

Foundations of Artificial Intelligence

27. Constraint Satisfaction Problems: Constraint Graphs

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Constraint Satisfaction Problems: Overview

Chapter overview: constraint satisfaction problems

- 22.–23. Introduction
- 24.–26. Basic Algorithms
- 27.–28. Problem Structure
 - 27. Constraint Graphs
 - 28. Decomposition Methods

Constraint Graphs

Motivation

- To solve a constraint network consisting of n variables and k values, k^n assignments must be considered.
- Inference can alleviate this combinatorial explosion, but will not always avoid it.
- Many practically relevant constraint networks are efficiently solvable if their **structure** is taken into account.

Constraint Graphs

Definition (constraint graph)

Let $\mathcal{C} = \langle V, \text{dom}, (R_{uv}) \rangle$ be a constraint network.

The **constraint graph** of \mathcal{C} is the graph whose vertices are V and which contains an edge between u and v iff R_{uv} is a nontrivial constraint.

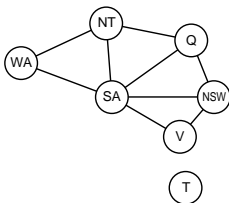
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example: coloring of the Australian states and territories



Disconnected Graphs

Unconnected Constraint Graphs

Proposition (unconnected constraint graphs)

If the constraint graph of \mathcal{C} has multiple connected components, the subproblems induced by each component can be solved separately.

The union of the solutions of these subproblems is a solution for \mathcal{C} .

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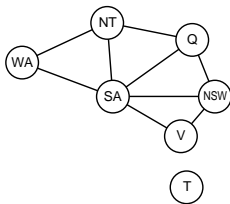
Proof.

A total assignment consisting of combined subsolutions satisfies all constraints that occur **within** the subproblems.

From the definitions of constraint graphs and connected components, **all** nontrivial constraints are within a subproblem. □

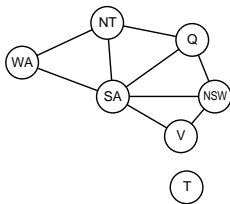
Unconnected Constraint Graphs: Example

example: Tasmania can be colored independently from the rest of Australia.



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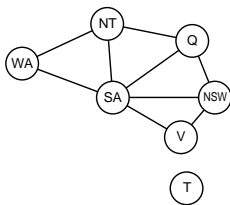
further example:

network with $k = 2$, $n = 30$ that decomposes into three components of equal size

savings?

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savings?

only $3 \cdot 2^{10} = 3072$ assignments instead of $2^{30} = 1073741824$

Trees

Trees as Constraint Graphs

Proposition (trees as constraint graphs)

*Let \mathcal{C} be a constraint network with n variables and maximal domain size k whose constraint graph is a **tree** or **forest** (i.e., does not contain cycles).*

Then we can solve \mathcal{C} or prove that no solution exists in time $O(nk^2)$.

example: $k = 5, n = 10$

$\rightsquigarrow k^n = 9765625, nk^2 = 250$

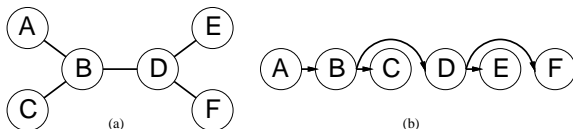
Trees as Constraint Graphs: Algorithm

algorithm for trees:

- Build a **directed** tree for the constraint graph.
Select an arbitrary variable as the root.
- Order variables v_1, \dots, v_n such that parents are ordered before their children.
- For $i \in \langle n, n-1, \dots, 2 \rangle$: call `revise($v_{\text{parent}(i)}$, v_i)`
 \rightsquigarrow each variable is arc consistent with respect to its children
- If a domain becomes empty, the problem is unsolvable.
- Otherwise: solve with `BacktrackingWithInference`, variable order v_1, \dots, v_n and forward checking.
 \rightsquigarrow solution is found **without backtracking steps**

Trees as Constraint Graphs: Example

constraint network \rightsquigarrow directed tree + order:



revise steps:

- $\text{revise}(D, F)$
- $\text{revise}(D, E)$
- $\text{revise}(B, D)$
- $\text{revise}(B, C)$
- $\text{revise}(A, B)$

finding a solution:

backtracking with order $A \prec B \prec C \prec D \prec E \prec F$

Summary

Summary

- Constraint networks with **simple structure** are easy to solve.
- **Constraint graphs** formalize this structure:
 - **several connected components:**
solve **separately** for each component
 - **tree:** algorithm **linear** in number of variables