

Planning and Optimization

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Fall Semester 2016

Exercise Sheet 5 Due: November 2, 2016

Exercise 5.1 (1+2 marks)

Consider the planning task $\Pi = \langle V, I, O, \gamma \rangle$ in positive normal form with

$$\begin{aligned} V &= \{haveCake, haveQuiche, haveSugar, haveNoSugar, notHungry\} \\ I &= \{haveCake \mapsto \mathbf{F}, haveQuiche \mapsto \mathbf{F}, haveSugar \mapsto \mathbf{T}, \\ &\quad haveNoSugar \mapsto \mathbf{F}, notHungry \mapsto \mathbf{F}\} \\ O &= \{bake, eatCake, eatQuiche\} \text{ with} \\ &\quad bake = \langle \top, (haveSugar \triangleright haveCake) \wedge (haveSugar \triangleright \neg haveSugar) \wedge \\ &\quad \quad (haveSugar \triangleright haveNoSugar) \wedge (haveNoSugar \triangleright haveQuiche), 5 \rangle, \\ &\quad eatCake = \langle haveCake, \neg haveCake \wedge notHungry, 1 \rangle, \\ &\quad eatQuiche = \langle haveQuiche, \neg haveQuiche \wedge notHungry, 1 \rangle \\ \gamma &= haveCake \wedge notHungry \end{aligned}$$

- (a) Provide the delete relaxation Π^+ of Π .
- (b) Provide a sequence π of operators from O such that π^+ is a plan for Π^+ but π is no plan for Π .

Exercise 5.2 (1 mark)

Provide a planning task $\Pi = \langle V, I, O, \gamma \rangle$ in positive normal form such that Π is unsolvable and Π^+ is solvable.

Exercise 5.3 (4 marks)

In the lecture, we have shown that the **BCPlanEx** problem restricted to delete-relaxed planning tasks is NP-complete (chapter C2, slides 11 and 12 in the handout version). In this exercise, we consider the special case of delete-relaxed planning tasks where, in addition, for every delete-relaxed operator o^+ , $pre(o^+)$ is a single atom or \top and $eff(o^+)$ is an atomic effect. Prove that the **BCPlanEx** problem for delete-relaxed planning tasks restricted to operators of this kind (i.e., to operators o^+ where $pre(o^+)$ is a single atom or \top and $eff(o^+)$ is an atomic effect) is still NP-complete.

Hint: Reduction from the set cover problem. Make use of zero-cost operators.

Please turn around

Exercise 5.4 (4 marks)

Consider the planning task $\Pi = \langle V, I, O, \gamma \rangle$ with

$$\begin{aligned} V &= \{a, b, c, d, e, f, g, h\} \\ I &= \{c \mapsto \mathbf{T}\} \cup \{v \mapsto \mathbf{F} \mid v \in V \setminus \{c\}\} \\ O &= \{o_1, o_2, o_3, o_4\} \text{ with} \\ o_1 &= \langle a, b, 1 \rangle \\ o_2 &= \langle b, a, 1 \rangle \\ o_3 &= \langle c, d \wedge (d \triangleright e) \wedge (b \triangleright f), 1 \rangle \\ o_4 &= \langle e \vee h, g, 1 \rangle \\ \gamma &= g \end{aligned}$$

- (a) Provide the relaxed task graph $RTG(\Pi^+)$ of Π graphically.
- (b) Give the most conservative valuation of $RTG(\Pi^+)$.
- (c) Provide a consistent valuation of $RTG(\Pi^+)$ that is different from your solution to exercise 5.4 b).

The exercise sheets can be submitted in groups of two students. Please provide both student names on the submission.