

Foundations of Artificial Intelligence

47. Uncertainty: Representation

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May 24, 2017

Uncertainty: Overview

chapter overview:

- 46. Introduction and Quantification
- 47. Representation of Uncertainty

Introduction

Running Example

We continue the *dentist example*.

	<i>toothache</i>		\neg <i>toothache</i>	
	catch	\neg catch	catch	\neg catch
cavity	0.108	0.012	0.072	0.008
\neg cavity	0.016	0.064	0.144	0.576

Full Joint Probability Distribution: Discussion

Advantage: Contains all necessary information

Disadvantage: Prohibitively large in practice:
Table for n Boolean variables has size $O(2^n)$.

Good for theoretical foundations, but **what to do in practice?**

Conditional Independence

Reminder: Bayes' Rule

General version with multivalued variables and conditioned on some background evidence \mathbf{e} :

$$\mathbf{P}(Y | X, \mathbf{e}) = \frac{\mathbf{P}(X | Y, \mathbf{e})\mathbf{P}(Y | \mathbf{e})}{\mathbf{P}(X | \mathbf{e})}$$

Multiple Evidence

If we already know that the probe catches and the tooth aches, we could compute the probability that this patient has cavity from

$$\begin{aligned} \mathbf{P}(Cavity \mid catch \wedge toothache) \\ = \alpha \mathbf{P}(catch \wedge toothache \mid Cavity) \mathbf{P}(Cavity). \end{aligned}$$

Problem: Need conditional probability for $catch \wedge toothache$ for each value of $Cavity$.

↪ same scalability problem as with full joint distribution

Conditional Independence: Example

	<i>toothache</i>		\neg <i>toothache</i>	
	catch	\neg catch	catch	\neg catch
cavity	0.108	0.012	0.072	0.008
\neg cavity	0.016	0.064	0.144	0.576

Variables *Toothache* and *Catch* not independent
but independent **given the presence or absence of cavity**:

$$\mathbf{P}(\textit{Toothache}, \textit{Catch} \mid \textit{Cavity}) = \mathbf{P}(\textit{Toothache} \mid \textit{Cavity})\mathbf{P}(\textit{Catch} \mid \textit{Cavity})$$

Conditional Independence

Definition

Two variables X and Y are **conditionally independent** given a third variable Z if

$$\mathbf{P}(X, Y \mid Z) = \mathbf{P}(X \mid Z)\mathbf{P}(Y \mid Z).$$

Conditional Independence and Multiple Evidence Example

Multiple evidence:

$$\begin{aligned}\mathbf{P}(Cavity \mid catch \wedge toothache) \\ &= \alpha \mathbf{P}(catch \wedge toothache \mid Cavity) \mathbf{P}(Cavity) \\ &= \alpha \mathbf{P}(toothache \mid Cavity) \mathbf{P}(catch \mid Cavity) \mathbf{P}(Cavity).\end{aligned}$$

↪ No need for conditional joint probabilities for conjunctions

Conditional Independence: Decomposition of Joint Dist.

Full joint distribution:

$$\begin{aligned}\mathbf{P}(Toothache, Catch, Cavity) \\ &= \mathbf{P}(Toothache, Catch \mid Cavity)\mathbf{P}(Cavity) \\ &= \mathbf{P}(Toothache \mid Cavity)\mathbf{P}(Catch \mid Cavity)\mathbf{P}(Cavity)\end{aligned}$$

↪ Large table can be decomposed into three smaller tables.

For n symptoms that are all conditionally independent given *Cavity* the representation grows as $O(n)$ instead of $O(2^n)$.

Bayesian Networks

Bayesian Networks

Definition

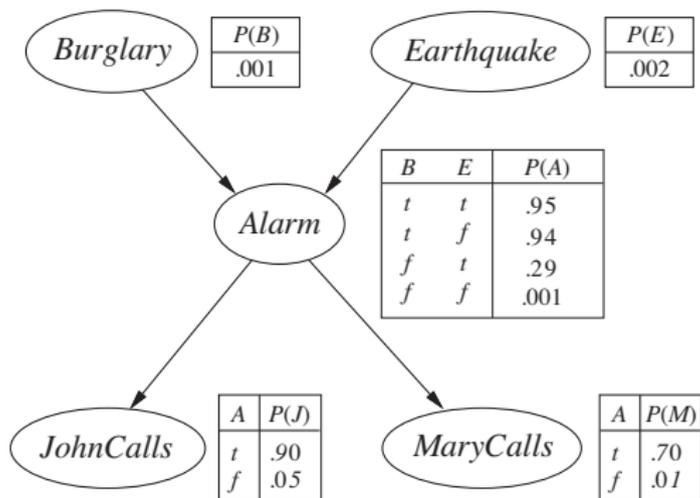
A **Bayesian network** is a directed **acyclic** graph, where

- each node corresponds to a random variable,
- each node X has an associated conditional probability distribution $\mathbf{P}(X \mid \text{parents}(X))$ that quantifies the effect of the parents on the node.

Bayesian networks are also called **belief networks** or **probabilistic networks**.

They are a subclass of **graphical models**.

Bayesian Network: Example



Semantics

The semantics for Bayesian networks expresses that

- the information associated to each node represents a **conditional probability distribution**, and that
- each variable is **conditionally independent of its non-descendants given its parents**.

Definition

A Bayesian network with nodes $\{X_1, \dots, X_n\}$ represents the full joint probability given by

$$P(X_1 = x_1 \wedge \dots \wedge X_n = x_n) = \prod_{i=1}^n P(X_i = x_i \mid \text{parents}(X_i)).$$

Naive Construction

Order all variables, e.g.. as X_1, \dots, X_n .

For $i = 1$ to n do:

- Choose from X_1, \dots, X_{i-1} a minimal set of parents of X_i such that $P(X_i | X_{i-1}, \dots, X_1) = P(X_i = x_i | \text{parents}(X_i))$.
- For each parent insert a link from the parent to X_i .
- Define conditional probability table $\mathbf{P}(X_i | \text{parents}(X_i))$.

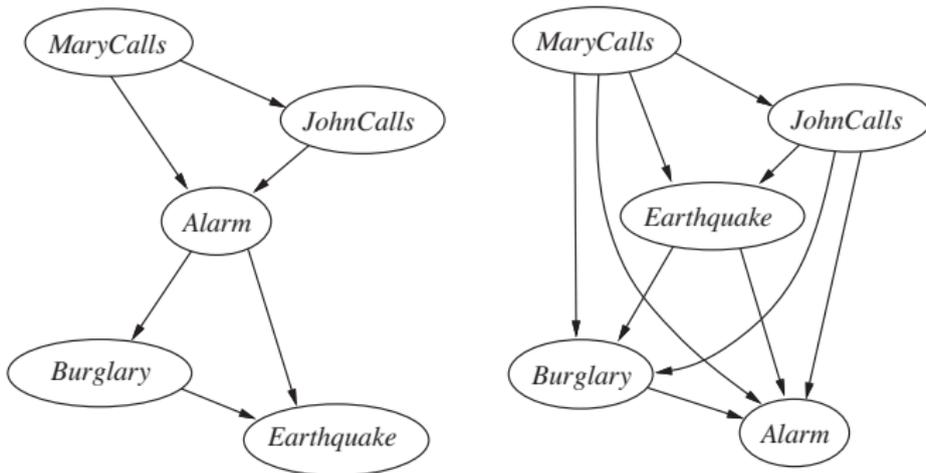
Compactness

Compactness of Bayesian networks stems from **local structures** in domains, where random variables are directly influenced only by a small number of variables.

- n Boolean random variables
- each variable directly influenced by at most k others
- full joint probability distribution contains 2^n numbers
- Bayesian network can be specified by $n2^k$ numbers

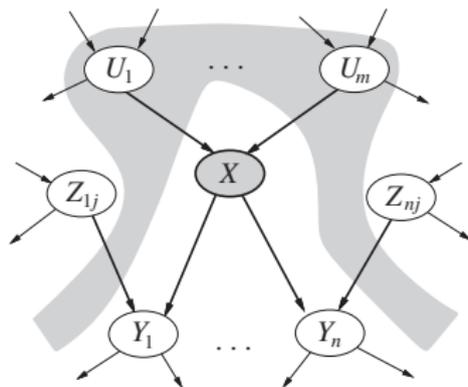
Influence of Node Ordering

A bad **node ordering** can lead to large numbers of parents and probability distributions that are hard to specify.



Conditional Independence Given Parents

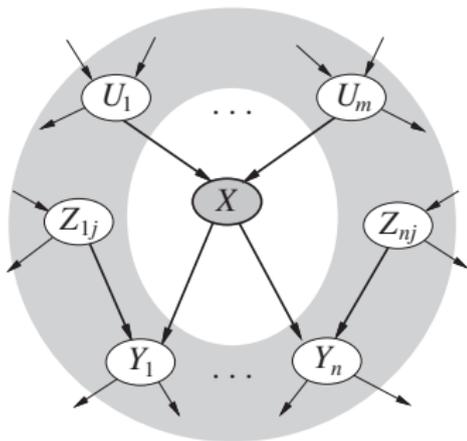
Each variable is **conditionally independent of its non-descendants given its parents.**



X is conditionally independent of the nodes Z_{ij} given $U_1 \dots U_m$.

Conditional Independence Given Markov Blanket

The **Markov blanket** of a node consists of its **parents, children and children's other parents**.



Each variable is **conditionally independent** of **all other nodes** in the network **given its Markov blanket** (gray area).

Summary

Summary & Outlook

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- **Conditional independence** is weaker than (unconditional) independence but occurs more frequently.
- **Bayesian networks** exploit conditional independence to compactly represent joint probability distributions.

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Outlook

- There are exact and approximate **inference algorithms** for Bayesian networks.
- **Exact inference** in Bayesian networks is **NP-hard** (but tractable for some sub-classes such as poly-trees).
- All concepts can be extended to **continuous** random variables.