Foundations of Artificial Intelligence

6. State-Space Search: Representation of State Spaces

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State-Space Search: Overview

Chapter overview: state-space search

- 5.–7. Foundations
  - 5. State Spaces
  - 6. Representation of State Spaces
  - 7. Examples of State Spaces
- 8.–12. Basic Algorithms
- 13.–19. Heuristic Algorithms

6.1 Representation of State Spaces

Representation of State Spaces

- practically interesting state spaces are often huge (10^{10}, 10^{20}, 10^{100} states)
- How do we represent them, so that we can efficiently deal with them algorithmically?

three main options:

1. as explicit (directed) graphs
2. with declarative representations
3. as a black box

German: explizite Graphen, deklarative Repräsentationen, Black Box

6.2 Explicit Graphs

State Spaces as Explicit Graphs

State Spaces as Explicit Graphs

represent state spaces as explicit directed graphs:

- vertices = states
- directed arcs = transitions

$\rightsquigarrow$ represented as adjacency list or adjacency matrix

German: Adjazenzliste, Adjazenzmatrix

Example (explicit graph for 8-puzzle)

`puzzle8.graph`

State Spaces as Explicit Graphs: Discussion

discussion:

- impossible for large state spaces (too much space required)
- if spaces small enough for explicit representations, solutions easy to compute: Dijkstra's algorithm $O(|S| \log |S| + |T|)$
- interesting for time-critical all-pairs-shortest-path queries (examples: route planning, path planning in video games)

6.3 Declarative Representations

State Spaces with Declarative Representations

State Spaces with Declarative Representations

represent state spaces declaratively:

- compact description of state space as input to algorithms
  $\rightsquigarrow$ state spaces exponentially larger than the input
- algorithms directly operate on compact description

$\rightsquigarrow$ allows automatic reasoning about problem:
reformulation, simplification, abstraction, etc.

Example (declarative representation for 8-puzzle)

`puzzle8-domain.pddl` + `puzzle8-problem.pddl`

6.4 Black Box

State Spaces as Black Boxes

State Spaces as Black Boxes

Define an abstract interface for state spaces.

For state space $\mathcal{S} = \langle S, A, cost, T, s_0, S_\star \rangle$
we need these methods:

- init(): generate initial state
  result: state s_0
- is_goal(s): test if s is a goal state
  result: **true** if $s \in S_\star$; **false** otherwise
- succ(s): generate applicable actions and successors of s
  result: sequence of pairs $\langle a, s' \rangle$ with $s \xrightarrow{a} s'$
- cost(a): gives cost of action a
  result: $cost(a)$ $(\in \mathbb{N}_0)$

Remark: we will extend the interface later
in a small but important way

State Spaces as Black Boxes: Example and Discussion

Example (Black Box Representation for 8-Puzzle)

demo: `puzzle8.py`

- in the following: focus on black box model
- explicit graphs only as illustrating examples
- near end of semester: declarative state spaces (classical planning)

6.5 Summary

Summary

- state spaces often huge ($> 10^{10}$ states)
  $\rightsquigarrow$ how to represent?
- explicit graphs: adjacency lists or matrices; only suitable for small problems
- declaratively: compact description as input to search algorithms
- black box: implement an abstract interface