

Foundations of Artificial Intelligence

13. State-Space Search: Heuristics

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State-Space Search: Overview

Chapter overview: state-space search

- ▶ 5.–7. Foundations
- ▶ 8.–12. Basic Algorithms
- ▶ 13.–19. Heuristic Algorithms
 - ▶ 13. Heuristics
 - ▶ 14. Analysis of Heuristics
 - ▶ 15. Best-first Graph Search
 - ▶ 16. Greedy Best-first Search, A^* , Weighted A^*
 - ▶ 17. IDA*
 - ▶ 18. Properties of A^* , Part I
 - ▶ 19. Properties of A^* , Part II

13.1 Introduction

Informed Search Algorithms

search algorithms considered so far:

- ▶ **uninformed** ("blind"): use **no information** besides **formal definition** to solve a problem
- ▶ **scale poorly**: prohibitive time (and space) requirements for seemingly **simple** problems (**time complexity** usually $O(b^d)$)

Informed Search Algorithms

search algorithms considered so far:

example: $b = 13$; 10^5 nodes/second

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d	nodes	time
4	30 940	0.3 s
6	$5.2 \cdot 10^6$	52 s
8	$8.8 \cdot 10^8$	147 min
10	10^{11}	17 days
12	10^{13}	8 years
14	10^{15}	1 352 years
16	10^{17}	$2.2 \cdot 10^5$ years
18	10^{20}	$38 \cdot 10^6$ years

Informed Search Algorithms

Rubik's cube:

example: $b = 13$; 10^5 nodes/second



- ▶ branching factor: ≈ 13
- ▶ typical solution length: 18

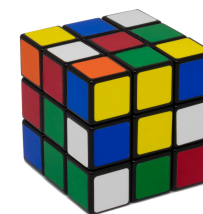
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Richard Korf, Finding Optimal Solutions to Rubik's Cube Using Pattern Databases (AAAI, 1997)

Informed Search Algorithms

Rubik's cube:

search algorithms considered now:



- ▶ **idea**: try to find (problem-specific) criteria to distinguish **good** and **bad states**
- ▶ **heuristic** ("informed") search algorithms prefer good states
- ▶ branching factor: ≈ 13
- ▶ typical solution length: 18

Richard Korf, Finding Optimal Solutions to Rubik's Cube Using Pattern Databases (AAAI, 1997)

13.2 Heuristics

Heuristics

Definition (heuristic)

Let S be a state space with states S .

A **heuristic function** or **heuristic** for S is a function

$$h : S \rightarrow \mathbb{R}_0^+ \cup \{\infty\},$$

mapping each state to a non-negative number (or ∞).

Heuristics: Intuition

idea: $h(s)$ estimates distance (= cost of cheapest path) from s to closest goal state

► heuristics can be **arbitrary** functions

► **intuition:**

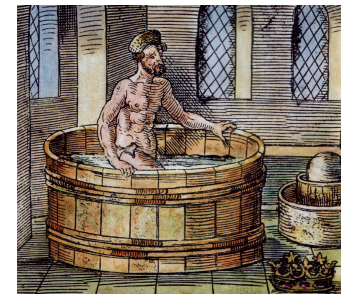
- ① the closer h is to true goal distance, the more efficient the search using h
- ② the better h separates states that are **close** to the goal from states that are **far**, the more efficient the search using h

Heuristics are sometimes defined for **search nodes** instead of states, but this increased generality is rarely useful. (Why?)

Why “Heuristic”?

What does “heuristic” mean?

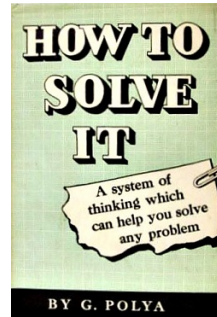
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- same origin as ἐνρηκα!



Why “Heuristic”?

What does “heuristic” mean?

- ▶ from ancient Greek $\epsilon\upsilon\text{ρισκω}$ (= I find)
- ▶ same origin as $\epsilon\upsilon\text{ρηκα!}$
- ▶ popularized by George Pólya: How to Solve It (1945)
- ▶ in computer science often used for: rule of thumb, inexact algorithm
- ▶ in state-space search technical term for **goal distance estimator**



Representation of Heuristics

In our black box model, heuristics are an additional element of the state space interface:

State Spaces as Black Boxes (Extended)

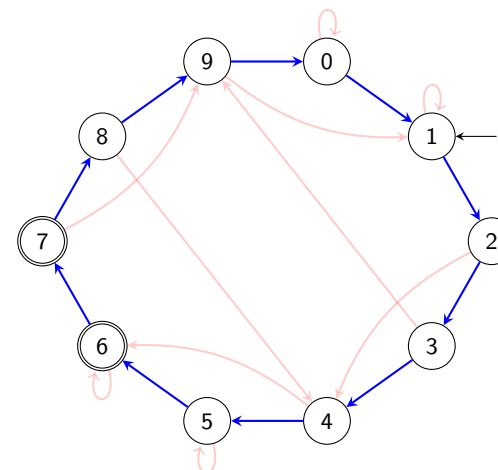
- ▶ `init()`
- ▶ `is_goal(s)`
- ▶ `succ(s)`
- ▶ `cost(a)`
- ▶ `h(s)`: heuristic value for state s
result: non-negative integer or ∞

13.3 Examples

Bounded Inc-and-square

bounded inc-and-square:

possible heuristics:



$$h_1(s) = \begin{cases} 0 & \text{if } s = 7 \\ (16 - s) \% 10 & \text{otherwise} \end{cases}$$

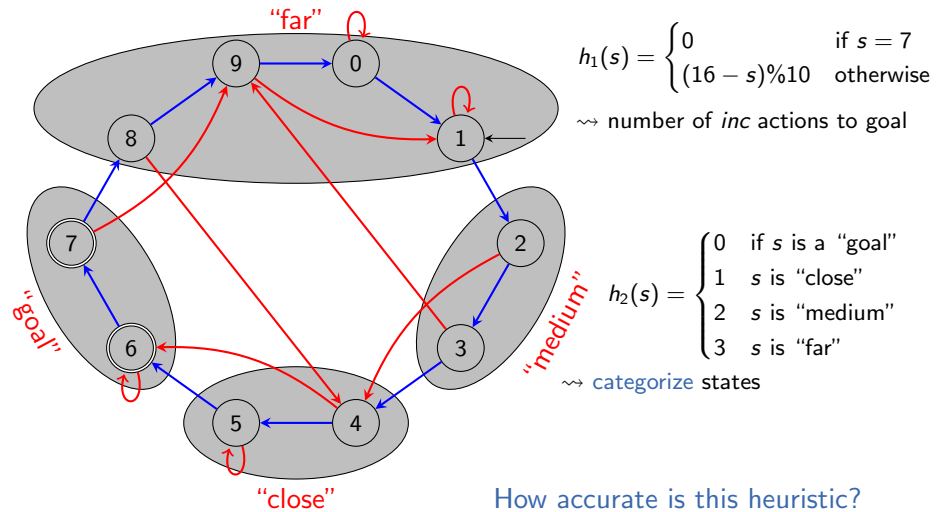
\rightsquigarrow number of *inc* actions to goal

How accurate is this heuristic?

Bounded Inc-and-square

bounded inc-and-square:

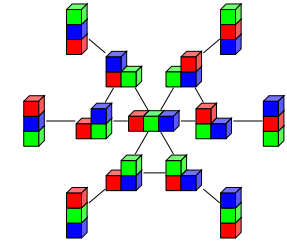
possible heuristics:



Example: Blocks World

possible heuristic:

count blocks x that currently lie on y and must lie on $z \neq y$ in the goal (including case where y or z is the table)

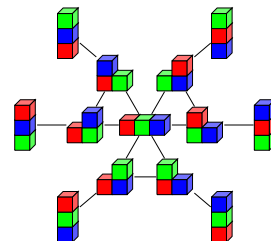


Example: Blocks World

possible heuristic:

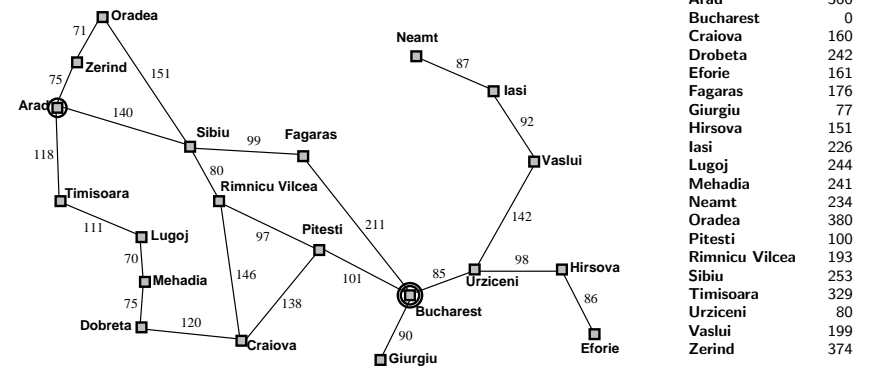
count blocks x that currently lie on y and must lie on $z \neq y$ in the goal (including case where y or z is the table)

How accurate is this heuristic?



Example: Route Planning in Romania

possible heuristic: straight-line distance to Bucharest



Example: Missionaries and Cannibals

Setting: Missionaries and Cannibals

- ▶ Six people must cross a river.
- ▶ Their rowing boat can carry one or two people across the river at a time (it is too small for three).
- ▶ Three people are missionaries, three are cannibals.
- ▶ Missionaries may never stay with a majority of cannibals.

possible heuristic: number of people on the wrong river bank

↪ with our formulation of states as triples $\langle m, c, b \rangle$:

$$h(\langle m, c, b \rangle) = m + c$$

13.4 Summary

Summary

- ▶ **heuristics** estimate distance of a state to the goal
- ▶ can be used to **focus** search on **promising** states
- ↪ **soon**: search algorithms that use heuristics