

# Foundations of Artificial Intelligence

## 43. Board Games: Introduction to Monte-Carlo Tree Search

Malte Helmert

University of Basel

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## Board Games: Overview

chapter overview:

- ▶ 40. Introduction and State of the Art
- ▶ 41. Minimax Search and Evaluation Functions
- ▶ 42. Alpha-Beta Search
- ▶ 43. Introduction to Monte-Carlo Tree Search
- ▶ 44. Advanced Topics in Monte-Carlo Tree Search
- ▶ 45. AlphaGo and Outlook

## 43.1 Introduction

## Monte-Carlo Tree Search: Brief History

- ▶ Starting in the 1930s: first researchers experiment with **Monte-Carlo methods**
- ▶ 1998: Ginsberg's **GIB** player achieves strong performance playing Bridge ~> [this chapter](#)
- ▶ 2002: Auer et al. present **UCB1** action selection for multi-armed bandits ~> [Chapter 44](#)
- ▶ 2006: Coulom coins the term **Monte-Carlo Tree Search** (MCTS) ~> [this chapter](#)
- ▶ 2006: Kocsis and Szepesvári combine UCB1 and MCTS into the most famous MCTS variant, **UCT** ~> [Chapter 44](#)

## Monte-Carlo Tree Search: Applications

Examples for successful applications of MCTS in games:

- ▶ board games (e.g., **Go** ~> [Chapter 45](#))
- ▶ card games (e.g., **Poker**)
- ▶ AI for computer games (e.g., for **Real-Time Strategy Games** or **Civilization**)
- ▶ **Story Generation** (e.g., for dynamic dialogue generation in computer games)
- ▶ **General Game Playing**

Also many applications in other areas, e.g.,

- ▶ **MDPs** (planning with **stochastic** effects) or
- ▶ **POMDPs** (MDPs with **partial observability**)

## 43.2 Monte-Carlo Methods

## Monte-Carlo Methods: Idea

- ▶ subsume a broad **family of algorithms**
- ▶ decisions are based on **random samples**
- ▶ results of samples are **aggregated** by computing the **average**
- ▶ apart from these points, algorithms **differ** significantly

## Aside: Hindsight Optimization vs. the Exam

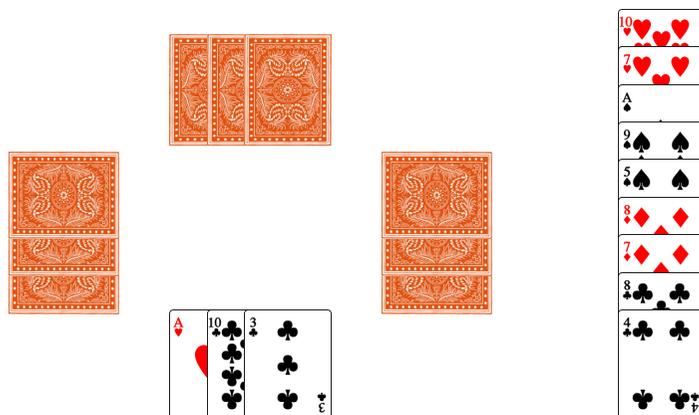
- ▶ As a motivating example for Monte-Carlo methods, we now briefly look at **hindsight optimization**.
- ▶ Hindsight optimization is interesting for settings with **randomness** and **partial observability**, which we do not otherwise consider in this course.
- ▶ To keep the discussion short, we do not provide formal details for how to model randomness and partial observability.
- ▶ Therefore, the slides on hindsight optimization are not relevant for the exam.

## Monte-Carlo Methods: Example

Bridge Player GIB, based on **Hindsight Optimization** (HOP)

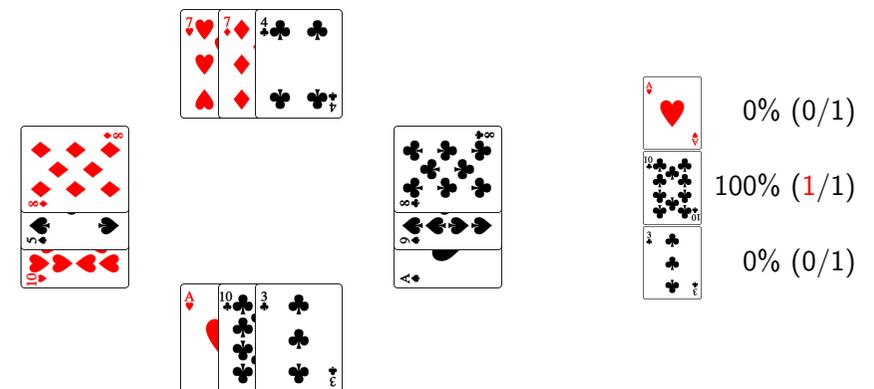
- ▶ perform **samples** as long as **resources** (deliberation time, memory) allow:
- ▶ **sample** hands for all players that are consistent with current knowledge about the game state
- ▶ for each legal move, compute if **fully observable** game that starts with executing that move is won or lost
- ▶ compute **win percentage** for each move over all samples
- ▶ play the card with the highest win percentage

## Hindsight Optimization: Example



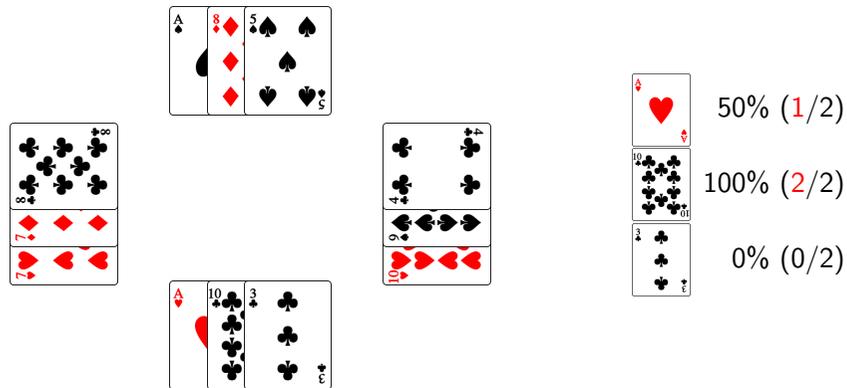
South to play, three tricks to win, trump suit ♣

## Hindsight Optimization: Example



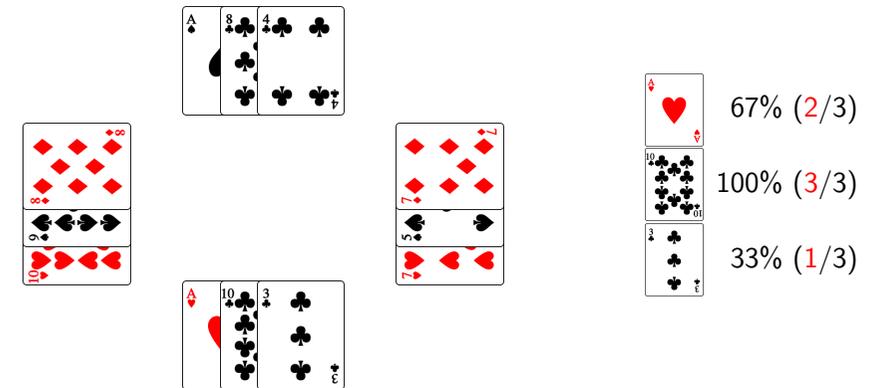
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## Hindsight Optimization: Example



South to play, three tricks to win, trump suit ♣

## Hindsight Optimization: Example

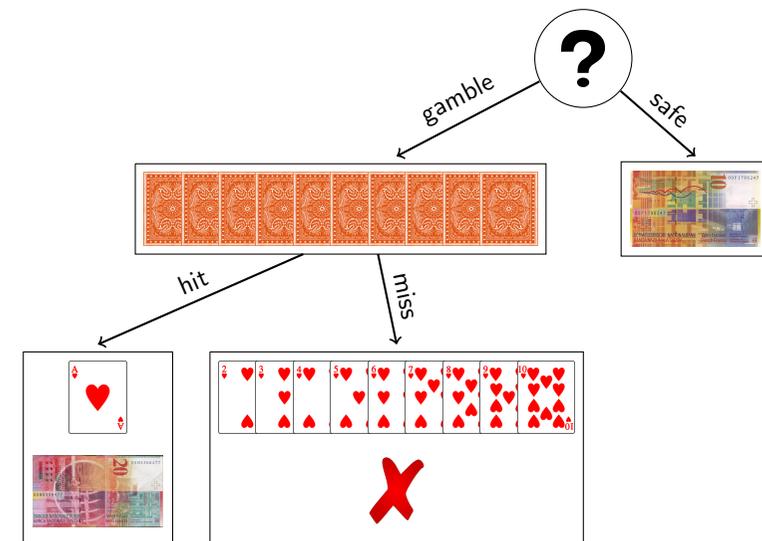


South to play, three tricks to win, trump suit ♣

## Hindsight Optimization: Restrictions

- ▶ HOP **well-suited** for partially observable games like most card games (Bridge, Skat, Klondike Solitaire)
- ▶ must be possible to **solve** or **approximate** sampled game **efficiently**
- ▶ often **not optimal** even if provided with infinite resources

## Hindsight Optimization: Suboptimality



## 43.3 Monte-Carlo Tree Search

## Monte-Carlo Tree Search: Idea

### Monte-Carlo Tree Search (MCTS) ideas:

- ▶ perform **iterations** as long as resources (deliberation time, memory) allow:
- ▶ **build a partial game tree**, where nodes  $n$  are annotated with
  - ▶ **utility estimate**  $\hat{u}(n)$
  - ▶ **visit counter**  $N(n)$
- ▶ initially, the tree contains only the root node
- ▶ each iteration adds **one node** to the tree

After constructing the tree, play the move that leads to the child of the root with **highest utility estimate** (as in minimax/alpha-beta).

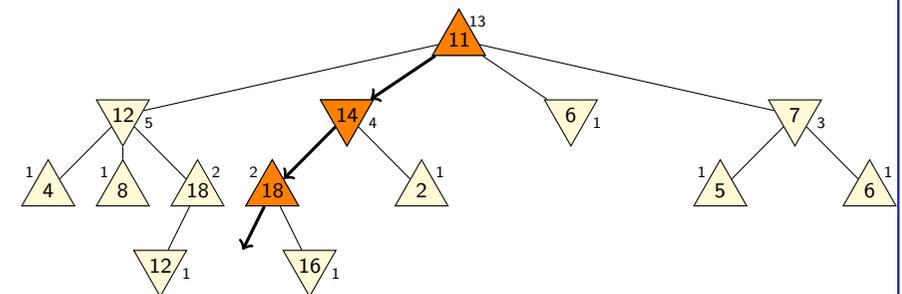
## Monte-Carlo Tree Search: Iterations

Each iteration consists of four **phases**:

- ▶ **selection**: traverse the tree by applying **tree policy**
  - ▶ Stop when reaching terminal node (in this case, set  $n_{\text{child}}$  to that node and  $p_*$  to its position and skip next two phases)...
  - ▶ ... or when reaching a node  $n_{\text{parent}}$  for which not all successors are part of the tree.
- ▶ **expansion**: add a missing successor  $n_{\text{child}}$  of  $n_{\text{parent}}$  to the tree
- ▶ **simulation**: apply **default policy** from  $n_{\text{child}}$  until a terminal position  $p_*$  is reached
- ▶ **backpropagation**: for all nodes  $n$  on path from root to  $n_{\text{child}}$ :
  - ▶ increase  $N(n)$  by 1
  - ▶ update current average  $\hat{u}(n)$  based on  $u(p_*)$

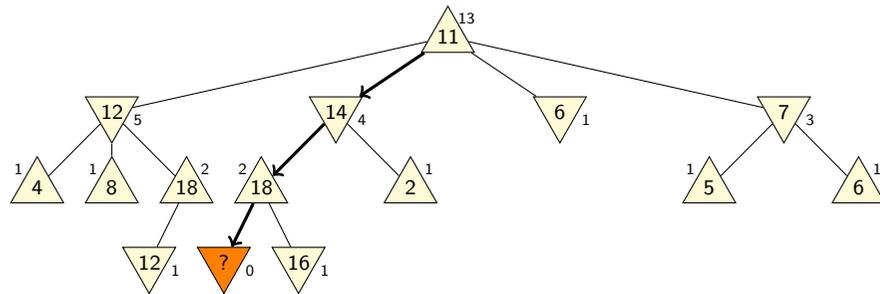
## Monte-Carlo Tree Search

**Selection**: apply **tree policy** to traverse tree



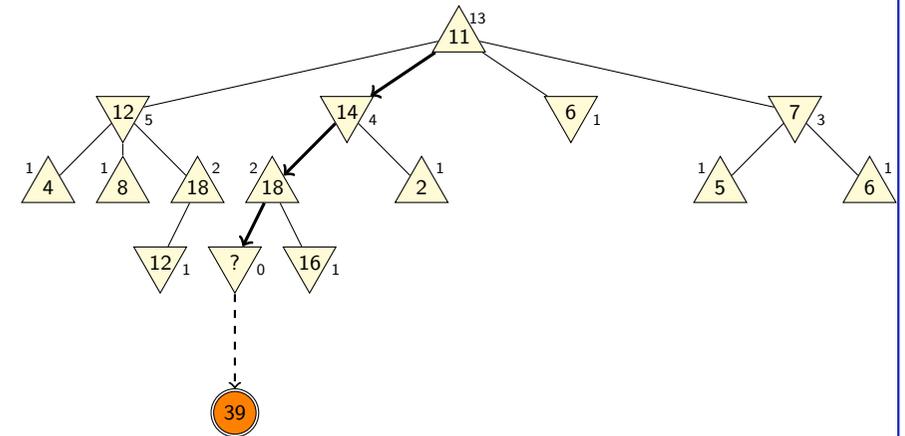
## Monte-Carlo Tree Search

**Expansion:** create a node for **first position** beyond the tree



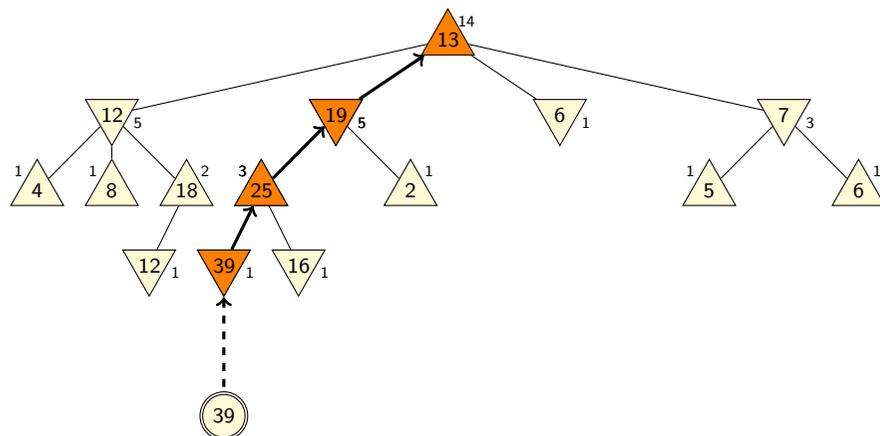
## Monte-Carlo Tree Search

**Simulation:** apply **default policy** until terminal position is reached



## Monte-Carlo Tree Search

**Backpropagation:** update **utility estimates** of visited nodes



## Monte-Carlo Tree Search: Pseudo-Code

### Monte-Carlo Tree Search

```

n0 := create_root_node()
while time_allows():
    visit_node(n0)
nbest := arg maxn ∈ succ(n0) ŷ(n)
return nbest.move
  
```

## Monte-Carlo Tree Search: Pseudo-Code

```
function visit_node(n)
  if is_terminal(n.position):
    utility := u(n.position)
  else:
    p := n.get_unvisited_successor()
    if p is none:
      n' := apply_tree_policy(n)
      utility := visit_node(n')
    else:
      p* := apply_default_policy_until_end(p)
      utility := u(p*)
      n.add_child_node(p, utility)
  update_visit_count_and_estimate(n, utility)
  return utility
```

## 43.4 Summary

## Summary

- ▶ Monte-Carlo methods compute **averages** over a number of random **samples**.
- ▶ Simple Monte-Carlo methods like **Hindsight Optimization** perform well in some games, but are suboptimal even with unbounded resources.
- ▶ **Monte-Carlo Tree Search (MCTS)** algorithms iteratively build a search tree, adding one node in each iteration.
- ▶ MCTS is parameterized by a **tree policy** and a **default policy**.