

Seminar: Search and Optimization

Consistency-Enforcing and Constraint Propagation

Presentation: Martin Wehrle

University of Basel

October 16, 2014

Inference

Inference

What is Inference?

- Derivation of additional constraints that are **implied** from known constraints

Why can Inference be Useful?

- Narrows the search space of possible partial solutions
- Search for solutions becomes more focused

Inference

Example

Constraint network with variables v_1, v_2, v_3 with domain $\{1, 2, 3\}$ and constraints $v_1 < v_2$ and $v_2 < v_3$.

It follows:

- v_2 cannot be equal to 3
(new unary constraint = restriction of the domain of v_2)
- $R_{v_1 v_2} = \{\langle 1, 2 \rangle, \langle 1, 3 \rangle, \langle 2, 3 \rangle\}$ can be made stronger to $\{\langle 1, 2 \rangle\}$
(tightened binary constraint)

Inference

Inference formally

For a given constraint network \mathcal{R} , replace \mathcal{R} with an **equivalent**, but **tighter** network.

Trade-off:

- the more **complex** the interference,
- the **more additional** constraints can be inferred, but
- the **higher** the time complexity

Inference

In this talk, we consider increasingly powerful inference methods.

Outline

- Arc-consistency
- Path-consistency
- *i*-consistency

Arc-Consistency

Arc-Consistency: Definition

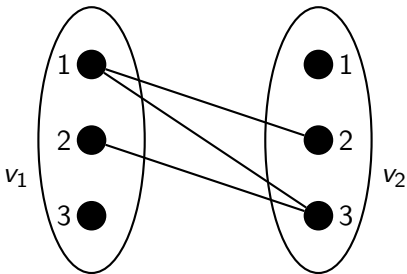
Definition (Arc-Consistent)

Let $\mathcal{R} = (X, D, C)$ be a constraint network.

- (a) A variable $v \in X$ is **arc-consistent** with respect to another variable $v' \in X$ if for every value $d \in D_v$ there is a value $d' \in D_{v'}$ such that $\langle d, d' \rangle \in R_{vv'}$.
- (b) The constraint network \mathcal{R} is **arc-consistent** if every variable $v \in X$ is arc-consistent with respect to every other variable $v' \in X$.

Arc-Consistency: Example

Consider a constraint network with variables v_1 and v_2 , domains $D_{v_1} = D_{v_2} = \{1, 2, 3\}$, and the constraint $v_1 < v_2$.



- v_1 not arc-consistent with respect to v_2
- v_2 not arc-consistent with respect to v_1

Enforcing Arc-Consistency

- Enforcing arc-consistency, i. e., removing values of D_v that violate the arc-consistency of v with respect to v' is a correct inference method. (Why?)
- In the following, we consider algorithms to enforce arc-consistency.

Single Pair of Variables: Function revise

function revise(\mathcal{R}, v, v'):

$(X, D, C) := \mathcal{R}$

for each $d \in D_v$:

if there is no $d' \in D_{v'}$ with $\langle d, d' \rangle \in R_{vv'}$:

remove d from D_v

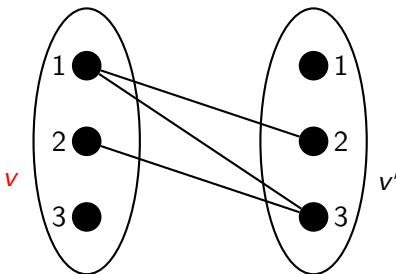
Input: Constraint network \mathcal{R} and two variables v, v' in \mathcal{R}

Effect: Enforces arc-consistency of v with respect to v' .

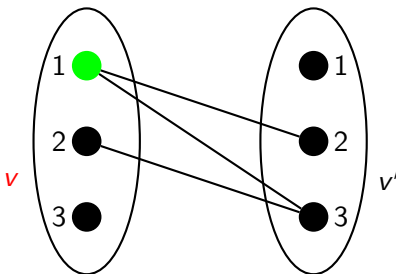
All violating values are removed from D_v .

Time complexity: $O(k^2)$, where k bounds the domain size.

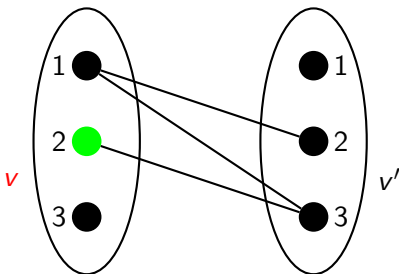
Example: revise



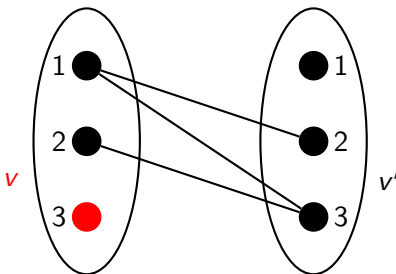
Example: revise



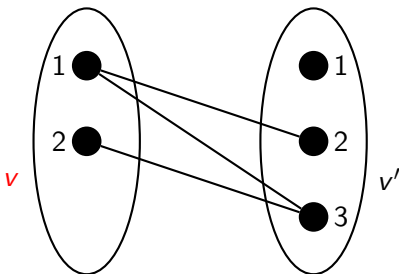
Example: revise



Example: revise



Example: revise



Enforcing Arc-Consistency: AC-1

```
function AC-1( $\mathcal{R}$ ):
```

```
( $X, D, C$ ) :=  $\mathcal{R}$ 
```

```
repeat
```

```
  for each nontrivial constraint  $R_{uv} \in C$ :
```

```
    revise( $\mathcal{R}, u, v$ )
```

```
    revise( $\mathcal{R}, v, u$ )
```

```
until no domain has changed in this iteration
```

Input: Constraint network \mathcal{R}

Effect: transforms \mathcal{R} into equivalent network that is arc-consistent

Time complexity: ?

Enforcing Arc-Consistency: AC-1

```
function AC-1( $\mathcal{R}$ ):
```

```
( $X, D, C$ ) :=  $\mathcal{R}$ 
```

```
repeat
```

```
  for each nontrivial constraint  $R_{uv} \in C$ :
```

```
    revise( $\mathcal{R}, u, v$ )
```

```
    revise( $\mathcal{R}, v, u$ )
```

```
until no domain has changed in this iteration
```

Input: Constraint network \mathcal{R}

Effect: transforms \mathcal{R} into equivalent network that is arc-consistent

Time complexity: $O(n \cdot e \cdot k^3)$, for n variables, e nontrivial constraints, and k maximal domain size

AC-1: Discussion

- AC-1 does the job, but in an inefficient way.
 - Often variable pairs are checked again and again although their domains have not changed.
 - These checks can be saved.
- ↪ more efficient algorithm: AC-3

Enforcing Arc-Consistency: AC-3

Idea: store variable pairs that are **potentially inconsistent** in a queue

function AC-3(\mathcal{R}):

$(X, D, C) := \mathcal{R}$

queue := \emptyset

for each nontrivial constraint $R_{uv} \in C$:

 insert $\langle u, v \rangle$ into *queue*

 insert $\langle v, u \rangle$ into *queue*

while *queue* $\neq \emptyset$:

 remove an arbitrary element $\langle u, v \rangle$ from *queue*

 revise(\mathcal{R}, u, v)

if D_u changed in the call to revise:

for each $w \in X \setminus \{u, v\}$ where R_{wu} is nontrivial:

 insert $\langle w, u \rangle$ into *queue*

AC-3: Discussion

- *queue* can be an arbitrary data structure that allows for “insert” and “get” operations (the order of getting the variable pairs does not affect the result)

↪ efficient e. g. a stack

- AC-3 has the same effect as AC-1: it enforces arc-consistency
- **Proof idea:** Invariant of the **while** loop: If $\langle u, v \rangle \notin \text{queue}$, then u is arc-consistent with respect to v

AC-3: Time Complexity

Proposition (Time complexity of AC-3)

Let \mathcal{R} be a constraint network with e nontrivial constraints and maximal domain size k .

Then AC-3 has time complexity $O(e \cdot k^3)$.

AC-3: Time Complexity (Proof)

Proof

Consider a pair $\langle u, v \rangle$ for which there is a nontrivial constraint R_{uv} .
There are e such pairs.

AC-3: Time Complexity (Proof)

Proof

Consider a pair $\langle u, v \rangle$ for which there is a nontrivial constraint R_{uv} .
There are e such pairs.

Every time a pair is inserted into the queue (except for the first time), the domain of the second variable has been reduced before.

AC-3: Time Complexity (Proof)

Proof

Consider a pair $\langle u, v \rangle$ for which there is a nontrivial constraint R_{uv} .
There are e such pairs.

Every time a pair is inserted into the queue (except for the first time), the domain of the second variable has been reduced before.

This can happen at most k times.

AC-3: Time Complexity (Proof)

Proof

Consider a pair $\langle u, v \rangle$ for which there is a nontrivial constraint R_{uv} .
There are e such pairs.

Every time a pair is inserted into the queue (except for the first time), the domain of the second variable has been reduced before.

This can happen at most k times.

Hence, every pair $\langle u, v \rangle$ is inserted into the queue at most $k + 1$ times \rightsquigarrow all in all, we have at most $O(ek)$ insert operations.

AC-3: Time Complexity (Proof)

Proof

Consider a pair $\langle u, v \rangle$ for which there is a nontrivial constraint R_{uv} . There are e such pairs.

Every time a pair is inserted into the queue (except for the first time), the domain of the second variable has been reduced before.

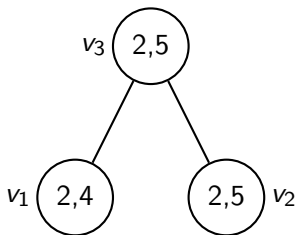
This can happen at most k times.

Hence, every pair $\langle u, v \rangle$ is inserted into the queue at most $k + 1$ times \rightsquigarrow all in all, we have at most $O(ek)$ insert operations.

This restricts the number of **while** iterations to $O(ek)$, therefore the revise calls need time at most $O(ek) \cdot O(k^2) = O(ek^3)$.

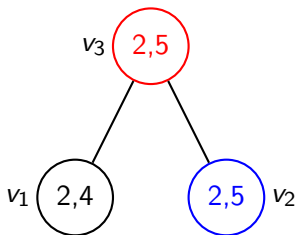
AC-3: Example

Consider the constraint network with three variables v_1 , v_2 , v_3 with $D_{v_1} = \{2, 4\}$ and $D_{v_2} = D_{v_3} = \{2, 5\}$ and the constraints $v_3|v_1$ and $v_3|v_2$ (“divides evenly”).

Queue (v_1, v_3) (v_3, v_1) (v_2, v_3) (v_3, v_2)

AC-3: Example

Consider the constraint network with three variables v_1 , v_2 , v_3 with $D_{v_1} = \{2, 4\}$ and $D_{v_2} = D_{v_3} = \{2, 5\}$ and the constraints $v_3|v_1$ and $v_3|v_2$ (“divides evenly”).



Queue

(v_1, v_3)

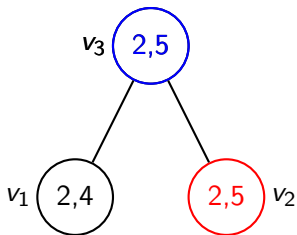
(v_3, v_1)

(v_2, v_3)

(v_3, v_2)

AC-3: Example

Consider the constraint network with three variables v_1 , v_2 , v_3 with $D_{v_1} = \{2, 4\}$ and $D_{v_2} = D_{v_3} = \{2, 5\}$ and the constraints $v_3|v_1$ and $v_3|v_2$ (“divides evenly”).



Queue

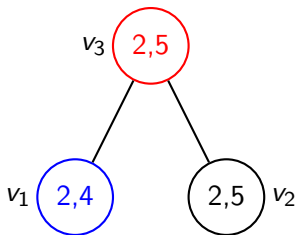
(v_1, v_3)

(v_3, v_1)

(v_2, v_3)

AC-3: Example

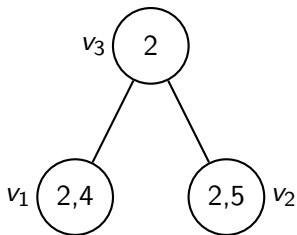
Consider the constraint network with three variables v_1 , v_2 , v_3 with $D_{v_1} = \{2, 4\}$ and $D_{v_2} = D_{v_3} = \{2, 5\}$ and the constraints $v_3|v_1$ and $v_3|v_2$ (“divides evenly”).

Queue

(v_1, v_3)
(v_3, v_1)

AC-3: Example

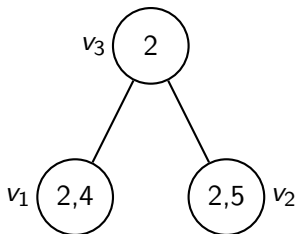
Consider the constraint network with three variables v_1 , v_2 , v_3 with $D_{v_1} = \{2, 4\}$ and $D_{v_2} = D_{v_3} = \{2, 5\}$ and the constraints $v_3|v_1$ and $v_3|v_2$ (“divides evenly”).



Queue
(v_1, v_3)

AC-3: Example

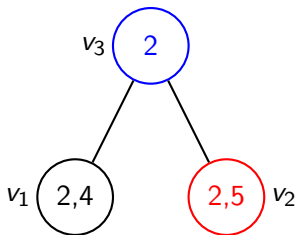
Consider the constraint network with three variables v_1 , v_2 , v_3 with $D_{v_1} = \{2, 4\}$ and $D_{v_2} = D_{v_3} = \{2, 5\}$ and the constraints $v_3|v_1$ and $v_3|v_2$ (“divides evenly”).

Queue

(v_1, v_3)
(v_2, v_3)

AC-3: Example

Consider the constraint network with three variables v_1 , v_2 , v_3 with $D_{v_1} = \{2, 4\}$ and $D_{v_2} = D_{v_3} = \{2, 5\}$ and the constraints $v_3|v_1$ and $v_3|v_2$ (“divides evenly”).

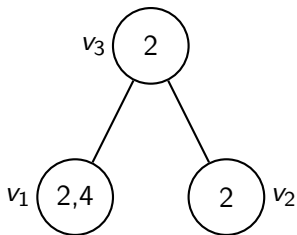


Queue

(v_1, v_3)
(v_2, v_3)

AC-3: Example

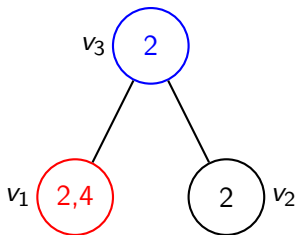
Consider the constraint network with three variables v_1 , v_2 , v_3 with $D_{v_1} = \{2, 4\}$ and $D_{v_2} = D_{v_3} = \{2, 5\}$ and the constraints $v_3|v_1$ and $v_3|v_2$ (“divides evenly”).



Queue
 (v_1, v_3)

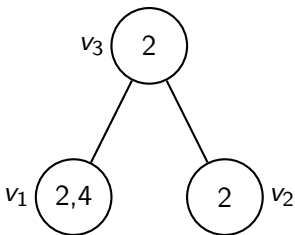
AC-3: Example

Consider the constraint network with three variables v_1 , v_2 , v_3 with $D_{v_1} = \{2, 4\}$ and $D_{v_2} = D_{v_3} = \{2, 5\}$ and the constraints $v_3|v_1$ and $v_3|v_2$ (“divides evenly”).

Queue (v_1, v_3)

AC-3: Example

Consider the constraint network with three variables v_1 , v_2 , v_3 with $D_{v_1} = \{2, 4\}$ and $D_{v_2} = D_{v_3} = \{2, 5\}$ and the constraints $v_3|v_1$ and $v_3|v_2$ (“divides evenly”).



Queue

Path-Consistency

Beyond Arc-Consistency: Path-Consistency

Recall: Idea of Arc-Consistency:

- For every value of variable u there exists a consistent value for every other variable v
- Values of u that do not have this property are not allowed

↪ tightens **unary constraint** on u

Idea can be extended to three variables (**path-consistency**):

- For every common valuation of u, v there must be a consistent value for every other variable w
- Pairs of values for u and v that do not have this property are not allowed

↪ tightens **binary constraint** on u and v

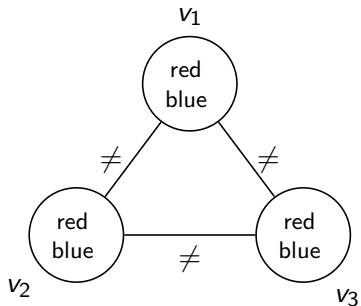
Path-Consistency: Definition

Definition (Path-Consistent)

Let $\mathcal{R} = (X, D, C)$ be a constraint network.

- (a) Two different variables $u, v \in X$ are **path-consistent** with respect to a third variable $w \in X$ if for all values $d_u \in D_u, d_v \in D_v$ with $\langle u, v \rangle \in R_{uv}$, there is a value $d_w \in D_w$ such that $\langle d_u, d_w \rangle \in R_{uw}$ and $\langle d_v, d_w \rangle \in R_{vw}$.
- (b) The constraint network \mathcal{R} is **path-consistent**, if for three different variables u, v, w , it holds that u and v are path-consistent with respect to w .

Path-Consistency: Example



arc-consistent, but not path-consistent

Triple of Variables: revise-3

Analogous to [revise](#) for arc-consistency:

```
function revise-3( $\mathcal{R}$ ,  $u$ ,  $v$ ,  $w$ ):
```

```
( $X$ ,  $D$ ,  $C$ ) :=  $\mathcal{R}$ 
```

```
for each  $\langle d_u, d_v \rangle \in R_{uv}$ :
```

```
    if there is no  $d_w \in D_w$  with
```

```
         $\langle d_u, d_w \rangle \in R_{uw}$  and  $\langle d_v, d_w \rangle \in R_{vw}$ :
```

```
            remove  $\langle d_u, d_v \rangle$  from  $R_{uv}$ 
```

Input: Constraint network \mathcal{R} and three variables u , v , w of \mathcal{R}

Effect: Turns u , v path-consistent with respect to w .

All violating pairs of variables are removed from R_{uv} .

Time complexity: $O(k^3)$, where k is the maximal domain size

Enforcing Path-Consistency: PC-2

Analogous to [AC-3](#) for arc-consistency:

```
function PC-2( $\mathcal{R}$ ):
```

```
( $X, D, C$ ) :=  $\mathcal{R}$ 
```

```
queue :=  $\emptyset$ 
```

```
for each set of two variables  $\{u, v\}$ :
```

```
    for each  $w \in X \setminus \{u, v\}$ :
```

```
        insert  $\langle u, v, w \rangle$  into queue
```

```
while queue  $\neq \emptyset$ :
```

```
    remove any element  $\langle u, v, w \rangle$  from queue
```

```
    revise-3( $\mathcal{R}, u, v, w$ )
```

```
    if  $R_{uv}$  changed in the call to revise-3:
```

```
        for each  $w' \in X \setminus \{u, v\}$ :
```

```
            insert  $\langle w', u, v \rangle$  into queue
```

```
            insert  $\langle w', v, u \rangle$  into queue
```

Path-Consistency: Summary

- Generalization of **arc-consistency** (which considers **pairs** of variables) to **path-consistency** (which considers **triples** of variables)
- Arc-consistency tightens **unary** constraints
- Path-consistency tightens **binary** constraints

i-Consistency

i-Consistency: Idea

- Further generalize previous concepts
 - For every valuation of v_1, \dots, v_{i-1} there must exist a corresponding consistent valuation of every other variable v_i
 - Otherwise the valuation for v_1, \dots, v_{i-1} (that is not extendable to v_i) is not allowed
- ↪ tightens **$(i - 1)$ -ary constraint** on v_1, \dots, v_{i-1}
- ↪ also affects non-binary constraints

i-Consistency: Definition

Definition (*i*-Consistent)

Let $\mathcal{R} = (X, D, C)$ be a constraint network.

- (a) A relation $R_S \in C$ with $|S| = i - 1$ is ***i*-consistent** with respect to a variable $y \notin S$ if for every $t \in R_S$, there is a value $d \in D_y$ such that t and d are consistent.
- (b) The constraint network \mathcal{R} is ***i*-consistent** if for any consistent valuation of any $i - 1$ distinct variables in X , there is a valuation of any i th variable such that the i values together satisfy all of the constraints among the i variables.

i-Consistency: Example

Constraint network \mathcal{R} for the 4-queens problem.

	v_1	v_2	v_3	v_4
1	Q			
2				
3		Q		
4				

	v_1	v_2	v_3	v_4
1	Q			
2			Q	
3				
4		Q		

- \mathcal{R} is 2-consistent: All single queen placements can be extended
- \mathcal{R} is not 3-consistent: There are valid placements of 2 queens that cannot be extended (left)
- \mathcal{R} is not 4-consistent: There are valid placements of 3 queens that cannot be extended (right)

Enforcing *i*-Consistency

- There exist extensions of arc- and path-consistency algorithms to enforce *i*-consistency
- We are not going into more detail here

Summary

Inference: Summary

- **Inference:** Derivation of additional constraints that are implied by the given constraints
- ↪ **equivalent** but **tighter** constraint network
- Useful for search-based solving approaches (↪ next chapters)
- **Trade-off:** Number of inferred constraints vs. time complexity