

# Foundations of Artificial Intelligence

## 42. Board Games: Alpha-Beta Search

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## 42.1 Alpha-Beta Search

## 42.2 Move Ordering

## 42.3 Summary

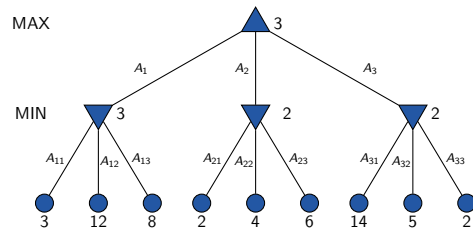
## Board Games: Overview

### chapter overview:

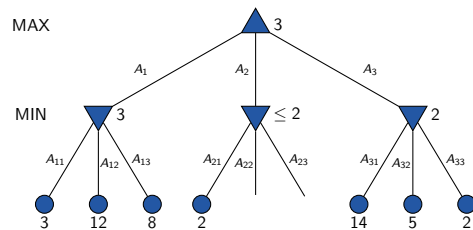
- ▶ 40. Introduction and State of the Art
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## 42.1 Alpha-Beta Search

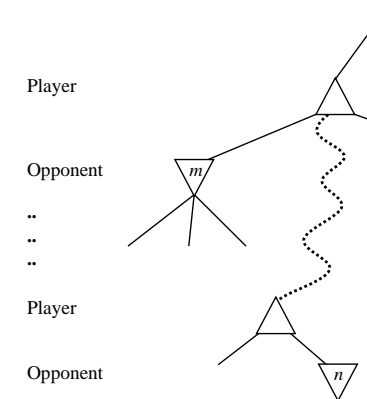
## Alpha-Beta Search



Can we save search effort?  
We do not need to consider all the nodes!



## Alpha-Beta Search: Generally



If  $m > n$ , then node with utility  $n$  will never be reached when playing perfectly!

## Alpha-Beta Search: Idea

**idea:** Use two values  $\alpha$  and  $\beta$  during minimax depth-first search, such that the following holds for every recursive call:

- ▶ If the utility value in the current subtree is  $\leq \alpha$ , then the subtree **is not interesting** because MAX will never enter it when playing perfectly.
- ▶ If the utility value in the current subtree is  $\geq \beta$ , then the subtree **is not interesting** because MIN will never enter it when playing perfectly.

If  $\alpha \geq \beta$  in the subtree, then the subtree is not interesting and does not have to be searched further ( **$\alpha$ - $\beta$  pruning**).

Starting with  $\alpha = -\infty$  and  $\beta = +\infty$ , alpha-beta search produces the **identical** result as minimax, with lower search effort.

## Alpha-Beta Search: Pseudo Code

- ▶ algorithm skeleton the same as minimax
- ▶ function signature extended by two variables  $\alpha$  and  $\beta$

```
function alpha-beta-main( $p$ )
 $\langle v, move \rangle := \text{alpha-beta}(p, -\infty, +\infty)$ 
return move
```

## Alpha-Beta Search: Pseudo-Code

```
function alpha-beta( $p, \alpha, \beta$ )
```

```
if  $p$  is terminal position:
```

```
  return  $\langle u(p), \text{none} \rangle$ 
```

```
initialize  $v$  and  $best\_move$ 
```

```
[as in minimax]
```

```
for each  $\langle move, p' \rangle \in succ(p)$ :
```

```
   $\langle v', best\_move \rangle := alpha-beta(p', \alpha, \beta)$ 
```

```
  update  $v$  and  $best\_move$ 
```

```
[as in minimax]
```

```
  if  $player(p) = MAX$ :
```

```
    if  $v \geq \beta$ :
```

```
      return  $\langle v, \text{none} \rangle$ 
```

```
       $\alpha := \max\{\alpha, v\}$ 
```

```
  if  $player(p) = MIN$ :
```

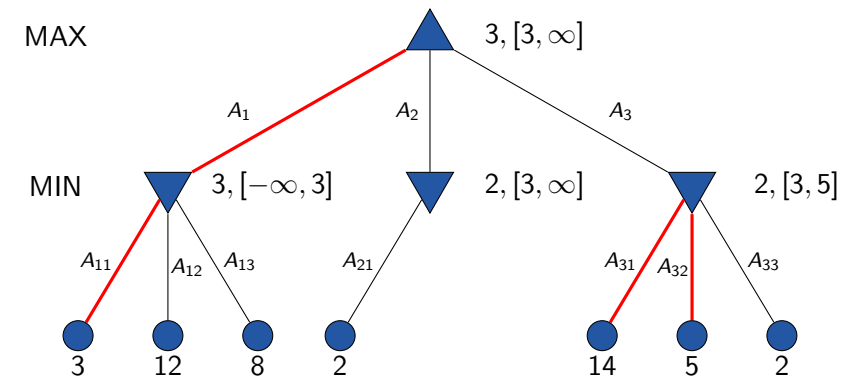
```
    if  $v \leq \alpha$ :
```

```
      return  $\langle v, \text{none} \rangle$ 
```

```
       $\beta := \min\{\beta, v\}$ 
```

```
return  $\langle v, best\_move \rangle$ 
```

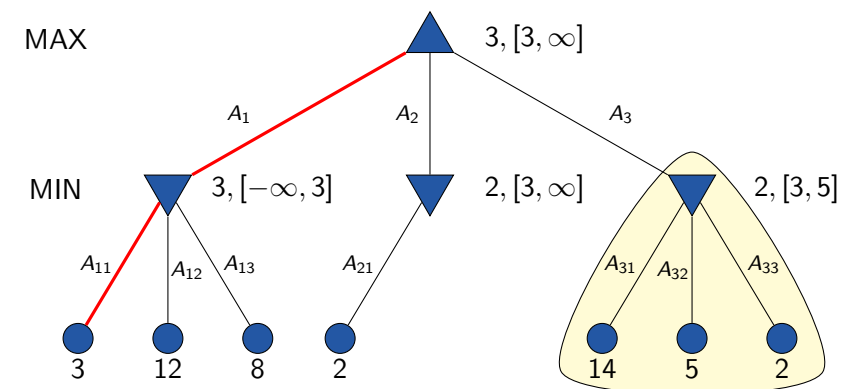
## Alpha-Beta Search: Example



Cf. screen slides for detailed steps.

## 42.2 Move Ordering

## Alpha-Beta Search: Example



If the last successor had been first, the rest of the subtree would have been pruned.

## Move Ordering

**idea:** consider first the successors that are likely to be best.

- ▶ **Domain-specific ordering function**  
e.g. chess: captures < threats < forward moves < backward moves
- ▶ **Dynamic move-ordering**
  - ▶ try first moves that have been good in the past
  - ▶ e.g. in iterative deepening search:  
best moves from previous iteration

## How Much Do We Gain with Alpha-Beta Search?

**assumption:** uniform game tree, depth  $d$ , branching factor  $b \geq 2$ ;  
MAX and MIN positions alternating

- ▶ **perfect move ordering**
  - ▶ best move at every position is considered first  
(this cannot be done in practice – *Why?*)
  - ▶ maximizing move for MAX, minimizing move for MIN
  - ▶ effort reduced from  $O(b^d)$  (minimax) to  $O(b^{d/2})$
  - ▶ doubles the search depth that can be achieved in same time
- ▶ **random move ordering**
  - ▶ effort still reduced to  $O(b^{3d/4})$  (for moderate  $b$ )

In practice, it is often possible to get close to the optimum.

## 42.3 Summary

## Summary

### alpha-beta search

- ▶ stores which utility both players can force somewhere else in the game tree
- ▶ exploits this information to **avoid unnecessary computations**
- ▶ can have significantly **lower search effort than minimax**
- ▶ best case: search **twice as deep** in the same time