

Foundations of Artificial Intelligence

46. Uncertainty: Introduction and Quantification

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Uncertainty: Overview

chapter overview:

- 46. Introduction and Quantification
- 47. Representation of Uncertainty

Introduction

Motivation

Uncertainty in our knowledge of the world caused by

- partial observability,
- unreliable information (e.g. from sensors),
- nondeterminism,
- laziness to collect more information,
- ...

Yet we have to act!

Option 1: Try to find solution that works in all possible worlds

~> often there is no such solution

Option 2: Quantify uncertainty (degree of belief) and maximize expected utility

Example

Have to get from Aarau to Basel to attend a lecture at 9:00.

Different options:

- 7:36–8:12 IR2256 to Basel
- 7:40–7:53 S 23 to Olten, 8:05–9:29 IC 1058 to Basel
- 7:40–7:57 IR 2160 to Olten, 8:05–9:29 IC 1058 to Basel
- 8:13–8:24 RE 4760 to Olten, 8:30–8:55 IR 2310 to Basel
- leave by car at 8:00 and drive approx. 45 minutes
- ...

Different utilities (travel time, cost, slack time, convenience, ...)
and **different probabilities of actually achieving the goal** (traffic jams, accidents, broken trains, missed connections, ...).

Uncertainty and Logical Rules

Example: diagnosing a dental patient's toothache

- $toothache \rightarrow cavity$

Wrong: not all patients with toothache have a cavity.

- $toothache \rightarrow cavity \vee gumproblem \vee abscess \vee \dots$

Almost unlimited list of possible problems.

- $cavity \rightarrow pain$

Wrong: not all cavities cause pain.

↪ Logic approach not suitable for domain like medical diagnosis.

Instead: Use probabilities to express degree of belief, e.g. there is a 80% chance that the patient with toothache has a cavity.

Probability Theory

Probability Model

Sample space Ω is countable set of **possible worlds**

Definition

A **probability model** associates a numerical probability $P(\omega)$ with each possible world such that

$$0 \leq P(\omega) \leq 1 \text{ for every } \omega \in \Omega \text{ and}$$

$$\sum_{\omega \in \Omega} P(\omega) = 1.$$

For $\Omega' \subseteq \Omega$ the probability of Ω' is defined as

$$P(\Omega') = \sum_{\omega \in \Omega'} P(\omega).$$

Factored Representation of Possible Worlds

- Possible worlds defined in terms of **random variables**.
 - variables Die_1 and Die_2 with domain $\{1, \dots, 6\}$ for the values of two dice.
- Describe sets of possible worlds by logical formulas (called **propositions**) over random variables.
 - $Die_1 = 1$
 - $(Die_1 = 2 \vee Die_1 = 4 \vee Die_1 = 6) \wedge (Die_2 = 2 \vee Die_2 = 4 \vee Die_2 = 6)$
 - also use informal descriptions if meaning is clear, e.g. “both values even”

Probability Model: Example



Two dice

- $\Omega = \{\langle 1, 1 \rangle, \dots, \langle 1, 6 \rangle, \dots, \langle 6, 1 \rangle, \dots, \langle 6, 6 \rangle\}$
- $P(\langle x, y \rangle) = 1/36$ for all $x, y \in \{1, \dots, 6\}$ (fair dice)
- $P(\{\langle 1, 1 \rangle, \langle 1, 2 \rangle, \langle 1, 3 \rangle, \langle 1, 4 \rangle, \langle 1, 5 \rangle, \langle 1, 6 \rangle\}) = 6/36 = 1/6$
- Propositions to describe sets of possible worlds
 - $P(\text{Die}_1 = 1) = 1/6$
 - $P(\text{both values even}) =$
 $P(\{\langle 2, 2 \rangle, \langle 2, 4 \rangle, \langle 2, 6 \rangle, \langle 4, 2 \rangle, \langle 4, 4 \rangle, \langle 4, 6 \rangle, \langle 4, 2 \rangle, \langle 4, 4 \rangle, \langle 4, 6 \rangle\}) =$
 $9/36 = 1/4$
 - $P(\text{Total} \geq 11) = P(\{\langle 6, 5 \rangle, \langle 5, 6 \rangle, \langle 6, 6 \rangle\}) = 3/36 = 1/12$

Relationships

The following rules can be derived from the definition of a probability model:

- $P(a \vee b) = P(a) + P(b) - P(a \wedge b)$
- $P(\neg a) = 1 - P(a)$

Probability Distribution

Convention: names of random variables begin with uppercase letters and names of values with lowercase letters.

Random variable *Weather* with

$$P(\textit{Weather} = \textit{sunny}) = 0.6$$

$$P(\textit{Weather} = \textit{rain}) = 0.1$$

$$P(\textit{Weather} = \textit{cloudy}) = 0.29$$

$$P(\textit{Weather} = \textit{snow}) = 0.01$$

Abbreviated: $\mathbf{P}(\textit{Weather}) = \langle 0.6, 0.1, 0.29, 0.01 \rangle$

A **probability distribution** \mathbf{P} is the vector of probabilities for the (ordered) domain of a random variable.

Joint Probability Distribution

For multiple random variables, the **joint probability distribution** defines values for all possible combinations of the values.

		$\mathbf{P}(\textit{Weather}, \textit{Headache})$	
		<i>headache</i>	\neg <i>headache</i>
<i>sunny</i>	$P(\textit{sunny} \wedge \textit{headache})$	$P(\textit{sunny} \wedge \neg \textit{headache})$	
<i>rain</i>			
<i>cloudy</i>		...	
<i>snow</i>			

Conditional Probability: Intuition

$P(x)$ denotes the **unconditional** or **prior** probability that x will appear in the absence of any other information, e.g.

$$P(\text{cavity}) = 0.6.$$

The probability of a cavity increases if we know that a patient has toothache.

$$P(\text{cavity} \mid \text{toothache}) = 0.8$$

↪ **conditional probability** (or **posterior probability**)

Conditional Probability

Definition

The **conditional probability** for proposition a given proposition b with $P(b) > 0$ is defined as

$$P(a | b) = \frac{P(a \wedge b)}{P(b)}.$$

Example: $P(\text{both values even} | \text{Die}_2 = 4) = ?$

Product Rule: $P(a \wedge b) = P(a | b)P(b)$

Independence

- X and Y are **independent** if $P(X \wedge Y) = P(X)P(Y)$.
- For independent variables X and Y with $P(Y) > 0$ it holds that $P(X | Y) = P(X)$.

Inference from Full Joint Distributions

Full Joint Distribution

full joint distribution: joint distribution for **all** random variables.

	<i>toothache</i>		\neg <i>toothache</i>	
	catch	\neg catch	catch	\neg catch
cavity	0.108	0.012	0.072	0.008
\neg cavity	0.016	0.064	0.144	0.576

Sum of entries is always 1. (Why?)

Sufficient for calculating the probability of any proposition.

Marginalization

For any sets of variables \mathbf{Y} and \mathbf{Z} :

$$\mathbf{P}(\mathbf{Y}) = \sum_{\mathbf{z} \in \mathbf{Z}} \mathbf{P}(\mathbf{Y}, \mathbf{z}),$$

where $\sum_{\mathbf{z} \in \mathbf{Z}}$ means to sum over all possible combinations of values of the variables in \mathbf{Z} .

$\mathbf{P}(\text{Cavity}) = \rightsquigarrow$ [blackboard](#)

Conditioning

To determine **conditional probabilities** express them as unconditional probabilities and evaluate the subexpressions from the full joint probability distribution.

$$\begin{aligned} P(\text{cavity} \mid \text{toothache}) &= \frac{P(\text{cavity} \wedge \text{toothache})}{P(\text{toothache})} \\ &= \frac{0.108 + 0.012}{0.108 + 0.012 + 0.016 + 0.064} = 0.6 \end{aligned}$$

Normalization: Idea

$$\begin{aligned}P(\text{cavity} \mid \text{toothache}) &= \frac{P(\text{cavity} \wedge \text{toothache})}{P(\text{toothache})} \\ &= \frac{0.108 + 0.012}{0.108 + 0.012 + 0.016 + 0.064} = 0.6\end{aligned}$$

$$\begin{aligned}P(\neg\text{cavity} \mid \text{toothache}) &= \frac{P(\neg\text{cavity} \wedge \text{toothache})}{P(\text{toothache})} \\ &= \frac{0.016 + 0.064}{0.108 + 0.012 + 0.016 + 0.064} = 0.4\end{aligned}$$

Term $1/P(\text{toothache})$ remains constant.

Probabilities from complete case analysis always sum up to 1.

Idea: Use normalization constant α instead of constant term.

Normalization: Example

$$\begin{aligned}\mathbf{P}(\text{Cavity} \mid \text{toothache}) &= \alpha \mathbf{P}(\text{Cavity}, \text{toothache}) \\ &= \alpha (\mathbf{P}(\text{Cavity}, \text{toothache}, \text{catch}) + \mathbf{P}(\text{Cavity}, \text{toothache}, \neg \text{catch})) \\ &= \alpha (\langle 0.108, 0.016 \rangle + \langle 0.012, 0.064 \rangle) = \alpha \langle 0.12, 0.08 \rangle = \langle 0.6, 0.4 \rangle\end{aligned}$$

With normalization, we can compute the probabilities without knowing $P(\text{toothache})$.

Full Joint Probability Distribution: Discussion

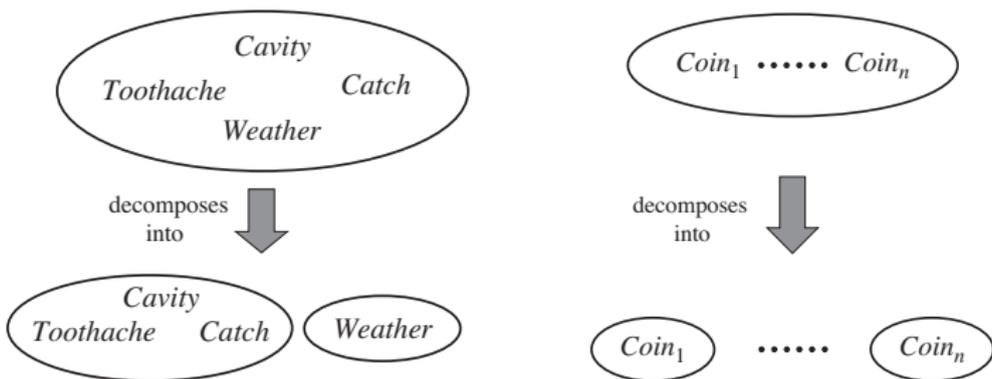
Advantage: Contains all necessary information

Disadvantage: Prohibitively large in practice:
Table for n Boolean variables has size $O(2^n)$.

Good for theoretical foundations, but what to do in practice?

Possible Solution: Factorization

Idea: Exploit **independence** $\mathbf{P}(X, Y) = \mathbf{P}(X)\mathbf{P}(Y)$ to factorize large joint distribution into smaller distributions.



Problem: Independence is quite rare.
(We will come back to this idea later.)

Bayes' Rule

Bayes' Rule

Product rule: $P(a \wedge b) = P(a | b)P(b)$, $P(a \wedge b) = P(b | a)P(a)$

Combination gives **Bayes' rule**

$$P(b | a) = \frac{P(a | b)P(b)}{P(a)}$$

General version with multivalued variables and conditioned on some background evidence \mathbf{e} :

$$\mathbf{P}(Y | X, \mathbf{e}) = \frac{\mathbf{P}(X | Y, \mathbf{e})\mathbf{P}(Y | \mathbf{e})}{\mathbf{P}(X | \mathbf{e})}$$

Bayes' Rule: Example

Meningitis causes a stiff neck 70% of the time.

The prior probability that a patient has meningitis is $1/50,000$, and the prior probability that a patient has a stiff neck is 1%.

What is the probability that a patient with a stiff neck has meningitis?

$$P(s | m) = 0.7$$

$$P(m) = 1/50000$$

$$P(s) = 0.01$$

$$P(m | s) = \frac{P(s | m)P(m)}{P(s)} = \frac{0.7 \cdot 1/50000}{0.01} = 0.0014$$

Summary

Summary

- **Uncertainty** is inescapable in complex, nondeterministic or partially observable environments.
- **Probabilities** summarize the agent's beliefs relative to the evidence.
- The **full joint probability distribution** specifies probabilities for each possible world.
- The full joint probability distribution contains sufficient information to calculate the probability of any proposition.
- An explicit representation of the full joint probability distribution is usually too large, but in the presence of **independence** it can be factored into smaller distributions.
- With **Bayes' rule** we can compute unknown probabilities from known conditional probabilities.