

# Theory of Computer Science

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## Exercise Sheet 11

Due: Sunday, May 28, 2017

*Note:* Submissions that are exclusively created with  $\text{\LaTeX}$  will receive a bonus mark. Please submit only the resulting PDF file (or a printout of this file).

### Exercise 11.1 (1.5+1.5+1 marks)

Consider the decision problem CLIQUE:

- *Given:* undirected graph  $G = \langle V, E \rangle$ , number  $K \in \mathbb{N}_0$
  - *Question:* Does  $G$  contain a clique of size  $K$  or more, i.e., a set of nodes  $C \subseteq V$  with  $|C| \geq K$  and  $\{u, v\} \in E$  for all  $u, v \in C$  with  $u \neq v$ ?
- (a) Specify a non-deterministic algorithm for CLIQUE, whose runtime is limited by a polynomial in  $|V| + |E|$ . Explain why the algorithm's runtime is polynomial.
- (b) Specify a deterministic algorithm for CLIQUE.
- (c) Estimate the runtime of your algorithm from part (b) in  $O$ -Notation.

You can use any common programming concepts in your answer. You do *not* have to use the restricted syntax of WHILE-programs or similar languages. High-level pseudo code is sufficient as long as it can be easily seen that each step runs in polynomial time. Use the GUESS statements from the lecture for non-deterministic statements.

### Exercise 11.2 (1+1+1.5+1.5 marks)

Prove or refute the following statements. In all cases, specify a short proof (2–3 sentences are sufficient).

- (a) Let  $X$  be an NP-hard problem and  $Y$  a problem with  $X \leq_p Y$ . Then  $Y$  is NP-hard.
- (b) Let  $X$  be an NP-hard problem. If there is a deterministic polynomial algorithm for  $X$ , then there also is a deterministic polynomial algorithm for DIRHAMILTONCYCLE.
- (c) There are NP-complete problems  $X$  and  $Y$  where there is a deterministic polynomial algorithm for  $X$  but not for  $Y$ .
- (d) Let  $Y \subseteq \Sigma^*$  be any problem with  $Y \neq \emptyset$  and  $Y \neq \Sigma^*$ . Then  $X \leq_p Y$  holds for all  $X \in \mathcal{P}$ .

### Exercise 11.3 (2+1 marks)

A *Hamilton path* is defined analogously to a Hamilton cycle (see chapter E1) with the only difference that we look for a simple path instead of a cycle. More formally: a Hamilton path in a directed graph  $\langle V, E \rangle$  is a sequence of vertices  $\pi = \langle v_1, \dots, v_n \rangle$  that defines a path ( $\langle v_i, v_{i+1} \rangle \in E$  for all  $1 \leq i < n$ ) and contains every vertex in the graph exactly once.

Consider the decision problem DIRHAMILTONPATH:

- *Given:* directed graph  $G = \langle V, E \rangle$
  - *Question:* Does  $G$  contain a Hamilton path?
- (a) Prove that DIRHAMILTONPATH is NP-hard. You can use without proof that DIRHAMILTONCYCLE is NP-complete.
- (b) Is DIRHAMILTONPATH NP-complete? Justify your answer.