

# **Chapter 7**

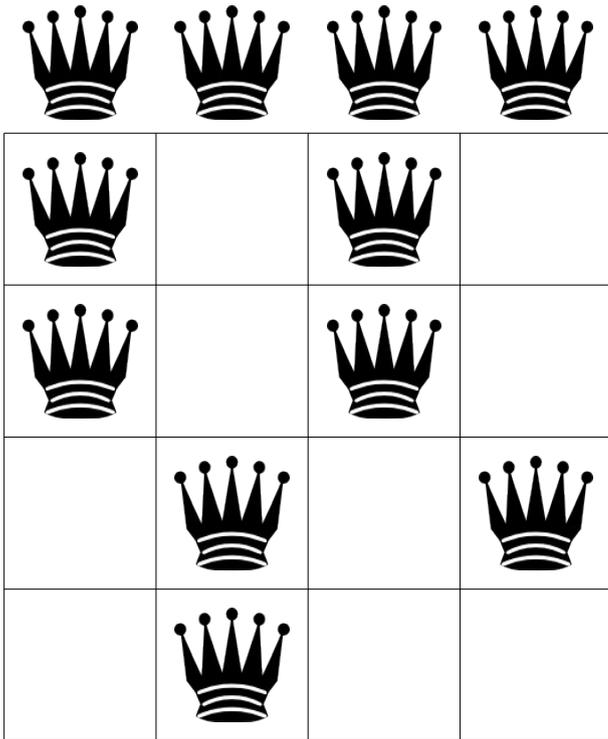
## **Stochastic Local Search**

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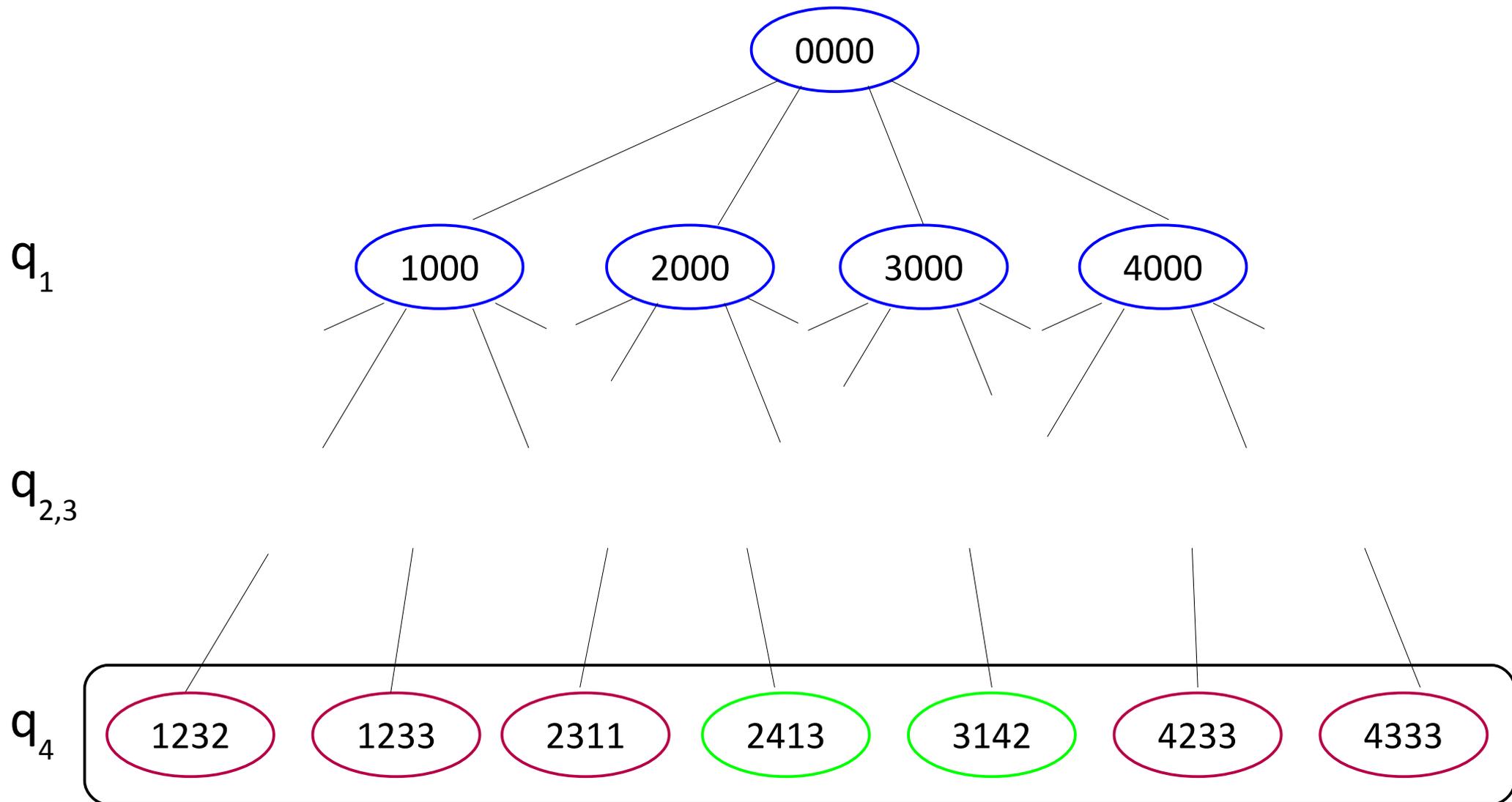
# Motivation

*n*-queens with Backtracking:



- guarantees to find all solutions
- reaches limit for big problems:  
Best backtracking methods  
solve up to *100*-queens
- Stochastic search:  
1 million queens solvable  
in less than a minute

# Systematic vs. Stochastic Search



# Greedy Local Search

- usually runs on complete instantiations (leaves)
- starts in a randomly chosen instantiation
- assignments aren't necessarily consistent



## Progressing:

- Local changes (of one variable assignment)
- *Greedy*, minimizing cost function (#broken constraints)

## Stopping Criterion:

- Assignment is consistent (const function = 0)

# Greedy SLS: Algorithm

**procedure:** SLS

**Input** : A constraint network  $\mathfrak{R} = (X, D, C)$ . A cost function defined on full assignments.

**Output:** A solution (no guarantee to terminate)

**initialization:** let  $\bar{a} = (a_1, \dots, a_n)$  be a random initial assignment to all variables.

**while**  $\bar{a}$  is not consistent **do**

    let  $Y = (x_i, a'_i)$  be the set of variable-value pairs that when  $x_i$  is assigned  $a'_i$ , give a maximum improvement in the cost of the assignment

    pick a pair  $x_i, a'_i \in Y$ .

$\bar{a} \leftarrow (a_1, \dots, a_{i-1}, a'_i, a_{i+1}, \dots, a_n)$  (just flip  $a_i$  to  $a'_i$ )

**end**

**return**  $\bar{a}$

# Example

4-queens with SLS:

|  |   |   |   |
|--|---|---|---|
|           |  |    |    |
|  <b>4</b> | <b>4</b>  | <b>5</b>  | <b>5</b>  |
| <b>4</b>   |  | <b>4</b>  | <b>5</b>  |
| <b>5</b>   | <b>4</b>  |   | <b>4</b>  |
| <b>4</b>   | <b>5</b>  |  |  |

- starts in a randomly chosen instantiation
- random change of one assignment
- *minimize* #broken constraints
- stop when cost function = 0

Cost function value:

6

# Example

4-queens with SLS:

|   |   |   |   |
|---|---|---|---|
|  | 3   | 5   | 2   |
| 4   |  | 3   |    |
| 3   | 3   | 6   | 2   |
| 4   | 4   |  |  |

- starts in a randomly chosen instantiation
- random change of one assignment
- *minimize* #broken constraints
- stop when cost function = 0

Cost function value:

4

# Example

4-queens with SLS:

|   |   |   |   |
|---|---|---|---|
|  |  | 4   | 2   |
| 3   |  | 3   |  |
| 2   | 1   | 5   | 2   |
| 2   | 2   |  | 4   |

- starts in a randomly chosen instantiation
- random change of one assignment
- *minimize* #broken constraints
- stop when cost function = 0

Cost function value:

2

# Example

4-queens with SLS:

|  |   |   |   |
|--|---|---|---|
|   |  | 4   | 3   |
| 3  | 2   | 3   |  |
|  | 1   | 2   | 2   |
| 1  | 2   |  | 3   |

- starts in a randomly chosen instantiation
- random change of one assignment
- *minimize* #broken constraints
- stop when cost function = 0

Cost function value:

1

# Problem with SLS

- Search can get stuck in a *local minimum* or on a *plateau*  
→ Algorithm never terminates

|   |   |   |   |
|---|---|---|---|
|  | 1   | 4   | 2   |
| 3   |  | 3   |  |
| 2   | 1   | 5   | 2   |
| 2   | 2   |  | 4   |

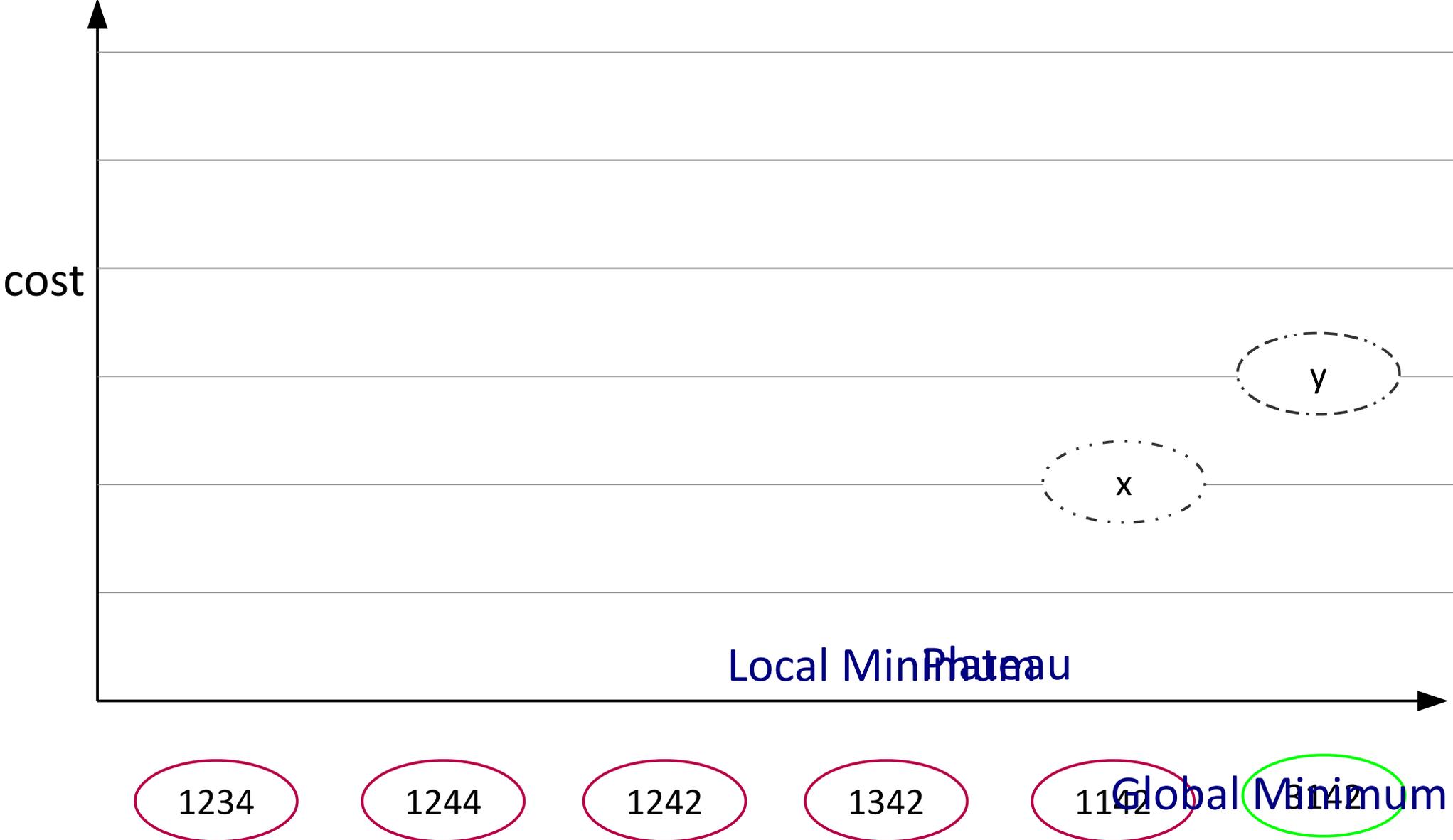


|   |  |   |   |
|---|--|---|---|
|  | 1  | 2   | 2   |
| 4   | 2  | 2   |  |
| 2   |  | 3   | 3   |
| 3   | 2  |  | 3   |

Cost function value: 2

Cost function value: 1

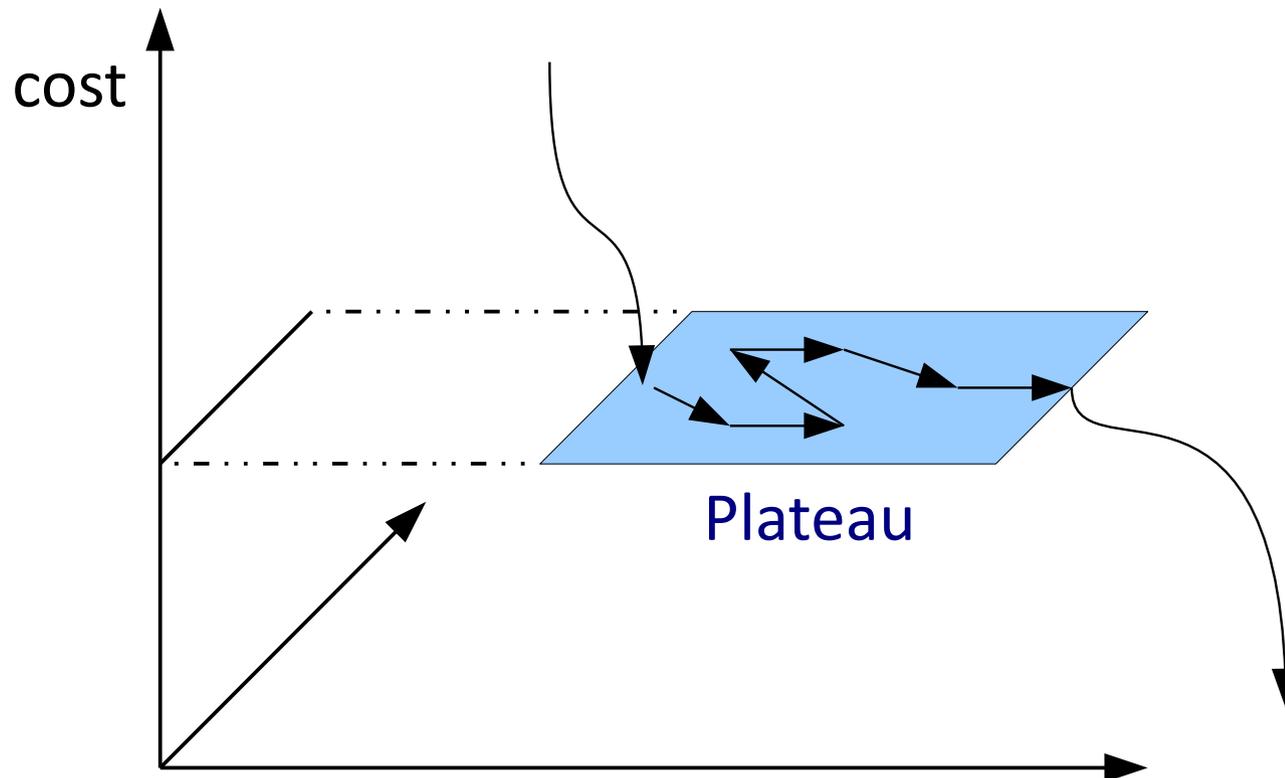
# Plateaus & Local Minima



# Escaping local minima

## 1. Plateau Search

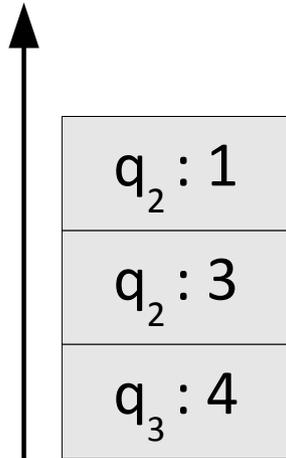
- Allow non-improving sideways steps
- Problem: running in circles



# Escaping local minima

## 2. Tabu search

- Store last  $n$  variable-value assignments
- Use list to prevent backward moves



# Escaping local minima

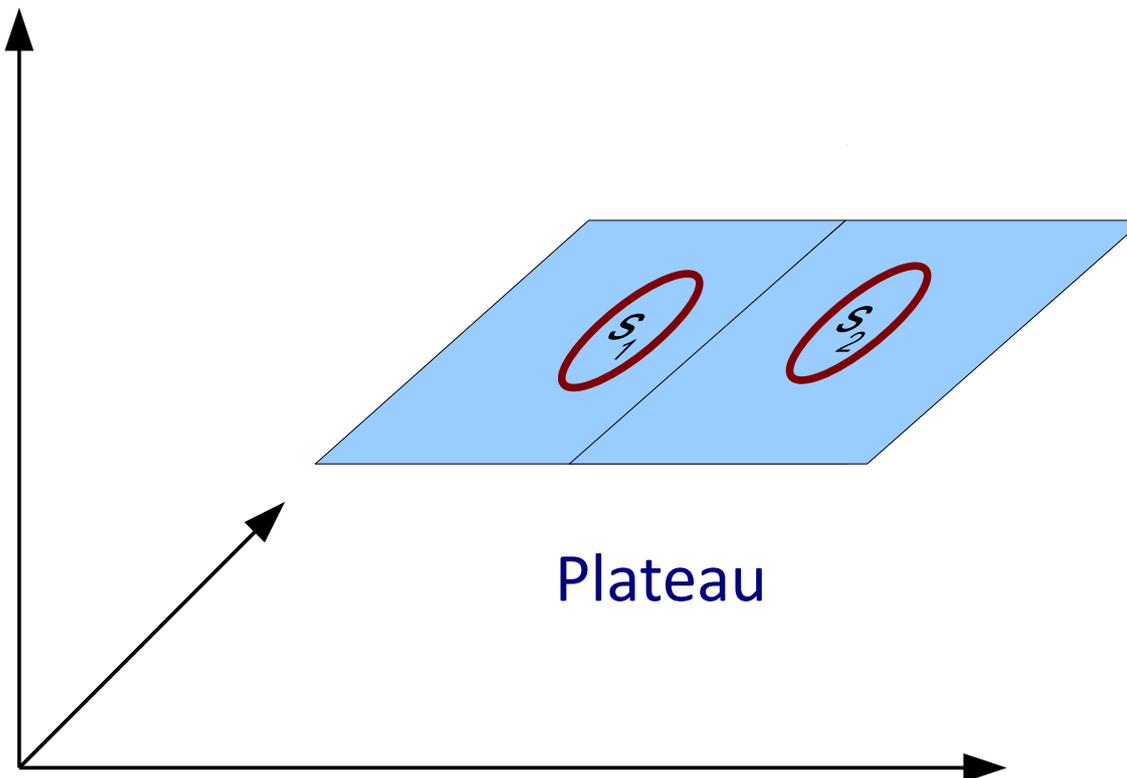
## 3. Random Restarts

- Restart algorithm in new random initialisation
- Can be combined with other escape-techniques
- Suggestions for restart:
  - when no improvement is possible
  - after *max\_flips* steps without improvement (Plateau search)
  - increase *max\_flips* after every improvement
- Achieve guarantee to find a solution

# Escaping local minima

## 4. Constraint weighting

- Cost function:  $F(\vec{a}) = \sum_i w_i * C_i(\vec{a})$
- Increasing weights of a violated constraint in local minima



# Other improvements

## Problem: Undetermined Termination

- Set a limit *max\_tries* for the algorithm when to stop
- **but:** we lose guarantee to find a solution

## Anytime Behaviour

- Store best assignment found so far (minimal #broken constraints)
- Return assignment when we need one (no solution)

# Random Walks

**procedure:** RandomWalk

**Input** : A network  $\mathfrak{R} = (X, D, C)$ , probability  $p$ .

**Output:** A solution iff the problem is consistent.

**start** with a random initial assignment  $\bar{a}$ .

**while**  $\bar{a}$  is not a solution **do**

- (i) **pick** a violated constraint  $C$ , randomly
- (ii) **choose** with probability  $p$  a variable-value pair  $\langle x, a' \rangle$  for  $x \in scope(C)$ ,  
or, with probability  $1 - p$ , choose a variable-value pair  $\langle x, a' \rangle$   
that minimizes the value of the cost function when the value of  $x$   
is changed to  $a'$ .
- (iii) Change  $x$ 's value to  $a'$ .

**end**

**return**  $\bar{a}$ .

Eventually hits a satisfying assignment (if exists)

# p and Simulated Annealing

- Optimal p values for specific problems

## Extension: **Simulated Annealing**

- Decrease p over time (by „cooling the temperature“)
  - more random jumps in earlier stages
  - more greedy progress later

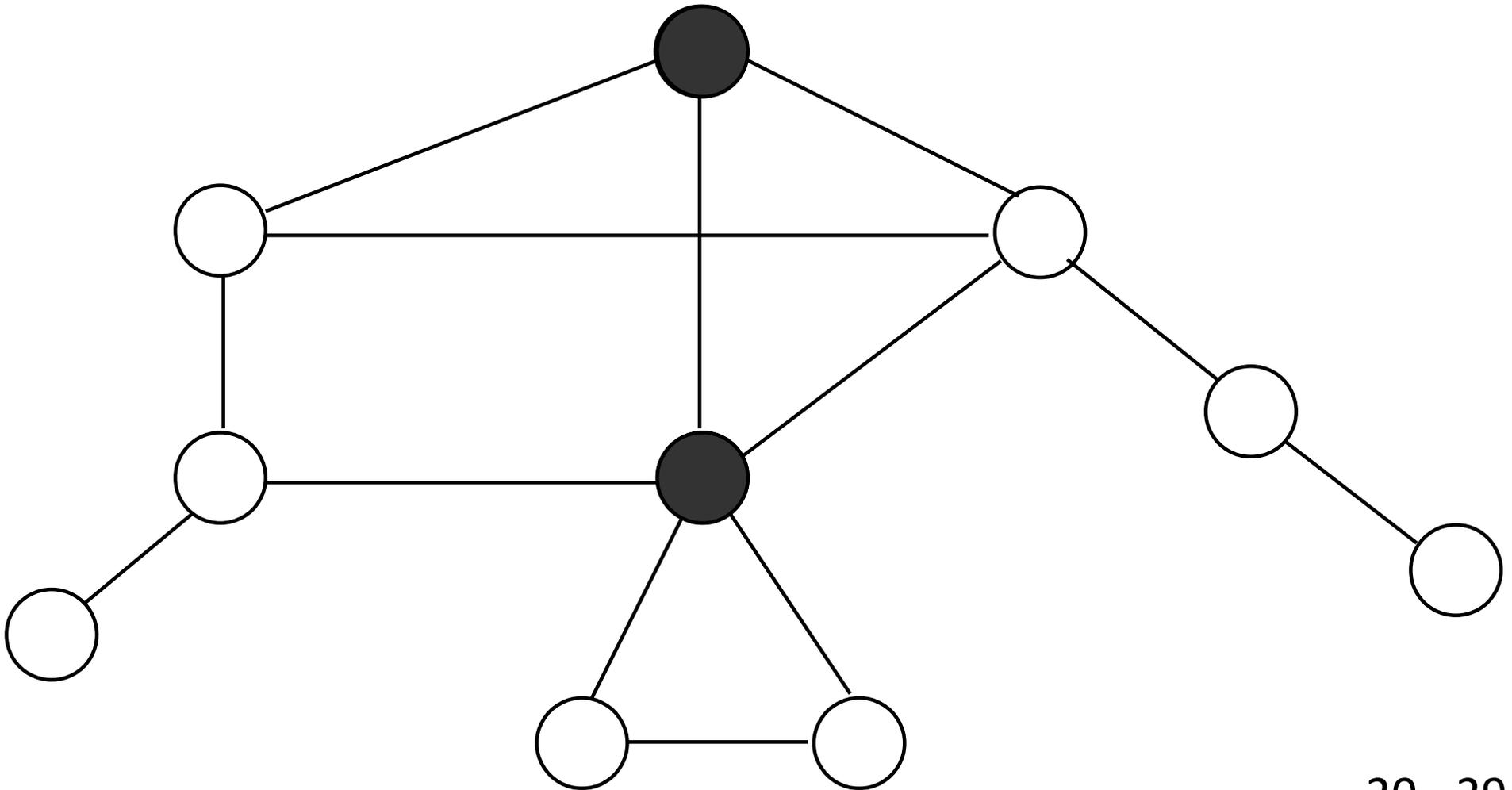
# SLS + Inference

Goal: Smaller search space

- use Inference methods as with systematic search
- constraint propagation: performance varies
  - very helpful for removing many near-solutions
  - not good for uniform problem structures

# SLS with Cycle-Cutset

Recap: Cycle-cutset decomposition



# SLS with Cycle-Cutset

Idea: Replace systematic search on cutset with SLS

- Start with random cutset assignment

Repeat:

- calculate minimal cost in trees:

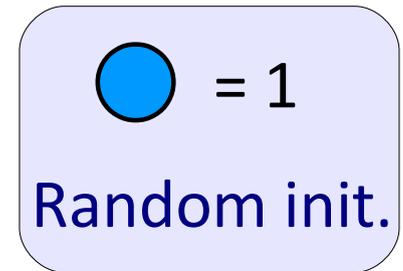
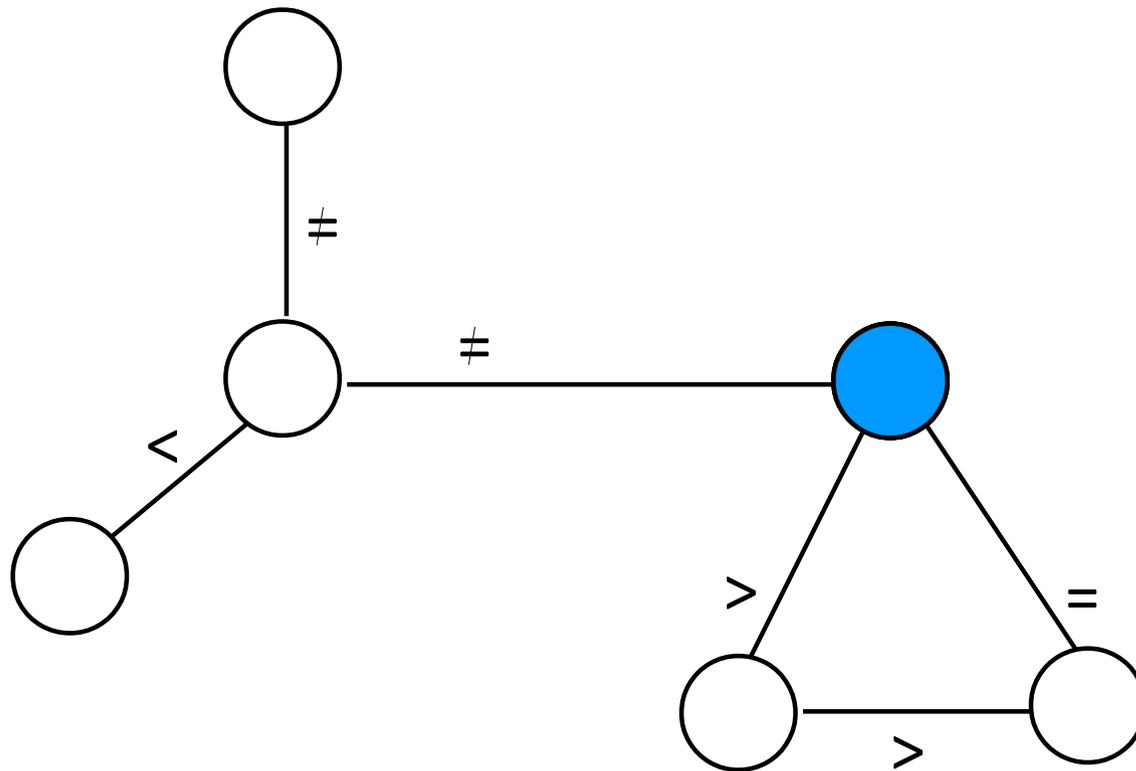
$$C(z_i \rightarrow a_i) = \sum_{\text{children } z_j} \min_{a_j \in D_{z_j}} (C(z_j \rightarrow a_j) + R(z_i \rightarrow a_i, z_j \rightarrow a_j))$$

- assign values with minimal cost to tree variables
- greedily optimize cutset assignment (Local Search)

# SLS with Cycle-Cutset

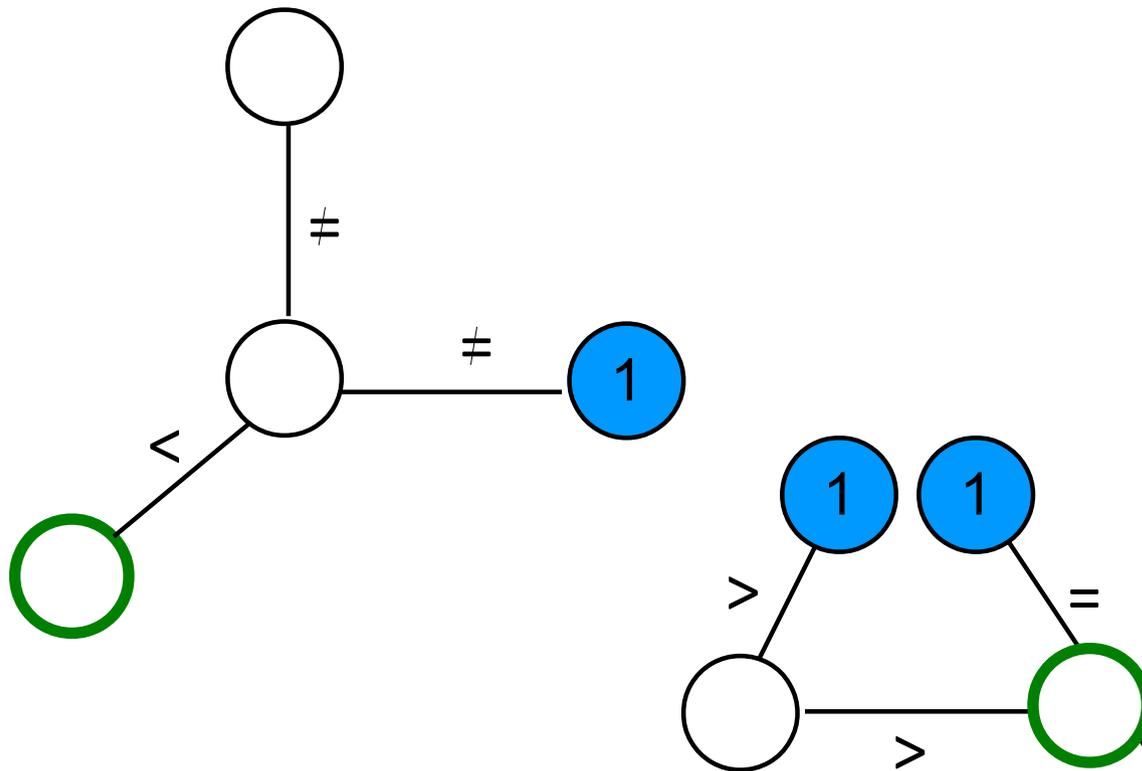
Example: Binary domains

1. Assign values to cutset variables



# SLS with Cycle-Cutset

Set a **Root** for each tree

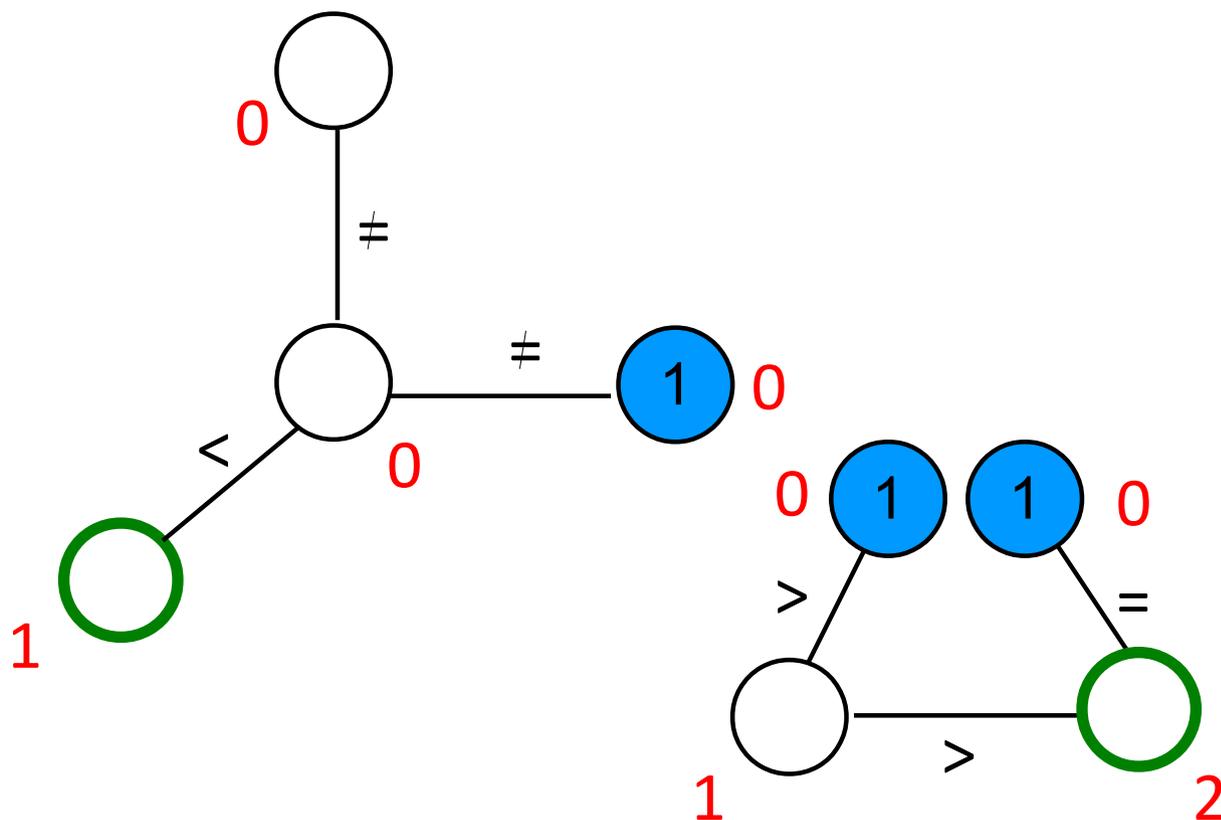
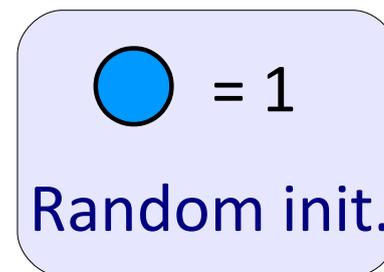


● = 1  
Random init.

# SLS with Cycle-Cutset

2. From leaves to root:

Calculate minimal **cost values**

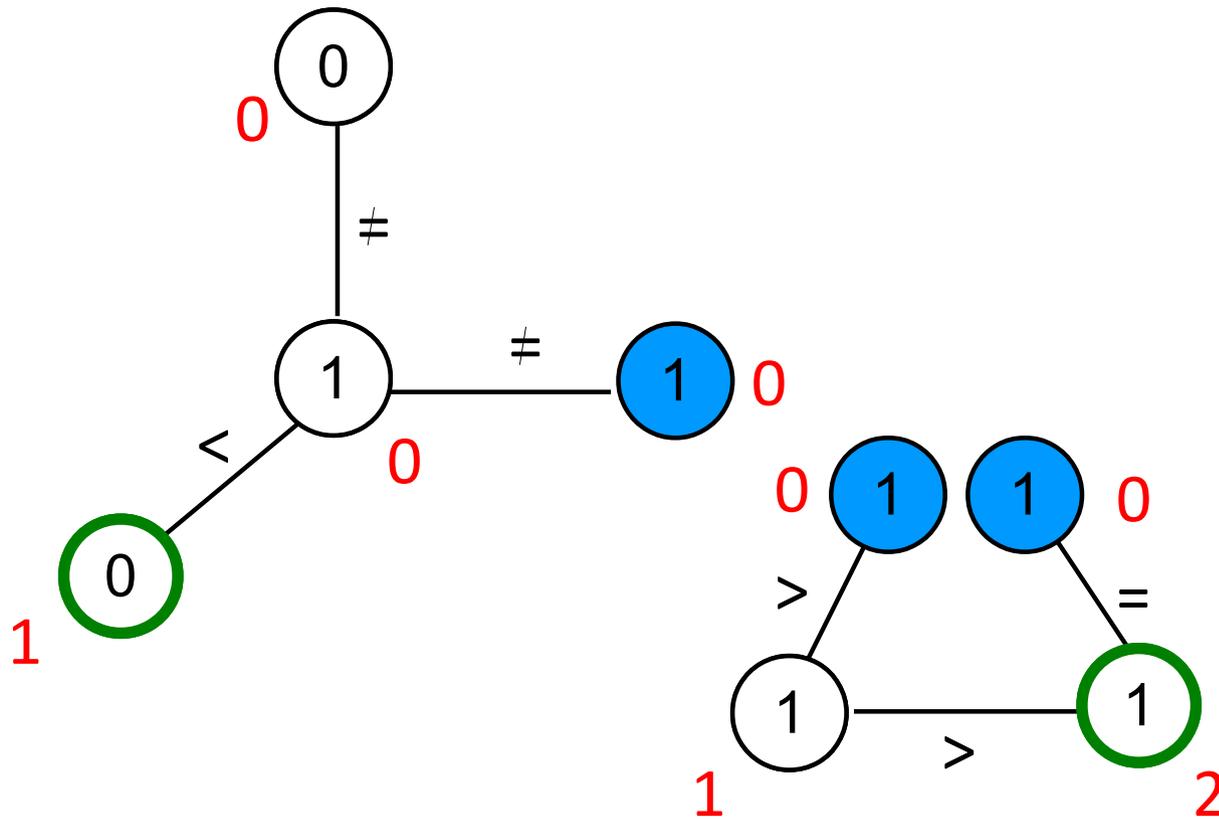


$$C(z_i \rightarrow a_i) = \sum_{\text{children } z_j} \min_{a_j \in D_{z_j}} (C(z_j \rightarrow a_j) + R(z_i \rightarrow a_i, z_j \rightarrow a_j))$$

# SLS with Cycle-Cutset

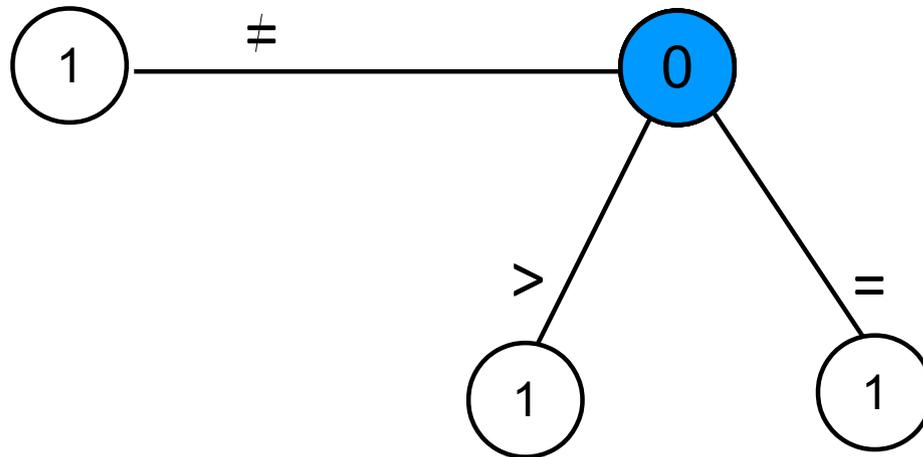
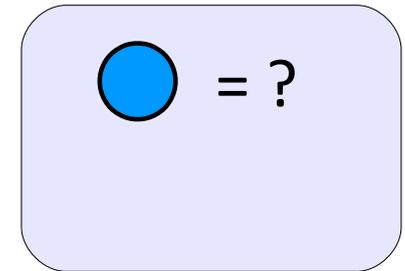
3. From root to leaves:

Assign values with minimal cost



# SLS with Cycle-Cutset

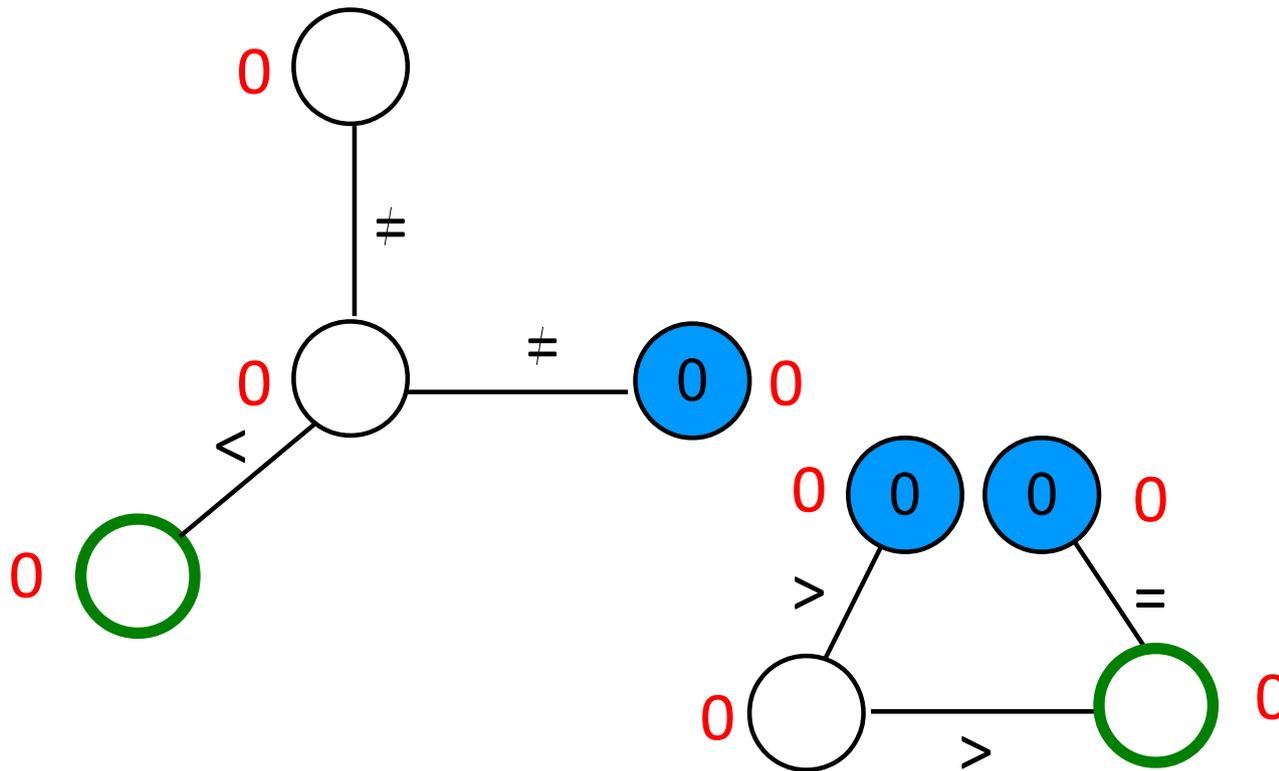
## 1. Assign values to cutset variables



# SLS with Cycle-Cutset

2. From leaves to root:

Calculate minimal **cost values**

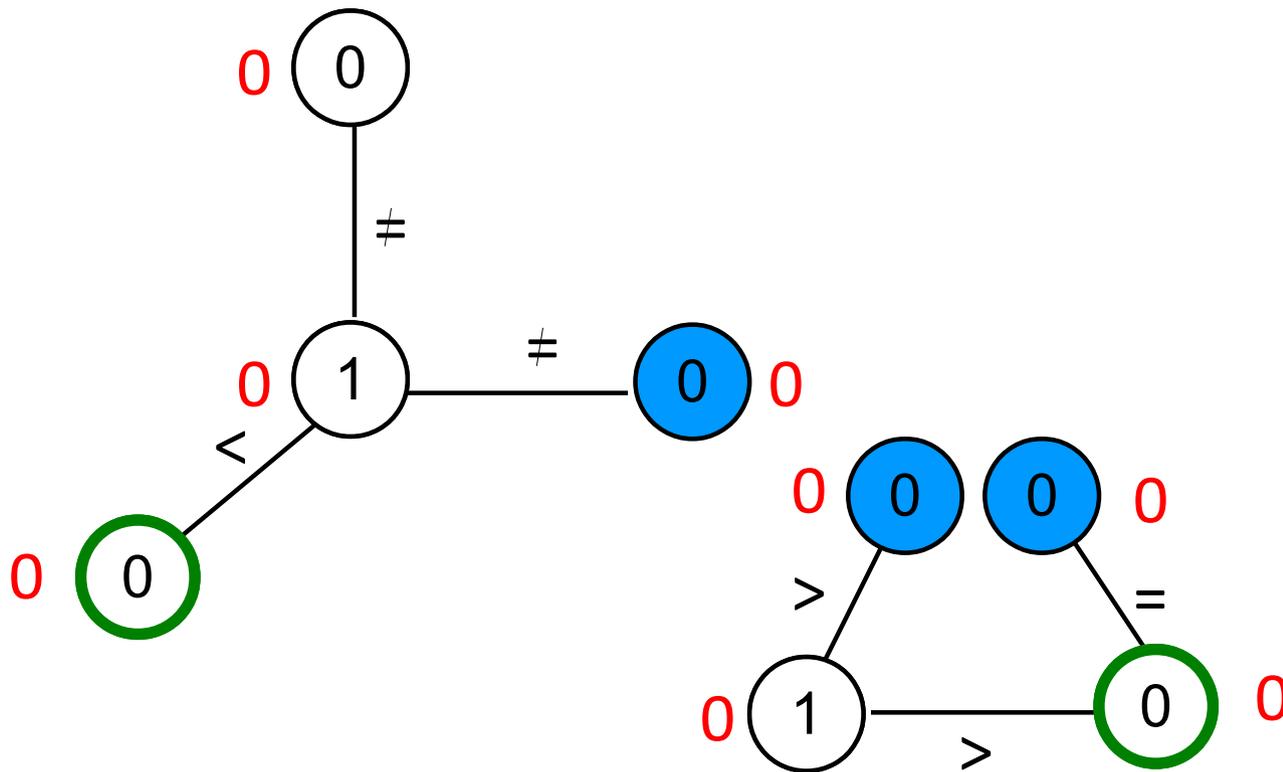


$$C(z_i \rightarrow a_i) = \sum_{\text{children } z_j} \min_{a_j \in D_{z_j}} (C(z_j \rightarrow a_j) + R(z_i \rightarrow a_i, z_j \rightarrow a_j))$$

# SLS with Cycle-Cutset

3. From root to leaves:

Assign values with minimal cost



# Summary

## Stochastic Local Search

- Approximates systematic search
- Greedy algorithms: Techniques to escape local minima
- Random Walk: combines greedy + random choices
- Combination with Inference methods can help
  
- Can work very well
- but no guarantee of termination AND finding a solution