha-beta search produces the **identical** result as minimax, with lower search effort.

Alpha-Beta Search: Generally



If $m > n$, then node with utility n will never be reached when playing perfectly!

Alpha-Beta Search: Pseudo Code

- ▶ algorithm skeleton the same as minimax
- ▶ function signature extended by two variables α and β

```
function alpha-beta-main(p)
  ⟨v, move⟩ := alpha-beta(p, -∞, +∞)
  return move
```

Alpha-Beta Search: Pseudo-Code

```

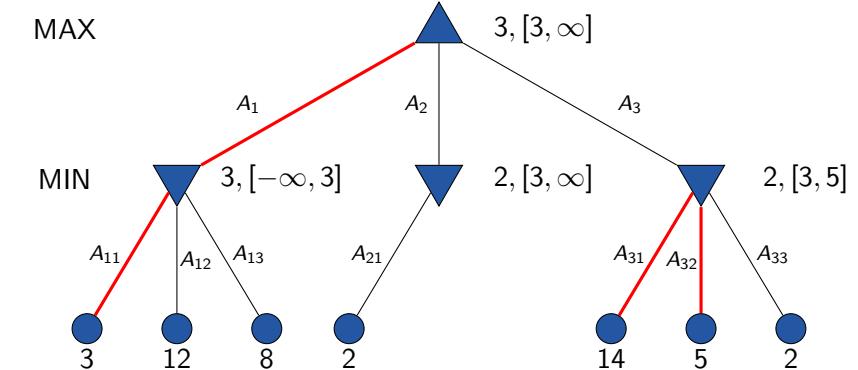
function alpha-beta( $p, \alpha, \beta$ )
  if  $p$  is terminal position:
    return  $\langle u(p), \text{none} \rangle$ 
  initialize  $v$  and  $\text{best\_move}$ 
  for each  $\langle \text{move}, p' \rangle \in \text{succ}(p)$ :
     $\langle v', \text{best\_move}' \rangle := \text{alpha-beta}(p', \alpha, \beta)$ 
    update  $v$  and  $\text{best\_move}$ 
    if  $\text{player}(p) = \text{MAX}$ :
      if  $v \geq \beta$ :
        return  $\langle v, \text{none} \rangle$ 
       $\alpha := \max\{\alpha, v\}$ 
    if  $\text{player}(p) = \text{MIN}$ :
      if  $v \leq \alpha$ :
        return  $\langle v, \text{none} \rangle$ 
       $\beta := \min\{\beta, v\}$ 
  return  $\langle v, \text{best\_move} \rangle$ 

```

[as in minimax]

[as in minimax]

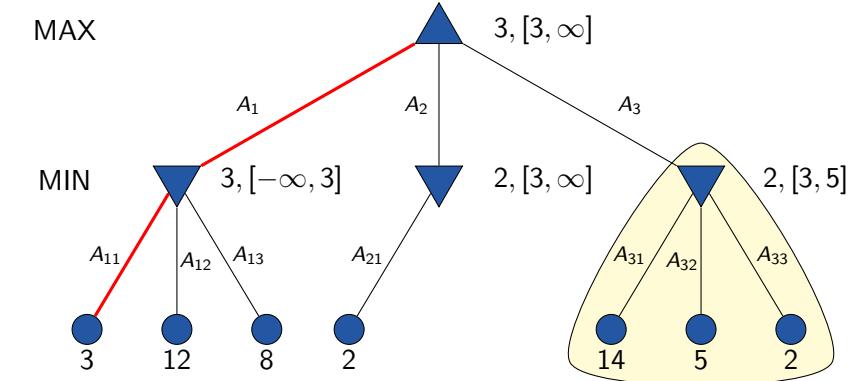
Alpha-Beta Search: Example



Cf. screen slides for detailed steps.

42.2 Move Ordering

Alpha-Beta Search: Example



If the last successor had been first, the rest of the subtree would have been pruned.

Move Ordering

idea: consider first the successors that are likely to be best.

- ▶ **Domain-specific ordering function**

e.g. chess: captures < threats < forward moves < backward moves

- ▶ **Dynamic move-ordering**

- ▶ try first moves that have been good in the past
- ▶ e.g. in iterative deepening search:
best moves from previous iteration

How Much Do We Gain with Alpha-Beta Search?

assumption: uniform game tree, depth d , branching factor $b \geq 2$;
MAX and MIN positions alternating

- ▶ **perfect move ordering**

- ▶ best move at every position is considered first
(this cannot be done in practice – [Why?](#))
- ▶ maximizing move for MAX, minimizing move for MIN
- ▶ effort reduced from $O(b^d)$ (minimax) to $O(b^{d/2})$
- ▶ doubles the search depth that can be achieved in same time

- ▶ **random move ordering**

- ▶ effort still reduced to $O(b^{3d/4})$ (for moderate b)

In practice, it is often possible to get close to the optimum.

42.3 Summary

Summary

alpha-beta search

- ▶ stores which utility both players can force somewhere else in the game tree
- ▶ exploits this information to **avoid unnecessary computations**
- ▶ can have significantly **lower search effort than minimax**
- ▶ best case: search **twice as deep** in the same time